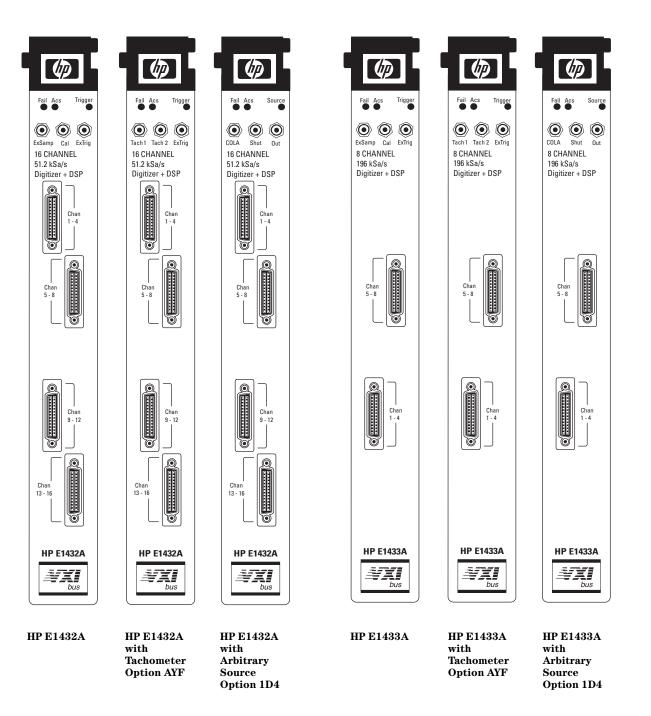




- 8-channel 196 kSa/sec/chan Digitizer plus DSP
- HP E1434A 4-channel 65 kSa/sec/chan Arbitary source

HP E1432A and HP E1433A Digitizer plus DSP

The HP E1432A 16-Channel 51.2 kSa/Sec/Chan digitizer and E1433A 8-channel 196 kSa/Sec/Chan digitizer integrate transducer signal conditioning, anti-alias protection, digitization, and high-speed measurement computation in a single-wide VXI module. Onboard digital signal processing and up to 32 Mbytes of RAM maximizes total system performance and simplifies system integration.



Onboard computation of measurement results, fast data transfer to the host computer, and a dedicated high-speed data bus for module-to-module communication provide a high-performance measurement architecture for demanding mechanical, acoustic, and electrical test applications.

Parallel Processing Architecture

Multi-channel systems generate large amounts of data fast. This can overwhelm a host computer's data busses and computational capabilities. A parallel processing architecture increases performance by distributing computations over multiple processors, all performing their computations simultaneously (see figures 1 through 4 for the block diagrams of both the HP E1432A and HP E1433A digitizers.)

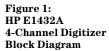
The HP E1432A and E1433A both use a floating point DSP processor to compute measurement results in the module. Computing measurement results onboard the HP E1432A and E1433A offloads computations from the host computer, preventing it from being a system performance bottleneck. This is especially important for large systems with many channels. Adding more HP E1432A and E1433A digitizers to a system adds more DSP processing capability, maintaining system performance even for extremely large systems. For example, an 80-channel HP E1433A-based system has 10 floating point processors computing measurement results in parallel. This provides a level of performance unattainable in systems that rely on the host computer alone to compute measurement results.

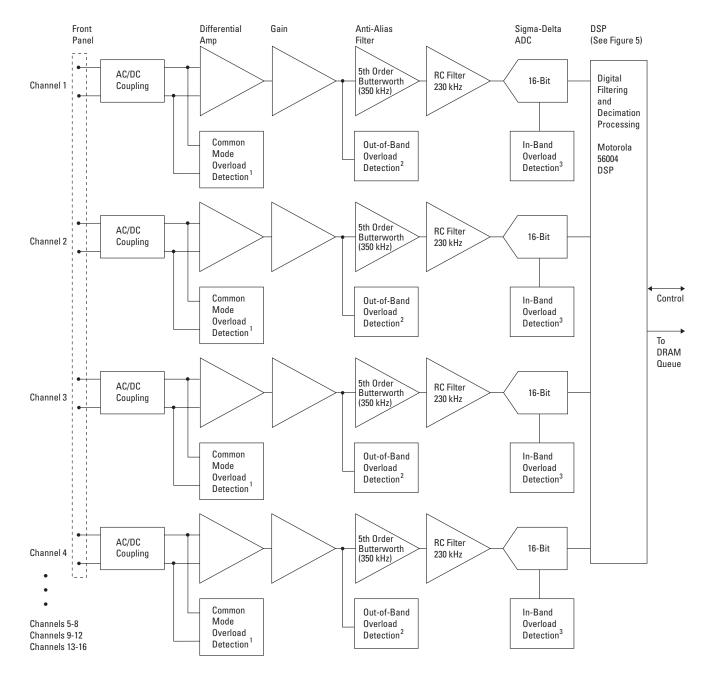
Move Data Fast

Once digitized data is processed, it must be moved to the host computer for display or further computations. The HP E1432A and E1433A provide very high data transfer rates to the host computer over the VXI bus so host computers can display information in real time. And, since the HP E1432A and E1433A can unload their information quickly, the VXI bus is not tied up, allowing other modules access to it.

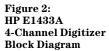
Dedicated High-Speed Local Bus

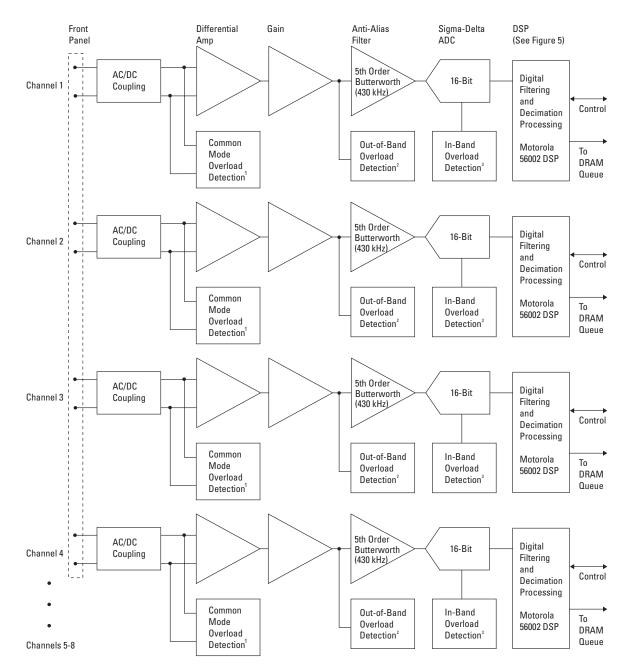
Applications such as throughput to disk require exceptionally high continuous data transfer rates to other VXI modules. VXI provides a dedicated "local bus" for such transfers. Since the local bus is dedicated to data only. its performance is unaffected by transfers between the host computer and other VXI modules. The HP E1432A can achieve a continuous (gapless) transfer of data over the local bus to an HP E1562E 8 GB SCSI data disk at >7.5 Msamples/sec (15 Mbytes/sec). Higher rates are achieved with multiple data disks. (See High Speed Data Capture section of this document.)





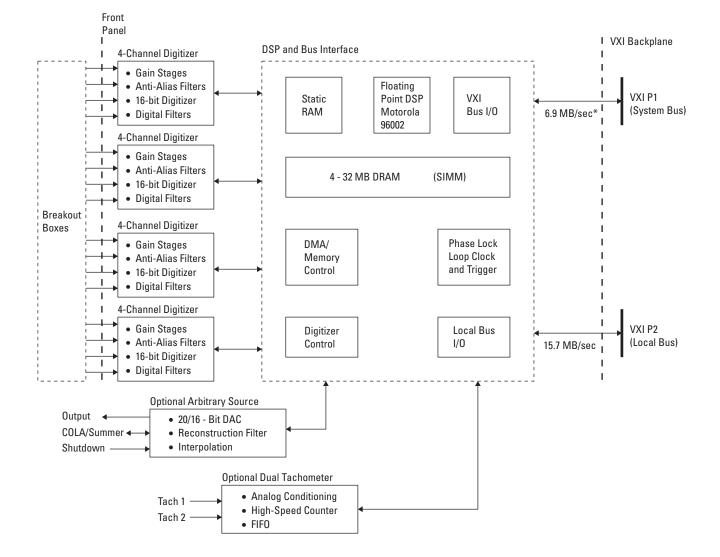
- ¹ Detects common mode overloads in differential amplifier.
- ² Detects signals which are more than 5 dB above selected input full scale range at all frequencies up to the MHz range.
- ³ Detects a full scale overload for signals within the pass band.





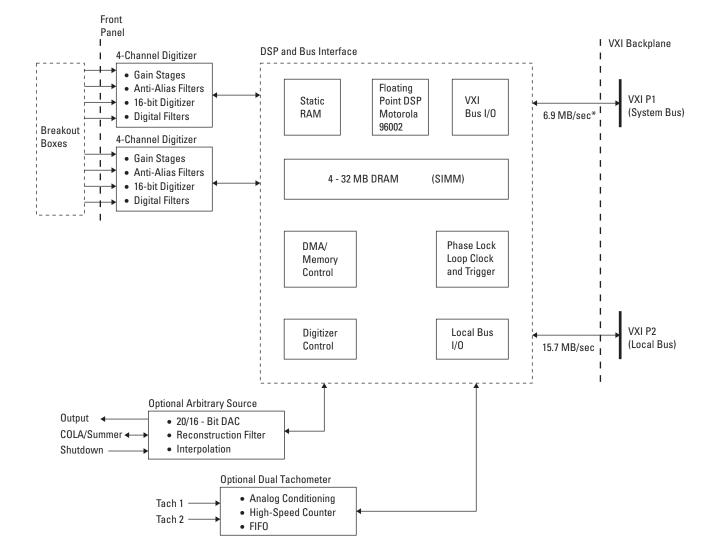
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- ³ Detects a full scale overload for signals within the pass band.





* 6.9 MBytes/sec represents the transfer rate over the VME bus when sending the 16 bit integer samples from the ADC to the host. A more typical transfer mechanism would be using the readFloat64Data which stores the data in the host as 64 bit floating point values. In this case the transfer rate is 27.6 MB/sec considering the 64 bit format as stored in the host.





* 6.9 MBytes/sec represents the transfer rate over the VME bus when sending the 16 bit integer samples from the ADC to the host. A more typical transfer mechanism would be using the readFloat64Data which stores the data in the host as 64 bit floating point values. In this case the transfer rate is 27.6 MB/sec considering the 64 bit format as stored in the host.

HP E1432A and E1433A Hardware Architecture

The HP E1432A and E1433A provide transducer signal conditioning, anti-alias filtering, digitization, and measurement computation in a single module. System software development is easier because you just set up one module. And, even more importantly, you don't have compatibility issues between separate signal conditioning, filter, digitizer, and DSP modules. The specifications of the entire measurement channel are predictable. If fact, they're guaranteed.

Signal Conditioning Breakout Boxes

The HP E1432A and E1433A use external breakout boxes to interface to voltage, Integrated **Electronics Piezo Electric (IEPE)** transducers, microphones, and piezoelectric charge transducers the most common transducers used in mechanical, acoustic, and electrical test. Four different breakout boxes let you configure your system any way you want. All breakout boxes, from the most economical voltage input breakout box to models that support three kinds of transducers, can be used with either the HP E1432A or E1433A. Different types can be mixed together on a single digitizer module. (See figures 5-8.)

Independent Input Channels

Each channel of an HP E1432A or E1433A has independent settings for:

- Range
- Differential/Single Ended
- •AC/DC coupling

The HP E1433A is the higherperformance model of the two digitizers. It supports lower fullscale input ranges, higher sample rates and bandwidths, has extra features, and has tighter specifications than the more economical HP E1432A.

HP E1433A Programmable Highpass Filters

Sometimes low-frequency noise components are larger than the signal you want to measure. Analog filters can remove the signal so you can reduce the channel's full-scale range, maximizing dynamic range. But analog filters have poor channel-to-channel phase matching due to component tolerances and component drift over time and temperature.

Digital filters, on the other hand, have great channel-to-channel phase matching but, since they only filter the data after it has been digitized, they don't allow you to reduce the input range to increase dynamic range. The HP E1433A uses a novel programmable 12 dB/octave highpass filter that provides the benefits of both analog and digital filters. By implementing the highpass filter digitally, but using a DAC to implement an actual analog summing at the input, the HP E1433A achieves the best of both technologies.

Acoustic intensity measurements are an application where tight channel-to-channel phase match is critical. In applications such as wind tunnel acoustic measurements, the HP E1433A removes low-frequency noise but still provides excellent channel-tochannel phase matching.

Simultaneous-Sampling Sigma-Delta ADCs

The HP E1432A and E1433A use an ADC per channel to avoid timing errors that often occur when a single ADC is multiplexed between multiple channels. Simultaneous sampling guarantees accurate channel-to-channel comparisons, both in the time and frequency domains. The HP E1432A and E1433A's sigma-delta ADCs use 64X over-sampling, allowing low-order analog anti-alias filters. Since the anti-alias filters corner frequencies are far above the channel's passband, the analog filters don't degrade performance in the passband.

Programmable Digital Anti-Alias Filters

Sigma-Delta ADC's by themselves have reduced aliasing protection as the sample rate is lowered. Aliased frequency products degrade measurement accuracy. Without good anti-alias filters, you can't trust your data. All filtering and sample-rate conversion in the HP E1432A and E1433A are done digitally, providing stable, drift-free filtering. For lower sample rates (f_.) the HP E1432A and E1433A use the on-board DSP to provide additional aliasing protection via digital filtering. This provides flat passbands and guaranteed -90 dB alias rejection down to very low sample rates — 6.25 Hz for the HP 1432A and 0.1464 Hz for the E1433A. See Figures 9 and 10 for the available sample rates and digital filter frequencies.

Figure 5: HP E3240A 8-Channel Voltage Breakout Box The HP E3240A is the most economical breakout box providing eight BNC connectors for interfacing to voltage signals.

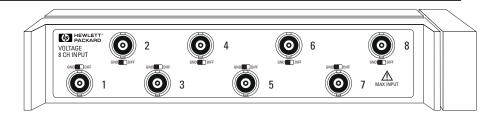


Figure 6: HP E3241A 8-Channel Voltage/Breakout Box with IEPE Power Supply The HP E3241A is identical to the E3240A with the addition of a software-switchable IEPE power supply.

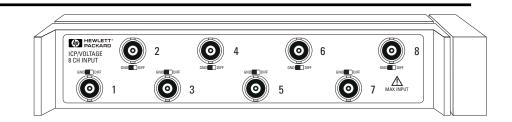
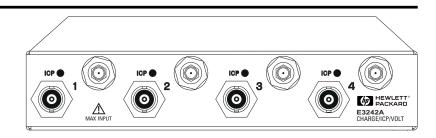


Figure 7: HP E3242A 4-Channel Charge/Voltage Breakout Box

The HP E3242A provides a charge amplifier for signal conditioning of piezoelectric transducers which are typical of many accelerometers. The HP E3242A also provides a voltage and an IEPE power supply.

Figure 8: HP E3243A 4-Channel Microphone/Voltage Breakout Box

For acoustic applications, the HP E3243A provides signal conditioning for microphones and also provides a voltage mode and an IEPE power supply.



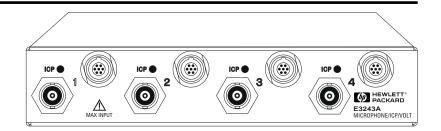
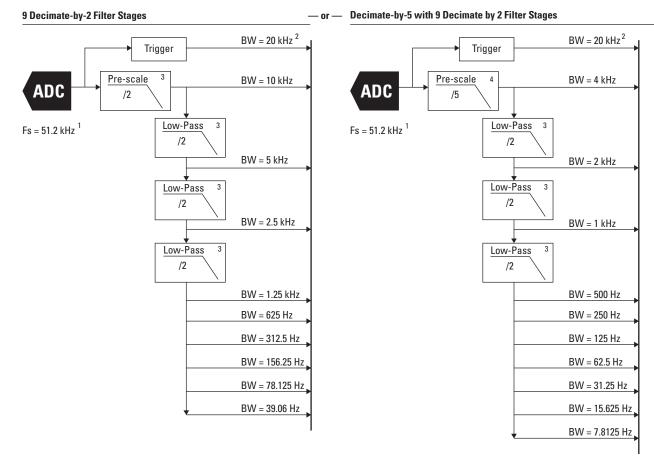


Figure 9: HP E1432A Digital Filtering and Decimation Processing



Zoom Digital Filtering HP E1432A

- ¹ Fs can be programmed to 32.000 kHz 51.2 kHz 40 kHz 50 kHz 40.96 kHz 31.250 kHz 49.152 kHz 39.0625 kHz 30.72 kHz 48 kHz 38.4 kHz or 26.2 kHz 44.1221 kHz 33.333 kHz 41.938 kHz 32.786 kHz If an external Fs is used, it must be a fixed freqency between 40.96 kHz and 102.4 kHz.
- ² 20 kHz represents 400 lines of 512-line spectrum. Before the first filter stage, 460 lines are actually accurate, giving 23 kHz maximum useable bandwidth.
- ³ 8th order elliptic.
- ⁴ 10th order elliptic.
- ⁵ Filters complex data

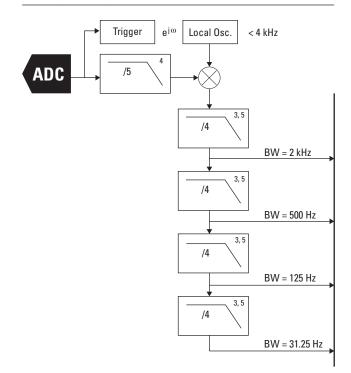
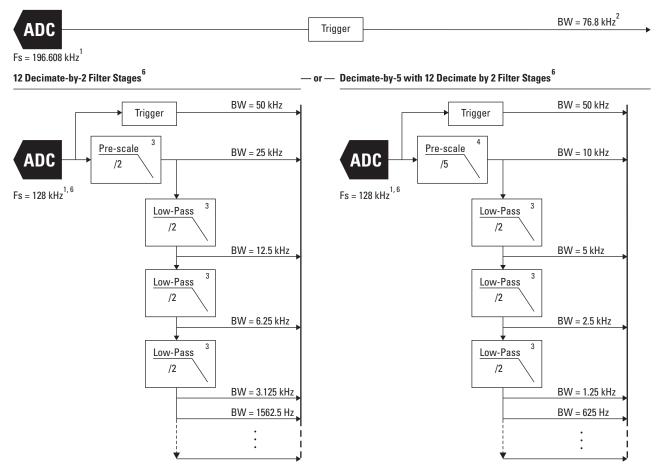
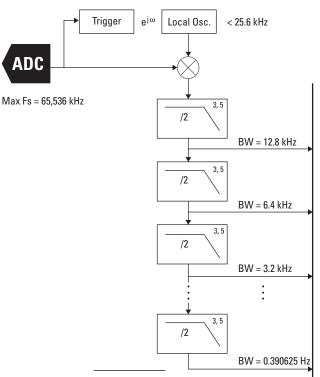


Figure 10: HP E1433A Digital Filtering and Decimation Processing



Zoom Digital Filtering HP E1433A



- ¹ Fs can be programmed to 196.608 kHz 100.0 kHz 61.44 kHz 192.00 kHz 98.304 kHz 52.4009 kHz 163.84 kHz 96.0 kHz 51.2 kHz 163.84 kHz 81.92 kHz 50.000 kHz 156.25 kHz 80.00 kHz 49.152 kHz 153.6 kHz 78.125 kHz 48.000 kHz 133.333 kHz 76.800 kHz 44.1221 kHz 128.0 kHz 66.666 kHz 41.9386 kHz 125.0 kHz 65.536 kHz or 40.96 kHz 122.88 kHz 64.0 kHz 102.4 kHz 62.5 kHz If an external Fs is used, it must be a fixed frequency between 40.96 kHz and 200 kHz.
- ² 78.6 kHz represents 400 lines of 512-line spectrum. Before the first filter stage, 460 lines are actually accurate, giving 88.32 kHz maximum useable bandwidth.
- ³ 8th order elliptic.
- ⁴ 10th order elliptic.
- ⁵ Filters complex data.
- ⁶ Note: Decimation only available for Fs 128 kHz and below.

Zoom for More Detail with the HP E1432A/E1433A

If you are only interested in the frequency range from 1000 to 2000 Hz, for example, why waste lines of resolution at other frequencies? Use zoom processing to put all frequency lines of the FFT in that range, focusing attention on the frequencies of interest.

Zoom spans available in the HP E1433A are 12.8 kHz, 6.4 kHz, down to 0.390625 Hz in power of 2 steps, with center frequencies less than 25.6 kHz. Zoom spans available in the HP E1432A are 2 kHz, 500 Hz, 125 Hz and 31.25 Hz with the center frequency less than 4000 Hz.

Onboard RAM Buffers

After data is digitized and filtered it is moved to circular RAM buffers, one buffer for each active channel. The buffers, combined with versatile pre- and post-triggering capabilities, make it easy to capture exactly the signal you want. To capture transients to onboard RAM, program the buffer size to the total number of samples you want to collect. Then set the amount of pre-trigger delay you want. Data will circulate through the buffers until the trigger occurs. The HP E1432A and E1433A will then freeze the pretrigger information in the buffers and continue collecting data until the desired total amount of data has been collected.

If you want to continuously acquire data to the host computer, the buffers can interrupt the host when they are half full. The host can then unload the buffers without effecting the ongoing data acquisition. Using these techniques, continuous data acquisition can proceed indefinitely. The only limitation is the rate at which data can be transferred to the host.

For very large acquisitions at very high rates, use the local bus to transfer data to an HP E1562E 8 Gbyte SCSI Data Disk at rates >15.7 Mbytes/sec. (See HP Publication 5965-6939E, and 5965-6938E.)

Onboard Measurements

A floating point processor copies data from the RAM buffer to its SRAM buffers for measurement computations. By computing FFTs, power spectrums, and order ratio analysis, it offloads work from the host processor. (See figure 11 for the HP E1432A data flow diagram.) It also creates a parallel processing architecture, allowing simultaneous processing in the host computer and each HP E1432A and E1433A.

The modules can also compute multiple measurements. You can send to the host time data and the FFT of this data, or, send raw time data, resampled time data and order data all at the same time.

In the HP E1433A you can also compute the RMS and Peak values.

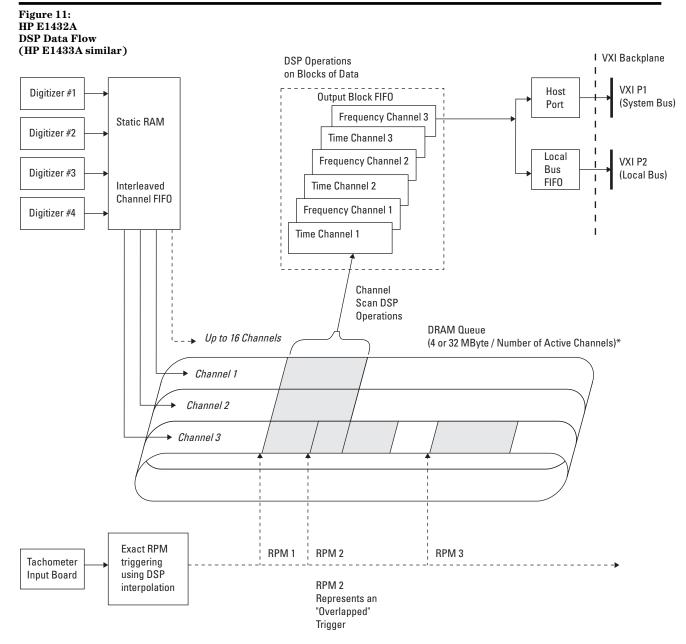
Two Highspeed Busses

The floating point processor can move data to the host computer over the VXI bus, or to another VXI module over the local bus. Or do both simultaneously. This allows the HP E1432A and E1433A to capture time data over the local bus to an HP E1562D/E Data Disk while also sending this time data (and computed FFTs of the acquired data) to the host over the VXI bus for monitoring the throughput process.

Optional Tach and Source

Two important options significantly enhance the HP E1432A and E1433A's capabilities. A tachometer (option AYF) input allows tight integration of tachometer information from rotating machinery with digitized data from the input channels. This provides the information the floating point processor needs to do RPM triggering of measurements, and order analysis measurements. (see Built-in Measurement section on page 14.) Since the tachometer is integrated with the digitizer, no host involvement is required for this functionality.

Instead of the tachometer you can add an optional 16-bit arbitrary source (option 1D4). Its sine, random, and arbitrary waveforms provide excitation for stimulus/ response testing. Again, tight integration of the source with the input channels and floating point processor simplifies testing since the host computer is not involved in controlling the measurement, the source DAC and ADC. The host is also relieved of computing many measurement results (windowing, FFT's, revolution domain resampling, etc).



* Note: FIFO size reduced with octave and peak/RMS calculations.

Built-In Measurements in Five Domains

The HP E1432A and E1433A turn data into information by providing data in whichever domain offers the most insight — time, frequency, octave, angle, or order. See figure 12 for a description of four data domains.

Time Domain

The most common data type for digitizers is the time domain. Since the HP E1432A and E1433A use simultaneous sampling, time relationships between signals are preserved, allowing accurate channel-to-channel comparisons.

Frequency Domain

Examining signals in the frequency domain allows you to resolve very small signals in the presence of large signals. The HP E1432A and E1433A use onboard DSP to compute windowed FFTs and averaged power spectrums. Averaging further improves your ability to see down into the noise. Several averaging types are supplied, including overlap processing.

The high performance of parallel processing is achieved without requiring any user programming.

Angle or Rotation Domain

Analyzing noise or vibration from rotating machines may require signal sampling to be synchronized to a shaft's rotational velocity. Adding Option AYF tachometer input lets you measure amplitude as a function of shaft angle, with fractions of a degree resolution. To further decrease noise, you can average multiple revolutions of the shaft.

The HP E1432A and E1433A avoid the inaccuracies and cost of the tracking filters and ratio synthesizers commonly used to make these measurements by computing the values in DSP. The floating point processor uses accurately measured tach times from the tachometer input to compute the actual values. Alias protection is guaranteed and errors associated with settling times of analog tracking filters and stability of ratio synthesizers are avoided.

Normalized Order Domain

Knowing the order, phase, and amplitude of signal components can be a great diagnostic tool in determining the cause of undesirable vibrations or noise in a rotating machine. The order domain provides the advantages of the frequency domain, but with all frequencies normalized to the shaft rotational velocity.

For example, to characterize the vibration of a rotating machine over its entire operating range of RPMs, choose a start RPM, stop RPM, and RPM interval. The tachometer input will trigger a set of order ratio spectrums to be measured at the selected RPMs during the machine's run-up or run-down. Onboard computations and automatic buffering of acquired data allow very fast run-ups and run-downs without missing data.

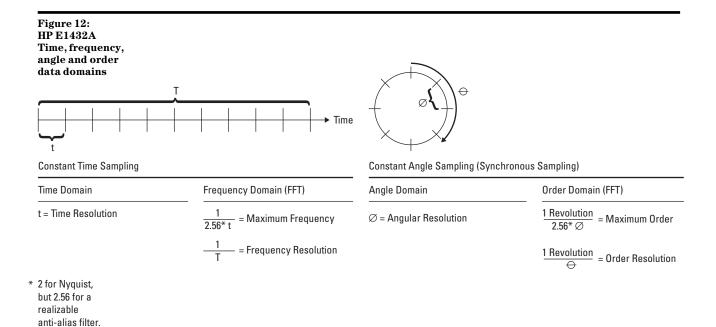
Optional Tachometer Input (Option AYF)

The optional tachometer input is required for angle and order domain analysis, but it has other uses. It provides RPM triggering of data acquisitions of all types time, frequency, angle, or order. Data acquired can be stamped with the RPM at which it was acquired. This optional tachometer input also provides a more flexible external trigger capability for either the HP E1432A or E1433A.

Optional Arbitrary Source (Option 1D4)

If your device-under-test requires excitation, the 16-bit arbitrary source option can provide stimulus to a shaker, loudspeaker, or electrical device. It saves money because it doesn't require an extra slot in the mainframe, and its trigger options make it easy to create elegant systems for doing stimulus/response testing.

The 1D4 option is equivalent to channel 1 of the HP E1434A 4-channel 65kSample/sec arbitary source. (See the HP E1434A section on page 17 for more information about the source option.)



Real Time Octave

The Fast Fourier Transform (FFT) has become very popular for quickly translating timedomain signals to the frequency domain. For acoustic applications the constant bandwidth distribution of an FFT (that is, the frequency scale is linear) is not as desirable as a constant percentage bandwidth distribution (a frequency scale that is logarithmic). The main reason for this constant percentage bandwidth is the human ear, which has a logarithmic characteristic.

Option 1D1 for the HP E1433A provides Real Time 1/1 or 1/3 Octave measurements. Third Octave bands cover 3.15 Hz to 20 kHz and the Full Octave bands cover 4 Hz to 16 kHz. All eight channels of the HP E1433A can be performing Real Time Octave measurements simultaneously. Adding multiple HP E1433A modules, each with option 1D1, allows Real Time Octave measurement to be running simultaneously on hundreds of channels.

The filter shapes meet or exceed ANSI S1.11.1986 Order 3, Type 1-D Extended and Optional Frequency Ranges, IEC 60225.

When the HP E1433A module is producing Real Time Octave data is can also send raw, unfiltered time domain data to the host. You can also request that the windowed, FFT of this raw, unfiltered data be computed and sent to the host. This capability allows both narrow band and constant percentage band data to be calculated simultaneously. There is a restriction in that the sample rate has to be the same (65536). The HP E3243A 4-Channel Microphone/Voltage Breakout Box provides a convenient signal conditioner for microphones when used with the HP E1433A. The HP E3243A provides -20, 0, or +20 dB of gain for the microphone signal, as well as, both the 28V preamplifier power and 200V microphone polarization voltage.

Choose:

- •A, B or C weighting
- •Exponential or linear averaging
- •Octave start and stop frequency
- •average integration time
- •exponential average time constant

Set:

- •a maximum level, hold mode
- averaging update rate (to the host) for either linear or exponential averages

High-Speed Data Capture

The HP E1432A and E1433A have multiple ways to record high-speed transients. Signals can be captured to onboard RAM, continuously sent to the host via the FIFO RAM buffer, or sent over the local bus to the HP E1562D/E SCSI Data Disk or other modules supporting local bus (HP E1485C).

Onboard RAM FIFOs

The HP E1432A and E1433A come standard with 4 MB of RAM. It can be increased to 32 MB RAM with the option ANC. Since there are 2 bytes per sample, this represents 16 Msamples of data. This RAM is evenly divided between the number of active channels. Digitized data flows into the RAM and can be read out to the host computer. If the data rates are not too fast, the host can read out the data continuously, without interrupting the measurement.

For very fast data rates, the RAM can be used to buffer the data for the host to read when the measurement is completed. Another method supported is to configure the buffer as a FIFO. This will allow the host to read out continuous data until the FIFO overflows. If the host is fast enough, the FIFO will never overflow. If the host can't read the FIFO fast enough, the FIFO will eventually overflow and the measurement will stop; however, the accumulated data can be read out at this time. You can also configure the RAM as a circular buffer that continually overwrites itself. This is useful if you want to capture the events that precede the trigger. Data will continually fill the

buffer until the trigger occurs. The RAM will then save the pretrigger data and continue taking data for the programmed amount of time.

Throughput to HP E1562D/E Data Disk

The VXI local bus provides a highspeed path to the HP E1562D/E SCSI Data Disk. Two versions are available, the 4 Gbyte HP E1562D with built-in 4 Gbyte DAT drive, or the 8 Gbyte E1562E without the DAT. The HP E1562E can capture data at a rate of greater than 5 Msamples/s (10 Mbytes/s) for the complete 8 Gbytes, with no gaps or glitches.

Using only the first 40% of the HP E1562E disks, the HP E1432A or the E1433A can achieve 7.5 Msample/s (15 Mbytes/s) sustained. Adding an HP E1562F to the HP E1562E, will allow sustained transfer rates of 7.5 Msample/s for all 17 Gbytes of disk space.

A system with one HP E1562E and one HP E1562F can sustain data transfers for 144 channels of HP E1432A's with each channel sampling at 51.2 kSa/s rate. For HP E1433A's, 40 channels at 196 kSa/s can be sustained using all 17 Gbytes of disk space.

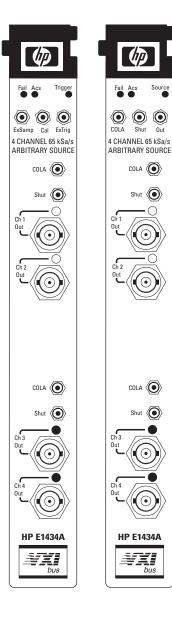
Monitor While Throughputting Data

Both the HP E1432A and the E1433A can throughput data to the E1562D/E via the local bus while at the same time, send a portion of this data over the slower VME bus to the host computer for monitoring purposes. The monitored data sent to the host can be either time data, frequency domain (FFT) or order data. This monitoring capability assures you that the data being recorded on the HP E1562D/E is valid.

Local bus is available for the HP E1432A and E1433A as option UGV.

When sending the sampled data to the host for monitoring, the two byte (integer) samples are typically converted to a 64 bit floating point value by the readFloat64Data function.

HP E1434A 4-Channel 65kSample/Sec Arbitrary Source



HP E1434A

HP E1434A with Option 1D4

The HP E1434A 4-Channel 65 kSamples/sec Arbitrary Source combines on-board creation of common waveforms with continuous arbitrary waveform playback to enhance ease of use and increase system performance compared to typical DAC architectures that have little built-in intelligence. The versatile waveform types and performance coupled with the HP E1434A's tight integration with both the E1432A and E1433A digitizers make it the ideal source for multi-channel stimulus-response measurements in both mechanical and electrical applications.

A single-channel version of the HP E1434A is available as an internal option (1D4) to the E1432A and E1433A digitizers.

Four Source Channels at 65 kSamples/Sec

The HP E1434A module provides 2, 4 or 5 arbitrary source channels. It provides four channels when run in the 16 bit, 65536 kSample/sec mode. This mode provides up to a 25.6 kHz bandwidth (also referred to as Span). A fifth source channel can be added to the HP E1434A with Option 1D4

For applications not needing four channels option 1DM can be ordered to delete two source channels.

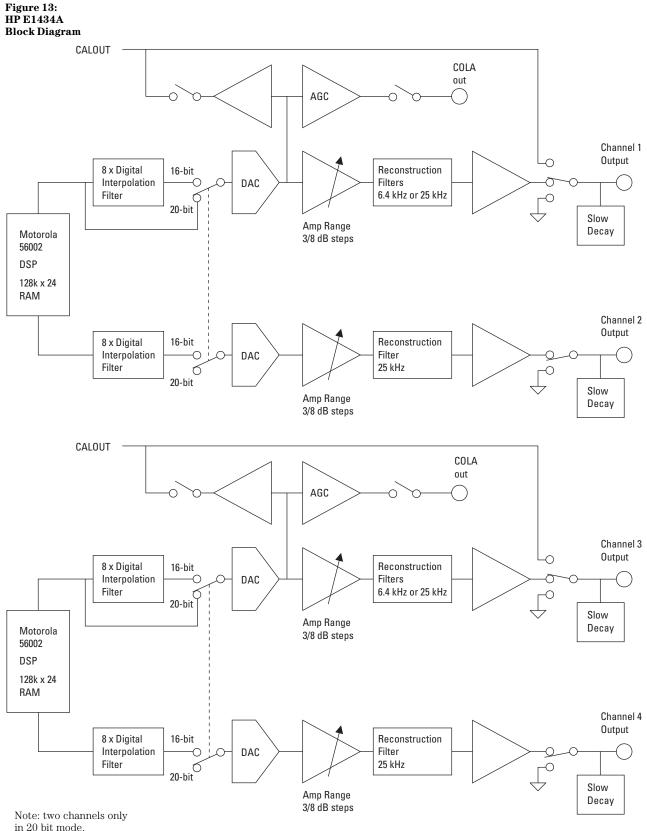
Common Waveforms Computed Internally

Built-in sine and random noise waveforms save development time and offload computations and data movement chores from the host computer. Multiple source channels can be programmed to output uncorrelated random noise, or each source channel can output the exact same random sequence.

The same versatile synchronization and triggering capabilities are available in both the HP E1434A and option 1D4. Since the HP E1434A is a separate module there is some additional flexibility from that offered by option 1D4. For instance, the input channels on an HP E1432A can be reinitialized without impacting the E1434A's current state.

Multiple Source Applications

In applications like Multiple-Input-Multiple-Output (MIMO) frequency response measurements or Structural Normal Mode testing, the number of sources (DACs) can easily be four or more. Also, in applications where large channel counts are needed for measured responses, the needed sources can be obtained either by adding an option 1D4 to each HP E1432A (or E1433A), or HP E1434As can be used to accomplish the same purpose.



in 20 bit mode.

High-Performance Architecture

Most simple DACs require the host computer to create waveforms and then download them to the DAC. By computing its own sine and random noise waveforms, the arbitrary source option offloads work from the host computer, preventing it from becoming a system performance bottleneck.

Both the HP E1434A and option 1D4 address this need.

Sine and Noise Waveforms

Sine waves are one of the most common test waveforms. Sinewaves can be continuous or burst waveforms, with frequencies from near zero to 25.6 kHz.

Uncorrelated and correlated noise waveforms are also available. The source provides pseudo random waveforms, in either continuous or burst mode. Different preprogrammed seeds (256) can be sent to each source to guarantee that each source's random output is uncorrelated with any other source in the system (or they can have the same seed which will cause the random output to be identical in each source). Additionally, the source can bandtranslate the noise to have a nonzero start frequency. This allows you to pinpoint the noise stimulus to frequencies of interest, avoiding troublesome resonances or frequencies that might damage the device under test. This bandtranslate capability allows the source to have a bandwidth and center frequency that matches the zoom FFT bandwidth and center frequency, creating a much higher quality measurement.

Arbitrary Waveforms

Use arbitrary waveforms to provide almost any stimulus you can imagine. Arbitrary waveforms are supported in both option 1D4 and the HP E1434A.

You can download an arbitrary waveform into the modules 32 MB RAM and then have the module output this waveform either repetitively or as a single shot, with no further intervention from the host.

Variable Resolutions

The arbitrary source can be used as a 16-bit source with 25.6 kHz bandwidth, or as a 20-bit source with 6.4 kHz bandwidth.

The two modes are selectable by software. The 20-bit mode is useful for applications where the extra head room allows smooth output level changes over a wide amplitude range. In the HP E1434A, the 20-bit mode reduces the available channels per module from four to two (see E1434A block diagram).

Safety Features

Since arbitrary sources can drive very expensive devices under test, it is important to provide an orderly shutdown in case of emergency. In addition to programmable ramp-up and rampdown rates, the arbitrary source has a smooth ramp-down from AC power failure, or in response to its emergency shutdown input.

Local Bus Option

Option UGV is available on the HP E1434A, but is not needed or useful for most applications.

VXI*plug&play* Library Functions

Software Support

Software support for the HP E1432A, E1433A and E1434A is very comprehensive, allowing the utmost in flexibility and performance. The VX|*plug&play* library supporting the module has a companion component that is downloaded the first time the module is used after a system powerup or reset.

This downloading feature allows the module to remain current with changes in operating systems, new software features and bug fixes. The most current revision of this library is always available at no cost to the user by an anonymous ftp connection to a Hewlett-Packard server .

High Performance

The VXI*plug&play* host library offers high-performance data movement and DSP computations within the module. In the case of the HP E1432A, up to nine modules, with 16 channels each (144 channels total) running at 51.2 kSamples/sec/channel can write their data to a local bus in real time. This is an aggregate rate of 15.7 Mbytes/sec continuously. The HP E1433A can achieve comparable rates. From a DSP performance perspective, the HP E1433A can be set up to compute FFTs on each channel and at the completion of 16 averages at a block size of 2048, upload these FFT results to an HP V743 host and stay real time at a 20 kHz bandwidth (51.2 kSa/sec/ch) for a total of 48 channels (six HP E1433A modules). There is a great deal of flexibility here. You can upload each time history along with each FFT average, change the number of averages, change the window type, etc.

Multiple Platforms Supported

The VXI*plug&play* host libraries for the HP E1432A, E1433A and E1434A are supported in HP-UX 9.X and 10.2 both with the embedded HP V743 host computer and external HP Series 700 computers via the MXI interface. Software environments such as HP VEE, MathWorks MATLAB, C, and C++ are supported.

For personal computers (PCs), the library supports both Win95 and WinNTTM environments on both embedded (HP E6234A) and external hosts via either Firewire (HP E8491A) or MXI-2 interfaces. Software environments such as HP VEE, MathWorks MATLAB, Microsoft C, C++ and Microsoft Visual Basic are supported. Contact your local HP representative for the current support matrix.

Full Featured

The VXI*plug&play* library contains more than 380 functions to extract the most in performance and flexibility from the modules. This library allows the HP E1432A/33A/34A to turn data into information by providing data in whichever domain offers the most insight — time, frequency, angle, order, or octave.

The next section lists the functions available in a hierarchical grouping. Most functions have both a "set" and "get" version. The set function, like setRange, allows a single channel (or group of channels) to have the full scale range set. The get function interrogates the current setting. For instance, suppose you setRange to 8.5 volts. The setRange function knows that there is no full scale range of 8.5 volts, and sets the full scale value to the next higher valid range. The getRange would return a value of 10 volts in this example, since 10 volts is the next higher range. Most all functions also have a default setting, so if no "set" is called a default value is used and can be interrogated by the get function.

Control HP E1432A/ E1433A/ E1434A Directly from Mathworks's MATLAB

If you are one of the more than 400,000 users of MATLAB and would like to directly control HP's high performance multi-channel digitizers and source modules, HP is now supplying this control capability as part of its standard Plug & Play library for the HP E1432A, HP E1433A and HP E1434A VXI modules. The combination of MATLAB 5.x's n-dimensional arrays, matrix math, color surface shaded 3-D graphics, user interface building tools and HP's high performance measurement hardware provide most impressive results with a minimum of programming effort. This environment is really the "measurement engineer's programming language" that quickly turns measurements into insight.

Simple for Simple Tasks

HP's Plug & Play library for the HP E1432A makes controlling the hardware easy for simple data acquisitions tasks. Setting up the module to acquire time data on four active channels onboard the HP E1432A card is shown in Figure 14. The program initializes the module with four active channels at a specific sample rate, full scale range and then uploads a 1024 block of samples for each channel to the host. Plotting is accomplished with the simple call of the MATLAB Plot command.

Figure 15 shows the on-line help text for one of the VXI*plug&play* library functions used in the example.

Figure 16 shows another example of the results obtained from a 10 second run up (1000 to 3500 RPM) of an automobile engine tracking the vibration (acceleration) response as a function of rpm. In this combined 3-D plot and top down view, the vibration response is plotted as harmonics of crankshaft rotation versus RPM. This presentation gives a quick overall feel of the vibration signature as a function of rpm and orders for this engine with over 100,000 miles on its odometer. To obtain these results a less than four page MATLAB program sets up and controls the HP E1432A and plots the results shown in figure 16. The HP E1432A digitizer in conjunction with its optional tachometer, digitizes the acceleration data at a fixed sample rate and then using the tachometer data and the sampled data (stored in its 32 MByte of RAM), resamples the data via a built-in digital filter to provide new samples that are now sampled at even increments of crankshaft rotation. This process is repeated at every 100 rpm increase in engine speed (user specified) with the results sent to the host computer on-line. This particular set of plots was obtained during a 10 second engine run-up with these final graphical results appearing on PC's screen within 5 seconds of completing the run-up (using an HP E6233A embedded Pentium controller). Matlab's user interface building tools make the user interface shown to setup the hardware easy to build - taking less than an hour to create. This program is one of the example MATLAB scripts included with the HP E1432A/ 33A/34A Plug and Play library. All of the VXI*plug&play* functions for the HP E1432A/33A/34A are available to the MATLAB user, except the seven interrupt functions. These MATLAB examples along with additional examples in C, Visual Basic and HP VEE give you a great head start in developing your application solutions.

Figure 14: Matlab example program using Plug & Play Library calls to the HP E1432A

% Simple Matlab example of a four% This runs continuously , updating		h "Control C"
BLOCKSIZE = 1024 OLDCHANNELS = [1 2 3 4 5 6 7 8] CHANNELS = [1 2 3 4] SPAN = 20000. RANGE = 10.0	% Make this variable 1 thru % Number of active channel	frequency span (sample rate divided by 2.56)
[status,session] = hpe1432('init','VXI		address 8 and return the session virtual
[status] = hpe1432('deleteAllChanG	roups',session); %House cleaning to delete a	ll previous channel groups
[status,gid] = hpe1432('createChann		CHANNELS),OLDCHANNELS);
	% Create a group of all % channels. NOTE that the o as gid (group ID)	channel id for this group of channels is returned
[status] = hpe1432('setActive',sessio	on,gid,'CHANNEL_OFF');	% Turn all channels off
[status] = hpe1432('deleteAllChanG	roups',session);	% Delete all channels groups
[status,gid] = hpe1432('createChann	elGroup',session,length(CHA)	NNELS),CHANNELS); % Create a group of four active channels
[status] = hpe1432('setBlocksize',set	ssion,gid,BLOCKSIZE);	% set the block size for all channels
[status] = hpe1432('setRange',sessio	on,gid,RANGE);	% Set full scale voltage range
[status] = hpe1432('setSpan',session	,gid,SPAN);	% Set alias protected span (sample rate / 2.56)
[status] = hpe1432('setDataMode',se	ession,gid,'BLOCK_MODE');	% Place module in block acquisition mode
[status] = hpe1432('setAutoTrigger',	session,gid,'MANUAL_TRIGG	ER'); % Setup trigger mode
[status] = hpe1432('initMeasure',ses	sion,gid);	% start data acquisition
A=1; while A>0,		
[status] = hpe1432('triggerMeasure',	session,gid,'NO_WAIT_FLAG % Trigger a block of data on	
[status,data,count] = hpe1432 ('read BLOCKSIZE*length(CHANNELS),'W	dFloat64Data', session,gid, 'TI /AIT_FLAG');	
plot(reshape(data,BLOCKSIZE,leng		a into 2D matrix (channels versus samples)
A=A+1 end	% let user know the loop is w	vorking
[status] = hpe1432('close',session);		

Figure 15: The on-line help text for each function is very useful when actually creating your measurement program. Shown here is an example of the help text for the setRange function.

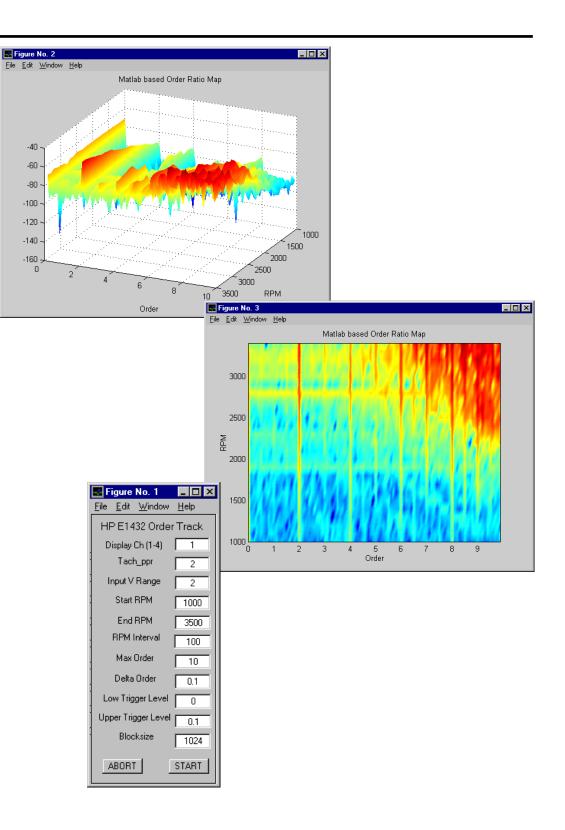
hpe1432_setRange

Syntax: ViStatus _VI_FUNC hpe1432_setRange(ViSession vi, ViInt32 group, ViReal64 range);

<u>Example</u> Sets the range of one or more channels.

vi	<u>Description</u> Instrument Handle returned from hpe1432_init(). Data Type: ViSession Input/Output: IN
group	This is the group handle returned from <u>hpe1432 createChannelGroup()</u> or a channel number of a channel that has been assigned to a group using <u>hpe1432 createChannelGroup()</u> .
	Data Type: ViInt32 Input/Output: IN Values: HPE1432_GROUP_ID_MIN8000 HPE1432_GROUP_ID_MAX 12288
range	Sets the input range in volts.
	Data Type: ViReal64 Input/Output: IN Values:
	HPE1432_RANGE_MIN 0.0 HPE1432_RANGE_MAX 10.0
Comments:	
hpe1432_set_range sets the ra	ange, of a single channel or group of channels, to the value given in range.
ID is either the ID of a group single channel.	of channels that was obtained with a call to hpe1432_create_channel_group, or the ID of a
	n volts. Signal inputs whose absolute value is larger than full scale will generate an ADC ually, there is several dB of overhead before the ADC will overflow, to avoid spurious overflo
The actual range that is set w range parameter.	vill be the nearest legal range value that is greater than or equal to the value specified by the
For input channels, the range	e is used only when the input mode is Voltage or IEPE transducer power supply
	put_mode). When the input mode is Charge, the range_charge parameter is used instead nge_charge). When the input mode is microphone mode, the range_mike parameter is used
(see hpe1432_set_rar instead (see hpe1432 For source channels the rang purpose), and can't b	put_mode). When the input mode is Charge, the range_charge parameter is used instead nge_charge). When the input mode is microphone mode, the range_mike parameter is used
(see hpe1432_set_rat instead (see hpe1432 For source channels the rang purpose), and can't b hpe1432_set_amp_sc	put_mode). When the input mode is Charge, the range_charge parameter is used instead nge_charge). When the input mode is microphone mode, the range_mike parameter is used 2_set_range_mike). ge specifies an overall maximum signal level (typically on a range DAC reserved for that be changed instantaneously during output. To change the signal amplitude during output, use cale, which can scale the output level by an (almost) arbitrary scale factor.
(see hpe1432_set_rar instead (see hpe1432 For source channels the rang purpose), and can't b hpe1432_set_amp_sc For tach channels, neither rar	put_mode). When the input mode is Charge, the range_charge parameter is used instead nge_charge). When the input mode is microphone mode, the range_mike parameter is used 2_set_range_mike). ge specifies an overall maximum signal level (typically on a range DAC reserved for that be changed instantaneously during output. To change the signal amplitude during output, use cale, which can scale the output level by an (almost) arbitrary scale factor.
(see hpe1432_set_rar instead (see hpe1432 For source channels the rang purpose), and can't b hpe1432_set_amp_sc For tach channels, neither rar This parameter may also be s After a reset, input channels l	put_mode). When the input mode is Charge, the range_charge parameter is used instead nge_charge). When the input mode is microphone mode, the range_mike parameter is used 2_set_range_mike). ge specifies an overall maximum signal level (typically on a range DAC reserved for that be changed instantaneously during output. To change the signal amplitude during output, use cale, which can scale the output level by an (almost) arbitrary scale factor. nge nor amplitude are used.
(see hpe1432_set_rar instead (see hpe1432 For source channels the rang purpose), and can't b hpe1432_set_amp_sc For tach channels, neither rar This parameter may also be s After a reset, input channels l	put_mode). When the input mode is Charge, the range_charge parameter is used instead nge_charge). When the input mode is microphone mode, the range_mike parameter is used 2_set_range_mike). ge specifies an overall maximum signal level (typically on a range DAC reserved for that be changed instantaneously during output. To change the signal amplitude during output, use cale, which can scale the output level by an (almost) arbitrary scale factor. nge nor amplitude are used. set with hpe1432_set_analog_input. have the range set to 10 volts. Source channels have the range set to the minimum legal source is also inactive, so no signal is produced).
(see hpe1432_set_rar instead (see hpe1432 For source channels the rang purpose), and can't b hpe1432_set_amp_sc For tach channels, neither rar This parameter may also be s After a reset, input channels h range (and the source Return Value: VI_SUCCESS: No er	put_mode). When the input mode is Charge, the range_charge parameter is used instead nge_charge). When the input mode is microphone mode, the range_mike parameter is used 2_set_range_mike). ge specifies an overall maximum signal level (typically on a range DAC reserved for that be changed instantaneously during output. To change the signal amplitude during output, use cale, which can scale the output level by an (almost) arbitrary scale factor. nge nor amplitude are used. set with hpe1432_set_analog_input. have the range set to 10 volts. Source channels have the range set to the minimum legal source is also inactive, so no signal is produced).





VXI*plug&play* Library Function List

Control by array arrayControl arrayNextChan arrayReadChan

Arm

getArmChannel setArmChannel getArmMode setArmMode getArmTimeInterval getArmTimeIntervalLimits setArmTimeInterval getNextArmRpm getPreArmMode setPreArmMode getPreArmRpm getPreArmRpmLimits setPreArmRpm getRpmHigh getRpmHighLimits setRomHigh getRpmInterval getRpmIntervalLimits setRpmInterval getRpmLow getRpmLowLimits setRpmLow getRpmSmoothing getRpmSmoothingLimits setRpmSmoothing

Control

setAutoGroupMeas getCalDac getCalDacLimits setCalDac getCalVoltage getCalVoltageLimits setCalVoltage getCalin setCalin getClockMaster setClockMaster getClockSource setClockSource getDataPort setDataPort getFifoSize getFifoSizeCurrentMax getFifoSizeLimits setFifoSize getLbusMode setLbusMode getLbusReset getMultiSync setMultiSync getSumbus setSumbus getTtltrgClock setTtltrgClock getTtltrgGclock setTtltrgGclock getTtltrgLines setTtltrqLines getTtltrgSatrg setTtltrgSatrg getTtltrgTrigger setTtltrgTrigger

Data Transfer

blockAvailable checkOverloads getCurrentValue getRawTachs readFloat64Data readRawData readTrailerData

Format

getAppendStatus setAppendStatus getDataMode setDataMode getDataSize setDataSize setUserData High Access setAnalogInput

setDataFormat setInterrupt setTrigger

Input

autoRange getAntiAliasAnalog setAntiAliasAnalog getAntiAliasDigital setAntiAliasDigital getAutoRangeMode setAutoRangeMode setCouplingFreq* getCoupling getCouplingFreq* getCouplingFreqLimits* setCoupling getInputHigh setInputHigh aetInputLow setInputLow aetInputMode setInputMode getInputOffset getInputOffsetLimits setInputOffset getPeakDecayTime* getPeakDecayTimeLimits* setPeakDecayTime* getPeakMode setPeakMode setRamp getRange getRangeCharge getRangeChargeLimits getRangeLimits setRange setRangeCharge getRangeMike getRangeMikeLimits setRangeMike aetRmsAvaTime* getRmsAvgTimeLimits* setRmsAvaTime* getRmsMode* setRmsMode* getScale getWeighting* setWeighting*

* Function only available in HP E1433A.

Interrupt

getInterruptMask setInterruptMask getInterruptPriority getInterruptPriorityLimits setInterruptPriority getInterruptReason reenableInterrupt

Measurement

getActive setActive getAvgMode setAvgMode getAvgNumber getAvgNumberLimits setAvgNumber getAvgUpdate getAvgUpdateLimits setAvgUpdate getAvgWeight getAvgWeightLimits setAvgWeight aetBlocksize getBlocksizeCurrentMax getBlocksizeLimits setBlocksize getCalcData setCalcData getCenterFreq getCenterFreqLimits setCenterFreq getClockFreq getClockFreqLimits setClockFreq getCurrentRpm getDataRpm getDecimationOutput setDecimationOutput getDecimationOversample setDecimationOversample getDecimationUndersamp getDecimationUndersampLimits setDecimationUndersamp getDecimation getDeltaOrder getDeltaOrderLimits setDeltaOrder

getEnable setEnable getFilterFreq getFilterFreqLimits setFilterFreq getFilterSettlingTime getFilterSettlingTimeLimits setFilterSettlingTime getMaxOrder getMaxOrderLimits setMaxOrder getMeasTimeLength getMeasTimeLengthLimits setMeasTimeLength getMmfDelay setMmfDelay getOverlap getOverlapLimits setOverlap getRmsDecayTime getRmsDecayTimeLimits setRmsDecayTime getSampleMode setSampleMode getSamplesToPreArm getSpan getSpanLimits setSpan setUserWindow getWindow setWindow getXferSize getXferSizeLimits setXferSize getZoom setZoom

Measurement Action armMeasure autoZero cachedParmUpdate finishMeasure getMeasState initMeasureFinish initMeasureFinish initMeasureMasterFinish initMeasureMasterSetup initMeasureSlaveFinish initMeasureToBooted preArmMeasure resetMeasure triggerMeasure

Octave

getCurrentData getOctaveAvgMode setOctaveAvgMode getOctaveBlocksize getOctaveHoldMode setOctaveHoldMode getOctaveIntTime getOctaveIntTimeLimits setOctaveIntTime getOctaveMeas setOctaveMeas getOctaveMode setOctaveMode getOctaveStartFreq getOctaveStartFreqLimits setOctaveStartFreq getOctaveStopFreq getOctaveStopFreqLimits setOctaveStopFreq getOctaveTimeConst getOctaveTimeConstLimits setOctaveTimeConst getOctaveTimeStep getOctaveTimeStepLimits setOctaveTimeStep octaveCtl

Source

checkSrcArbRdy checkSrcOverload checkSrcOverread checkSrcShutdown checkSrcUnderrun getAmpScale getAmpScaleLimits setAmpScale getDutyCycle getDutyCycleLimits setDutyCycle getRamp getRampRate getRampRateLimits setRampRate getSineFreq getSineFreqLimits setSineFreq getSinePhase getSinePhaseLimits setSinePhase getSourceBlocksize getSourceBlocksizeLimits setSourceBlocksize getSourceCenterFreq getSourceCenterFreqLimits setSourceCenterFreq getSourceCola setSourceCola getSourceMode setSourceMode getSourceOutput setSourceOutput getSourceSeed getSourceSeedLimits setSourceSeed getSourceSpan getSourceSpanLimits setSourceSpan getSourceSum setSourceSum getSrcArbStates getSrcBufferInit setSrcBufferInit getSrcBufferMode setSrcBufferMode getSrcBufferSize getSrcBufferSizeLimits setSrcBufferSize getSrcParmMode setSrcParmMode srcGetFwrev srcGetRevsrcProgRomImage srcRxfr updateSrcParm writeSrcBufferData

Tach

getTachClockFreq getTachDecimate getTachDecimateLimits setTachDecimate getTachDelay getTachHoldoff getTachHoldoffLimits setTachHoldoff getTachIrqNumber getTachIrqNumberLimits setTachIrqNumber getTachMaxTime getTachMaxTimeLimits setTachMaxTime getTachPpr getTachPprLimits setTachPpr sendTachs

Trigger

getAutoTrigger setAutoTrigger getCalTrigCorr getTriggerChannel setTriggerChannel getTriggerDelay getTriggerDelayLimits setTriggerDelay getTriggerExt setTriggerExt getTriggerLevel getTriggerLevelLimits setTriggerLevel getTriggerMaster setTriggerMaster getTriggerMode setTriggerMode getTriggerSlope setTriggerSlope getTriggersPerArm getTriggersPerArmLimits setTriggersPerArm sendTrigger

Utility Errors

errorDetails error_message error_query setTraceLevel

Low Level

readl2C readRegister16 readRegister32 scaDspDownload scaDspExecQuery writel2C writeRegister16 writeRegister32

Overhead

channelGroupAdd channelGroupRemove createChannelGroup deleteAllChanGroups deleteChannelGroup find getAutoGroupMeas getFwrev getGroupInfo getHWConfig getMeasWarning getMeasWarningString getNumChans getSerialNum install nstallFile preset . reset resetLbus revision_query selftest



HP E1432A, E1433A, E1434A

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Hewlett-Packard Canada Ltd. 5150 Spectrum Way Mississauga, OntarioL4W 5G1 (905) 206 4725

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