Nuts & Volts

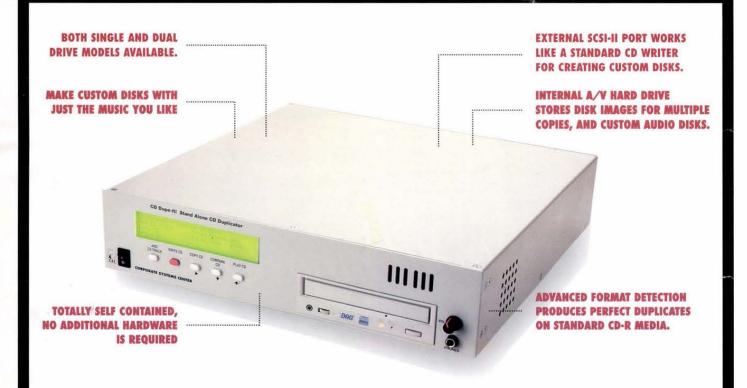
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February 1999 Vol. 20 No. 2

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Interface box has two SCSI-II ports on back, and a DC power input (we do not have the adapter), and on the front.

it has a mic. out jack, composite video out (BNC), and the

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- Fig. 1 Automatic Finding dialer has solew terminals for sensor input, power adapter, and very long phone cord.
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HSC#17720 Digital Control Motion Alarm \$15.00 \$008B Digital Control Motion Alarm with Safety Chime has wall-mount keypad, PIR infrared motion detector (same as \$002M above) with very loud alarm OR safety chime

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- alarm or pleasant door chime. Uses 3 AAA batteries (not included) HSC#17722 Digital Entry Guard Alarm

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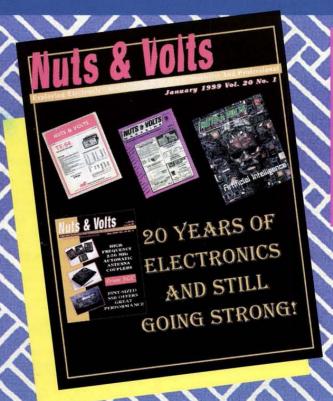
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February Drawing hosted by RESOURCES UNLIMITED (see page 14)

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BOATERS AND ROVERS UPSET WITH HF SSB PHONE SERVICE SHUTDOWN

February 28th is the final day that AT&T will handle telephone calls over high-frequency single sideband. But there will still be ways to communicate effectively ...

Gordon West ... Page 6

LOOKING INSIDE A POWER SPLITTER

Ever wonder what's inside a TV power splitter? Read on ...

Gerald Roylance ... Page 10

AUTOMOTIVE NAVIGATION: WHERE IT'S AT AND WHERE IT'S GOING

This article explains the inner workings of automotive navigation systems. Jeff Stefan ... Page 19

BUILD AN INEXPENSIVE WHOLE-HOUSE TEMPERATURE/ **HUMIDITY MONITORING SYSTEM — PART 1**

With the THX10 remote monitoring system described in this article, you will be able to transmit data from up to eight monitoring stations on your house's power line, and receive the information on your PC, without any calibration or wiring between rooms.

Mike Keryan ... Page 33

MAGNIFIERS 1X TO 1000X

Magnifiers come in many sizes, shapes, and prices. Find out which one is the best for your applications.

John C. Little ... Page 76

DOING ELECTRONIC CALCULATIONS WITH ELCAD

Learn to use this simple software program that allows you to do some fairly complex electronic calculations quickly, and print out the results.

Fred Blechman ... Page 89

Columns

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AMATEUR ROBOTICS NOTEBOOK

Even though you will be starting with a very simple hardware/software combination, this month's project will put your skills to the test. Robert Nansel ... Page 82

ELECTRONICS Q & A

TJ Byers ... Page 66

OPEN CHANNEL

Lightning observing: some lightning detection history, types of lightning, and constructing a storm scope.

Cover Story

Joe Carr ... Page 15

RESOURCE BIN

Another look at some favorite websites.

Don Lancaster ... Page 79

STAMP APPLICATIONS

If you ever wanted to store a text file and parse the data out to some serial device, or have a string of serial data stored automatically, then the RAMPack B may be just what you're looking for.

Lon Glazner ... Page 62

Nuts & Volts Magazine, 430 Princeland Court, Corona, CA THE COMPUTER-CONTROLLED WORLD

Will return next month ...

DEPARTMENTS

91719

Nuts & Volts Magazine is published monthly for \$19.00 per year by T&L Publications, Inc., 430 Princeland Court. Corona, CA. POSTMASTER: Send address changes to

Advertiser's Index ... 74 Classified Ad Info ... Dealer Directory ... 88 Events Calendar ... 41 New Product News ... 93 News Bytes ... 32 NV AdMart ... 86-87 Reader Feedback ... 13 Tech Forum ... 69

CLASSIFIED AD INDEX

44
0
44
0
45
46
46
46
48

90. Satellite Equipment	50
95. Military Surplus Electronics	50
100. Audio/Video/Laser	50
110. Cable TV	51
115. Telephone/Fax	52
120. Components	
125. Microcontrollers	53
130. Antique Electronics	53
135. Aviation Electronics	54
140 Publications	54

145. Robotics	54
150. Plans/Kits/Schematics	
155. Manuals/Schematics	
Wanted	55
160. Misc. Electronics For Sale	55
170. Misc. Electronics Wanted	56
175. BBS & Online Services	57
180. Education	57
190. Business Opportunities	57
200. Repairs/Services	

















BOATERS AND ROVERS UPSET WITH HF SSB PHONE SERVICE SHUTDOW

by Gordon West

ometime in the late afternoon on February 28th, AT&T station KMI in San Francisco, AT&T station WOO in New Jersey, and AT&T station WOM in Miami go off the air. Thousands of boaters, missionary stations, RVers, backpackers, and isolated stations depending on them for powerful high-frequency telephone coverage won't even get a friendly operator to tell them there is no more service. All they will hear on the 50 channels on high frequency between 2 MHz to 26 MHz is white noise.

For decades, the AT&T high seas radiotelephone service has provided powerful global

high-frequency connections to the AT&T land-line system in the United States. Their three stations each ran thousands of watts of power into phased-array towers, giving mariners out on the high seas almost global coverage to their stations manned by helpful technical and telephone operators. Ship station equipment could be a simple 10watt marine single sideband, or an elaborate full-duplex commercial kilowatt origiis sometimes a problem. For satellite calls to the geostationary relay space stations, the delay is due to the 22,500-mile radio path. On local digital cellular networks, the delay is the analog-to-dialogue-to-analog conversion. The delay will sometimes cause an echo, but will usually make a fastsible when both parties are trying to speak at the same time.

paced conversation almost impos-But on marine single sideband over high frequency, there was no delay - and this made HF

Electronic techs will have good business programming old SSB with new WLO "AT&T's high seas radiotelephone service has played an integral role in the development of maritime communications. However significant the accomplishment, time and technology have steadily advanced commercial mobile satellite communications. So much, in fact, that demand from seafarers for more sophisticated and costeffective methods of communications has outpaced the needs for terrestrial radio services. As a result, AT&T will close its three radio coast stations as of February 28, 1999," comments Vince Zuza, Mobile Satellite Service Manager of AT&T.

Gordon West (L) discusses the new channels for WLO with ICOM America's Jim Tindall (R).

nally found aboard cruise ships. The AT&T channels were duplex, so bigger equipment could allow full duplex — talk and listen — so either party could interrupt each other during the phone call.

Full duplex on marine single sideband high frequencies is actually more desirable for a phone call than the new satellite systems. The satellite systems, including new digital cellular systems, have a delay in a full-duplex conversation, so interrupting a fast-paced phone call

February 28, 1999, is the final day that AT&T will handle telephone calls over high-frequency single sideband.

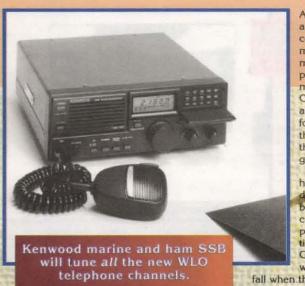
phone calls from a relatively simple piece of high-frequency equipment a great way to go. Prices were also cheap through the AT&T high seas service, who charged no monthly fee to be registered, and the only time you paid \$5.00 a minute was when you were actually speaking with a party you were calling or the party that

had called you in the remote area. You would not be charged for a busy number, nor would you be charged for radio checks, calls to the Coast Guard, or calls to the operator just to double-check for messages holding.

Not only will boaters be off the air with single sideband phone calls to AT&T, but also the thousands of users who use the AT&T station to their SSB equipment SOMEWHERE out there in radio land. Although the high seas ser-

channels.





vice is specifically for boats, there are thousands of users who may be sailing in jungles, mountain peaks, remote deserts, remote campsites in Alaska, remote valleys in Canada, remote villages in Mexico, and just about anywhere else that is not presently served by cellular telephone service. The AT&T operators were only concerned about your signal strength, not the fact that you were necessarily beside the ocean, on the ocean, or under the ocean. As long as you appeared as a registered ship station, that was fine with them.

'To help insure that customers migrate to substitute services in a smooth manner, we are introducing an INMARSAT satellite service for

AT&T radiotelephone customers with a special rate of \$2.50 per minute," comments Zuza. He is expecting that mariners will chuck their SSB equipment overboard and buy a "discount priced" \$5,000.00 INMARSAT marine mini-M terminal through Mackay Communications. I see no mention about the steep monthly service fees for INMARSAT, so for the mariner that doesn't make many phone calls, this might NOT be a viable way to

Does this shutdown of AT&T high-frequency service mean the demise of high-frequency single sideband? Absolutely not! Ham operators can run phone calls, called phone patch, through state-side ham stations. And the ham license for General class worldwide operation will be easier than ever to obtain next

fall when the code requirements drop from 13 wpm to 5 wpm. The only thing that ham radio cannot do is handle business traffic.

SSB equipment can also contact "private coast stations" that may offer phone patch capabilities to their member stations. There is a fine line here before that private coast station becomes a public coast station, so we'll have to wait and see what happens.

There is also single sideband E-Mail. E-Mail could be run on ham frequencies if the operator was a ham, and may also be run on public coast E-Mail stations if out on the water or roaming in a water region. There is also Sail Mail where a single sideband set can work through private coast stations to access E-Mail services on line. It takes an additional radio

modem to go along with the SSB, plus the computer, but nonetheless, E-Mail over high frequency is another good way to get the very last drop of signal out of your SSB radio investment. (Next month, high-frequency SSB E-Mail will be explained.)

GOOD NEWS FROM STATION WLO

AT&T is not the only FCC-licensed, public coast, single sideband radiotelephone station. Down in Mobile, AL, a company called Mobile Marine Radio offers 24-hour-a-day voice single sideband radiotelephone service, and they have a powerful antenna system that can reach out up to 10,000 miles away. They have been licensed to operate on specific ITU channels between 2 MHz to 25 MHz, and this allows 15 channels of half-duplex or full-duplex SSB communications to registered stations anywhere in the world. You could even register a dingy, using temporary FCC call signs made up of the dingy bow state registration number and the letter "K" preceding the two-letter, fournumber combination.

The call sign of the high seas radio service is WLO - Whiskey, Lima, Oscar - and their signals come in loud and clear on the following frequencies:

ITU	Receive	Transmit	
Channel	Frequency	Frequency	
2XX	2672 KHz	2430 KHz	
405	4369 KHz	4077 KHz	
414	4396 KHz	4104 KHz	
419	4411 KHz	4119 KHz	
607	6519 KHz	6218 KHz	
824	8788 KHz	8264 KHz	
829	8803 KHz	8279 KHz	



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AN/URM-120 50 OHM THRU-LINE RF WATTMETER

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plug-in coupler elements (included). CU-753 2 to 30MHz 50 to 100 watts CU-754 25 to 250MHz 10 to 500 watts CU-755 200 to 1000MHz 10 to 500 watts. Connector: Type N. Case included. Size: 7"Wx6-5/8"Hx7-1/5"D. Weight: 6.5 lbs. Price: \$395

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"And we are looking for customers," comments Rene Stiegler of WLO. "We are capable of handling the registration of those mariners who may be leaving any other turned-off service," adds

But we will miss the friendly sounds of the AT&T high seas operators. These men and women were there to handle Mayday emergency calls, rescue calls to the Coast Guard Rescue Coordination Center, and just radio checks and "I'm lonely, anyone there?" calls in the middle of the night. We are disappointed that these operators won't be heard on the airwaves anymore - they have done a fabulous job over the years past for



So don't throw out your marine SSB yet and if you're looking for an inexpensive way of making phone calls from an SSB, contact WLO and get registered with no monthly registration charge.

Remember, next month - all about highfrequency SSB E-Mail. NV



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February 1999/Nuts & Volts Magazine

Scott Edwards Electronics





3.66" by

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DEFENDER

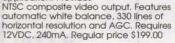
B/W CCD camera measures only 1½" x 1½" x 1". Provides NTSC composite video output. Built-in 3.6mm lens provides viewing angle of 92°. Requires 12VDC, 300mA. (#58-3330 AC adaptor). Regular price \$64.95



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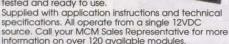


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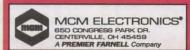


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What's inside a TV power splitter?

Ever wonder what's inside a TV power splitter? Several events made me curious about how they worked and their performance, so I opened some up and made some measurements. Power splitters have an input port S and two output ports, A and B. Ideally, the signal power going into port S splits equally between the coupled ports.

Some important criteria for power splitters are:

- Port Impedance Matching
- Port Isolation
- DC Power Distribution

TV power splitters for 75-ohm cable should look like 75 ohms at each port. Mismatched ports cause reflections and power losses, and that hurts the signal-to-noise performance. Except for weak signal environments, rents to be the same $(i_A = i_B)$. If the output currents are the same and they both flow into

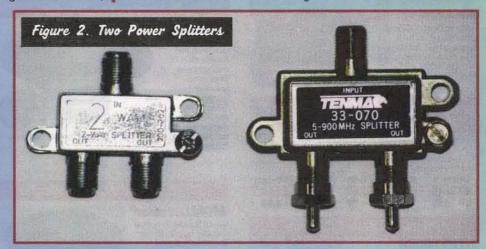
by Gerald Roylance

the same output impedance (Zo), then the output voltages (VA and VB) will be the same. Thus, the transformer enforces the basic divider operation by forcing the input current to divide equally between the two output ports.

The transformer is also a voltage divider, so the center-tap voltage is at the midpoint of the two output voltages, (VA+VB)/2. If the output port impedances are similar, then the output voltages are equal. Consequently, the center-tap voltage also equals the output voltages, and there would be zero volts across the transformer.

The operation of the balancing resistor is subtle. If the output ports are matched, then the output voltages are equal and no current flows through the balancing resistor - it's as if the balancing resistor weren't there. If the output voltages are different, then a current will flow through the resistor. The value of the balancing resistor is chosen so that all of the

Looking Inside a

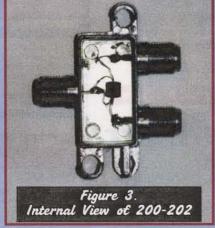


the losses won't mean much (a two-way splitter has an intrinsic 3dB loss already), but the reflections can cause ghosts.

The second criteria port isolation - helps to keep signals clean even when there are reflections. A signal going into port A of a power splitter should not appear on port B. Port isolation prevents reflections and noise on port A from causing ghosts and interference on port B and vice versa.

DC power distribution is important when a power splitter sits between an inline amplifier and its

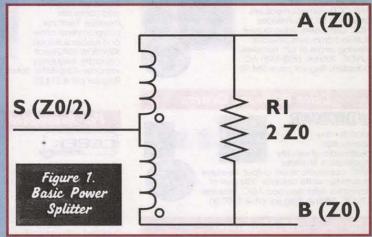
power source. In low signal strength areas, placing an amplifier at the antenna will eliminate feed line losses and improve reception. To simplify installation, these amplifiers often get their power over the coaxial cable from a power insertion module located inside the house. A power splitter that shorts DC to ground prevents power from getting to the amplifier; a splitter that blocks DC cannot be used between the amplifier and the power source. Three of the four splitters I looked at would pass DC.



Power Splitters

In his book Introduction to Radio Frequency Design, American Radio Relay League, 1994, Wes Hayward describes the basic power splitter as seen in Figure 1. The circuit - also called a zero degree hybrid - consists of a center-tapped ideal transformer and a balancing resistor. The circuit operation is clever, but its basic operation follows from a few observations.

Ignore the resistor for the moment and focus on how the transformer splits the power to the outputs. The transformer forces the two output cur-



unbalanced current flows through the resistor and none enters the transformer.

The basic power splitter has unequal port impedances: Z_S = 0.5 Z_A because the two output ports are essentially connected in parallel (when the loads are balanced, all the port voltages are the same). To make the impedances match, the splitter needs an impedance matching network. For broadband performance, that network is a 2:1 matching transformer.

The Power Splitters

Four different power splitters were tested. The first two are shown in Figure 2, and their internal parts are shown later. In addition to these two splitters, two other splitters were electrically tested.

Power Splitter Number One

The first power splitter of the group has model number 200-202 molded on its case. Black Point Products distributes the splitter as a BV-017, Two-Way Splitter, but other companies distribute the same part.

Figure 3 reveals the inside of the 200-202 power splitter - only the center-tapped transformer of the basic splitter design. This splitter design omits the matching transformer and the balancing resistor. Consequently, the match at the input port and the isolation should be poor. The design easily passes DC current among all ports because the transformer appears as a wire at DC.

Since the design does not have an impedance transformer, the input impedance will be 75 ohms divided by 2, or 37.5 ohms. The mismatch causes reflections at the input port, and the reflection coefficient is ρ = (75 - 37.5)/(75 + 37.5) = 1/3. One ninth (i.e., ρ^2) of the input signal power will be reflected and lost. The input mismatch causes a loss of 0.5 dB.

The missing balancing resistor will not affect the power split if the output ports are matched, but it will affect the isolation.

Power Splitter Number Two

The second power splitter is a Tenma model 33-070, 5-900 MHz splitter. The insides are shown in Figure 5, and its schematic is shown in Figure 6. This splitter has a matching transformer, but does not have a balancing resistor. The matching 4:3 autotransformer has a 16:9 impedance ratio, so the transformer converts the 37.5 ohms of the power splitter section to 67 ohms at the input port. The resulting p is 0.06 and the mismatch loss is 0.01 dB.

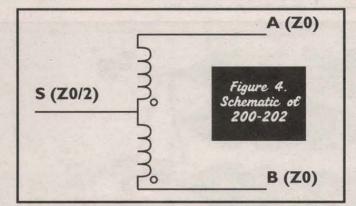
The matching transformer returns to ground through a 1nF blocking capacitor that prevents a DC short. Consequently, this splitter will pass DC power to all ports. The 2pF shunt capacitor tunes out the lead inductance to make the splitter have a broader bandwidth.

Other Power Splitters

Two other power splitters were electrically tested. Power splitter number three is a Gemini Industries, Inc., model number CV60. This model looks similar to the Tenma splitter. The fourth splitter is a Tru-Spec DSV-2, 5-450MHz, and is a splitter that my cable TV company installed.

Electrical Testing

Clearly, all power splitters are not created equal. Some are missing





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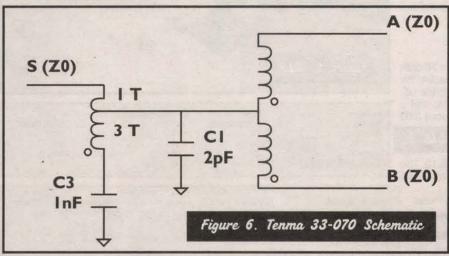
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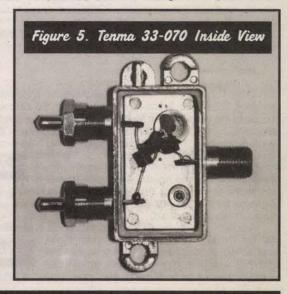
elements such as matching transformers and balancing resistors. Do these omissions affect performance a lot, or are there some subtler design tricks hidden in their design? Running some electrical tests will verify their performance.

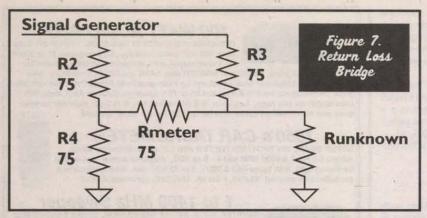
To that end, a return loss bridge (RLB) was made for reflection testing, and some isolation measurements were made.

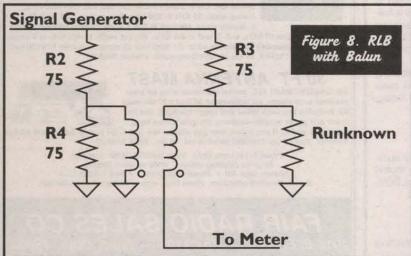
Return Loss Bridge

Reflection measurements can be made with a return loss bridge (Figure 7). The basic bridge looks like five resistors — four resistors for the bridge and one resistor (Rmeter) across the bridge that represents the









measuring instrument. One of the four bridge resistors (Runknown) is the transmission line that we are trying to measure. If the bridge is balanced, then the voltage across the bridge (between V2 and V1) will be zero and the measuring instrument will read zero. Hayward (c.f. page 151) describes how V2 - V1 is proportional to the reflection coefficient $\rho = (1 - y)/(1 + y) = (z - 1)/(z + 1)$.

Unfortunately, the voltage between VA and VB is floating, so it is difficult to measure with a grounded instrument. A balun transformer (see Figure 8) converts the balanced bridge voltage to an unbalanced signal that drives a terminated detector (I used my oscillo-

scope). The actual bridge is shown in Figure 9.

When making measurements, all ports and lines must be properly terminated. Most of my test equipment is 50 ohm, so I used some 75-ohm to 50-ohm min-loss attenuators in some crucial places, so my 50-ohm generator, cables, and scope would not compromise the measurement. The min-loss attenuator has a series 43.3-ohm resistor on the 75-ohm side and a shunt 86.6-ohm resistor on the 50-ohm side.

Reflection Testing

Table 1 shows the reflection measurements made with a 75-ohm bridge at 138.6 MHz. A two-foot length of foam RG-59 connected the bridge to the device under test. An open circuit was used as the reference ($\rho = 1.0$). A 75-ohm terminator produced $\rho = 0.18$, and a short produced $\rho = 0.89$. The terminator should have produced 0.00

and the short 1.00, so the numbers in the table Table 1 have some uncertainty. A ρ = 0.18 means about three percent of the signal power is reflected. A

terminator at the bridge (no RG-59 cable) produced $\rho = 0.10$. The numbers for the 200-202 and the Tenma are what we would expect from looking at the circuit.

A power splitter should be used with ports A and B terminat-

ed, but the table includes measurements with one or two ports unterminated. Notice that the 200-202 and the Gemini reflect almost the

Table 2

entire signal when both ports are unterminated. Curiously, the

Tenma splitter reflection coefficient is not close to one when A and B are open - apparently the splitter consumes about 1/3 of the incident signal power.

Transmission/Isolation Testing

The isolation between ports A and B is tested by injecting a signal into port A while looking at port B. Port S is terminated in 75 ohms. The 200-202 splitter should have poor isolation because its S port is mismatched (remember it is 37.5 ohms). Here is how the S port mismatch hurts isolation. The test signal from port A travels to the S port, where some of it is reflected by the 37.5- to 75-ohm mismatch. The reflected portion travels back through the power splitter, where it divides equally between the A and B ports. Good input match is required for

Although the Tenma splitter should have poor isolation because it does not have a balancing resistor, its isolation figure is reasonable. The transmission numbers agree with the reflection coefficients above: Those units with high reflection coeffi-

cients show more transmission loss (see Table 2).

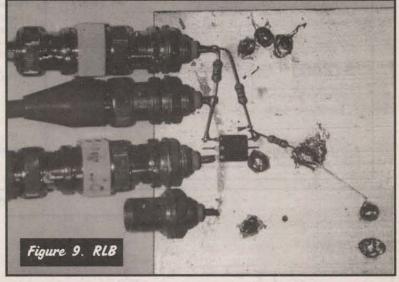
Summary

Sadly, some power splitters have mismatched ports. TV splitters do not cost much, so some manufacturers have omitted

the matching transformer and/or balancing resistor.

Although the Tenma and the Gemini splitters look almost identical on the outside, the Gemini's poor reflection coefficient suggests the inside is closer to the 200-202. Curiosity got the better of me just now, and my can opener reveals the Gemini is the same design as the 200-202. Maybe the Tru-Spec has all the right components, but it is not mine, so the can opener goes back to the kitchen.

All but the Tru-Spec splitter pass DC power among the three ports. The three Tru-Spec ports are DC shorts to ground, so the design is probably similar to the Tenma splitter without the 1nF DC blocking capacitor. Get out your ohmmeter before you apply power through a splitter. NV



Splitter Model	A&B Terminated	A Terminated, B Open	A&B Open
200-202	.34	.25	.95
Tenma	.13	.36	.80
Gemini	.32	.48	.98
Tru-Spec DSV-2	.15	.55	.90

Splitter Model	Isolation port A -> port B	Transmission — Term
200-202	.17 = 15dB	.68 = -3.4dB
Tenma	.05 = 26dB	.69 = -3.2dB
Gemini	.08 = 22dB	.65 = -3.7dB
Tru-Spec DSV-2	.03 = 30dB	.70 = -3.1dB

readel FeedBack

Dear Nuts & Volts:

I am a long-time subscriber having paid \$25.00 for a lifetime subscription when Nuts and Volts was an infant, I saw what I thought was a good opportunity to get a good subscription to a good magazine, and I have never been disappointed with your magazine.

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I have been a ham and experimenter since 1950 and you are "right down my alley."

Jim Waits Bruce, FL

Dear Nuts & Volts:

I have the following comments regarding question #11986 which was posted in your Nov. '98 issue of Nuts & Volts magazine, and its corresponding answer which was posted in your Dec. '98 issue.

I also have a RadioShack multi-meter - a Micronta 22-168 and encountered the same serial communication problems that Grant Fair had with his meter, when I wrote a Windows95/DOS application in Basic to read the meter from my Compaq Pentium laptop.

I wanted to be able to automatically sort various resistors and capacitors that I had obtained at the surplus stores by using the application to read the meter and find the closest standard value to the actual reading.

I read the response given to Grant's question by Roger Omori, in your Dec. '98 issue and tried some of his suggestions which were very helpful in getting my application running.

First, I tried the various serial protocol changes suggested by Roger, using the Procom communications package, but I could not get a reading from the

Next, I coded versions of the example in GW-Basic, Stamp BS2 BASIC, and Borland C++ and could not get any of them to work.

Finally in desperation, I found the number for the RadioShack customer support on the web and contacted them. Their response was to let me know that the Basic program listed in their manual was just an "example" and as such they

could not provide me with any information or support. This included questions I asked them regarding what kind of Basic was used for developing the example, and who the actual meter manufacturer was, so that I could contact them for information

I tried once more to code the example, this time with Quick Basic, making sure that there were no other Windows 95 applications using the COM1 serial port.

I also checked the serial device driver for COM1 using the Windows 95 control icon under the settings menu, and doublechecked all cables.

I specified the serial communications protocol using the following Quick Basic statement: OPEN

"com1:1200,n,7,2,rs,cs,ds,cd" FOR RANDOM AS #2 (see attached

listing for more details). When I turned on the meter, to my surprise, I was able at last to obtain the resistance read-

To this day, I still don't know why the application did not work. The root cause of the problem could have been due to the fact that the meter may be using hardware handshaking, because the serial cable provided for the meter has five pins instead of the customary three pins used for most serial RS-232 communications. This would certainly explain why the communications software did not work, if it was not setup to use hand-

Unfortunately, the manual does not describe the handshaking protocol used. If any of your readers have more information on this subject, I would appreciate hearing from them.

Daniel F. Ramirez Amherst, NH

Dear Nuts & Volts:

Congratulations on 20 years! Great stuff for newbies and old timers in every issue.

John Capron Newark, CA

Dear Nuts & Volts:

Mr. Roylance delivered a great article. I was gratified to read history that escaped me in 50 years of electronics!

Modern computing and standard surge suppressors... a recipe for disaster.

Almost all surge protection devices use MOV's (metal oxide varistors) as their active element. MOV's are sacrificial/wear/limited life components. Surge suppressors based on this technology are doomed to failure. These surge "suppressors" also don't suppress a thing. They divert powerline surges equally to the ground and neutral wire. When you put current on the common ground wire of interconnected equipment some of that current will flow (through the inherent ground loops) to the data lines. This is a major cause of lock-ups and misoperations that plague today's computer environments. Another fact; all modern computers use switch mode power supplies. During surges the power supply capacitors must charge to the clamping level of the MOV before the MOV turns on. A recent study has shown that it takes a 3000A surge 15 microseconds (15,000 nanoseconds) to charge the typical capacitors of these power supplies to that level. The surge is virtually over before the MOV reacts. (See five things you probably don't know about your surge suppressor at www.fivethings.com.)

THE POINT: Standard surge suppressors allow too much current to hit the computer. Standard surge suppressors divert surge current to the ground wire and disrupt data transfer. Standard surge suppressors eventually fail without warning. Modern computers have logic voltage levels (the signals that transmit the data) and power supply voltages that are dramatically lower than that of their recent predecessors. Modern computers use integrated circuits with transistors of ever decreasing physical geometries. Modern computers are virtually always interconnected to other computers or peripheral equipment. The bottom line; modern computers are much more sensitive and susceptible to powerline anomalies.

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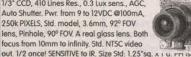
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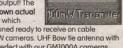
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Lightning Observing

ightning is a familiar and often feared natural phenomenon. Although lightning is seen in all areas of the country, southern Arizona and central Florida are areas of extremely high flash density (i.e., the number of cloud-to-ground strikes per square mile per year). When lightning strikes, property can be damaged, fires started, trees can be split in two (or, oddly, the bark can come off leaving the tree core intact), and, sadly, sometimes people are killed. It's not surprising that the electrical power industry is a leader in lightning research because of the damage done to their power lines by lightning.

Human casualties are common. The daughter of a former governor of Virginia was struck at the National Guard Camp at Pendleton (Virginia) beach in southeast Virginia. Florida saw 298 confirmed lightning deaths in the 30-year period 1959 to 1989. Between 1940 and 1989, there were 8,103 confirmed lightning deaths in the United States (SIRS 1990, Earth Science, Article 67). According to the National Oceanic and Atmospheric Administration (NOAA), lightning killed 88 people in 1995.

About 30 percent of the people struck each year are killed. I would have guessed that nearly all of them would have been killed, with only a few survivors. But the statistics apparently suggest otherwise. Those people who are killed usually succumb to cardiac arrest. The survivors frequently suffer serious heart problems thereafter, and most have to be treated for severe burns. One source claimed that there are cases on record where lightning did not even break the skin, but traveled the wet surface of their body to ground. The skin was said to be severely burned, after the manner of scalding.

It is estimated that the earth is struck by lightning 20 million times per year. And if you believe the old myth about "lightning never strikes the same place twice," then consider the fact that the Empire State Building in New York City takes about 12 strikes per year. Radio and television antenna towers are also

struck frequently, although I hasten to add that they do not "attract" lightning that would not have come anyway (they tend to act as lightning rods).

The lightning is generated under up to 15,000,000 volts of electrical potential. According to one source, there is normally an atmospheric potential cloud-to-ground of 200,000 to 500,000 volts, and a constant but miniscule current of 1012 amperes. The temperature inside the lightning bolt is 15,000 to 60,000 degrees Centigrade, which is several times the temperature on the sun. The lightning bolt travels at speeds up to 100,000,000 feet per second. A lightning bolt is actually a series of strokes, averaging about four. Durations vary from a few nanoseconds upward, but about 30 microseconds (30 µS) is said to be average. The average peak power per stroke is 1012 watts.

Many people struck by lightning were in unsafe situations. For example, on an open beach or in an open field such as a golf course. It is also not smart to be in a boat on the water. Standing next to a tree or other tall object (e.g., radio tower) is also rather dangerous, as the light-ning may easily be attracted to that tree. In one case, a group of golfers in Massachusetts were struck when lightning struck a nearby tree, then traveled underground to a covered pavilion where they had taken refuge from the storm. Carrying an umbrella with a metal tip above the canopy has caused lightning injuries, pre-sumably because it looks to the lightning like a lightning rod ... and you look like a ground wire!

As a general (but not absolute) rule, as long as you can hear thunder, the danger of strike is small. Lightning travels at the speed of light (3 x 108 meters/second), while sound travels at 331.3 meters per second at 0°C (sound velocity changes a bit with air temperature), or 1,087 feet per second. As a result, the flash of light arrives instantaneously, while the sound of thunder arrives a short time later (measured in seconds).

A "rule of thumb" is to count the

seconds between the flash and thunder clap, and then divide by five, to find the number of miles to the lightning bolt. One reason why doubt validity of the "can hear thunder" advice is that I've been under thunderstorms where the lightning flash and thunder were very

nearly simultaneous, indicating it was right overhead.

More precise measurements of distance can be done using a good stopwatch to measure the time of arrival of the thunderclap. From that data, you can calculate the distance from D = VT, where D is the distance and V is the velocity (if you use m/s for T, then D is in meters, but if ft/s is used, T is in feet). You can further refine your measurements by consulting a table of sound velocity related to temperature and atmospheric pressures.

Some Lightning Detection History

Before we talk about early lightning research, let me hasten to add a caution: DON'T EVEN THINK ABOUT DOING THESE EXPERI-MENTS YOURSELF! People who've tried to duplicate these experiments have been killed in the attempt.

Electrical phenomenon was researched starting in the early eighteenth century. It was noticed that certain substances, when rubbed, produced static electricity arcs. It was also found that a type of capacitor called a Leyden Jar could store an electrical charge. It was believed — correctly, of course — that these sparks looked enough like lightning to suggest a connection.

In May 1752, Thomas Francois D'Alibard in France performed an experiment that Benjamin Franklin had failed at the year before. The experimenter stood on an electrical stand, holding an iron rod in one hand. The idea was to produce an electrical arc between that rod and another rod in the other hand connected to a grounded iron wire. In an attempt to repeat the experiment in July 1753, Swedish physicist G.W. Richmann, working in Russia, was killed by the lightning.

Benjamin Franklin conducted his famous kite experiment in 1752. He used a rain-damped kite string connected to a key at the bottom. The lightning traveled down the string, and jumped from the key to a dry silk ribbon tied to Franklin's knuckles, and then through his grounded body. Others who attempted this experiment were killed. It's interesting to wonder what the American republic would look like if Franklin, having been killed in 1752, was not alive to provide wisdom to the Constitutional Convention (his compromise suggestion, which reconciled the "large states vs. small states" controversy, is supposedly how we got the bicameral Congress).

When photography and spectroscopy were invented in the nineteenth century, additional facts were learned about lightning. Timeresolved photography was used to count the number of strokes per lightning strike. Current measurements were made by Pockels in Germany during 1897-1900. He analyzed the magnetic fields induced by the lightning currents to estimate the current level from basic electrical fundamentals. C.T.R. Wilson (ca. 1920s), who also invented the cloud chamber, used electric field measurements to study lightning. Wilson hypothesized that the electrical fields cause such great ionization, that it's



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Most Common Activities Leading to Lightning Strikes on Humans

(derived from NASA web site http://www.thunder.msfc.nasa.gov/primer.html)

- 1. Working, playing, or walking in open fields.
- 2. Boating, fishing, swimming.
- 3. Working on heavy farm or road construction equipment.
 - 4. Playing golf (!!!)
 - 5. Talking on the telephone.
 - 6. Using electrical appliances.



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possible for discharges to occur between the clouds and the upper atmosphere. Seeming confirmation of the 1925 theory was provided on April 28, 1990 when Shuttle mission STS-32 videotaped a single luminous discharge in the stratosphere.

Modern lightning research still measures electrical and magnetic fields, but adds other techniques to their armamentarium. Cameras with electrically-triggered shutters can be used with photosensors to make photographs of lightning strikes. High-speed movie cameras are also used, although the invention of charge coupled device (CCD) sensors (which are used in video cameras) has allowed a number of new instruments to emerge.

Other researchers rely radiowaves, especially the whistlers, spherics, and broadband RF noise generated in the ELF/VLF/LF portions of the radio spectrum. This type of research is also easily conducted by amateur scientists.

At a site in Florida, researchers fire three-foot high solid fuel rockets into thunderclouds. The rocket trails a grounded wire that conducts the stroke to earth (AMATEUR ROCKE-TEERS: DON'T DO THIS!). The Space Shuttle and satellites are also being used for lightning research. Some hauntingly beautiful video clips of space shuttle lightning are available from NASA web sites. High altitude aircraft lightning research revealed newly discovered phenomenon called sprites and jets.

Types of Lightning

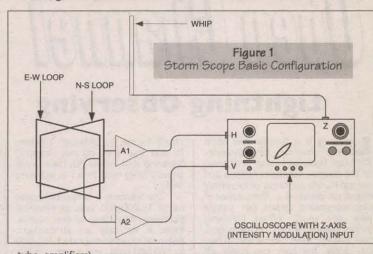
Cloud-to-ground lightning passes from a cloud overhead to the earth beneath. Most cloud-to-ground strikes occur in the higher latitudes, although recent research indicates a more important variable is cloud top height. Cloud-to-ground ligthning is what causes injury and damages. Cloud-to-cloud or "inter-cloud" lightning passes from one cloud to another. Intra-cloud lightning appears with-in a single cloud. The "jagged" light-ning that we see so often is called chain lightning, while sheet lightning is a generalized bright flash.

Other types of lightning may or may not be little more than myths, poor observations (e.g., optical illusions), variations on other types, or real, depending on who you consult. These include ball lightning, tubular lightning, bead lightning, silent lightning, cloud-to-air lightning (as opposed to cloud-to-cloud), and heat lightning.

Storm Scope

Lightning research can be terribly dangerous, especially if it puts you out in the open or if you are foolish enough to mimic professional methods such as ground wire tethered rockets. There are, however, some instruments that are easily built and relatively safe to use. The storm

scope is one such instrument. Figure 1 shows the basic configuration. This project was originally published by Thomas P. Leary in the June 1964 QST magazine (although his implementation used vacuum



tube amplifiers). The storm scope consists of a pair of orthogonal small loop antennas; one oriented North-South (N-S loop) and the other East-West (E-W loop). Keep in mind that a small loop antenna (e.g., 0.18λ wire length) shows a figure-8 pattern with nulls broadside to the loop plane, and maxi-ma off the ends. Align the ends the loop (maximum sensitivity direction) in E-W and N-S directions. compass will make the accuracy better.

The loops are fed through differential amplifiers, with gains in the 20 to 80 dB range, to the vertical and horizontal plates of the oscilloscope. The reason for the wide gain scale is that oscilloscopes vary. The original project connected the amplifier outputs directly to the oscilloscope deflection plates. Modern two-channel oscilloscopes can be used in the X-Y to form a vectorscope, of which the storm scope is a variation on the

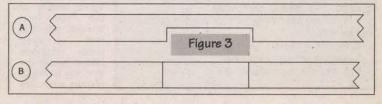
Although any two-channel scope with an X-Y mode is usable, a directional ambiguity exists unless the 'scope also has a Z-axis (a.k.a., intensity modulation) input. This input is often present, but hidden on the rear panel of the 'scope. The Zaxis is used to intensity-modulate the screen with a signal from a sense whip or vertical antenna near the two-X loop. It may be necessary to amplify the Z-axis input signal, but in that case a single-ended rather than

3-FT 50-TURN (OR MORE) LOOP Figure 2 Loop & amplifier Configuration

differential amplifier is used.

Figure 2 shows the loop and amplifier configuration. The loop consists of at least 50 turns (50-t.) of small gauge insulated wire in a three-foot (3-ft.) loop. Either square or circular loops can be used, although it appears to me that the square is more easily constructed. The loop is untuned. The output of the loop is applied to the input terminals of the

differential or push-pull amplifier. It is critical to shield the loops. Wrap either copper foil or aluminum foil (or tape) over the entire loop, except for a small quarter inch or so gap along the top edge (this prevents the shield from acting like a single-turn shorted loop itself). The shielded loop will be less prone to pattern distortions from capacitive coupling. In addition, it responds largely to the magnetic component of the light-ning electromagnetic field. It is less sensitive to electrical fields, so will not pick up as much locally-generated



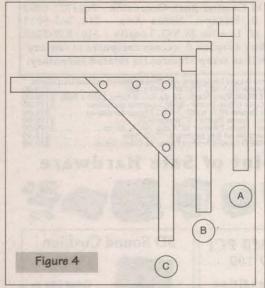


Figure 5
Wiring of the loop

power line and appliance noise.

I constructed a loop pair using 0.75" x 4" x 36" lumber. Although my own woodworking skills leave something to be desired (polite for "atrocious"), others are able to make a better job of the method shown in Figure 3. A notch (Figure 3A) is cut at the center of the top and bottom members of each loop. The depth of the notch is the thickness of the lumber, while the width is sufficient to snug-fit the other piece of wood in it (Figure 3B).

The square loop will tend to

"trapazoid" out of shape

if left to its own devices. As a result, some or all of the methods of Figure 4 are used at the four corners of each loop. In Figure 4A, the wood elements are butted together, glued, and nailed (or screw fastened). A small block, about 0.5 inch square and as wide as the loop arm, is glued in the corner to give strength. In Figure 4B, the same method is used, but the joint between the wood members is a bit different. I am told this method is stronger, even though

it is more difficult. Finally, a triangular gusset plate cut from a thin sheet of plywood or spruce modeling lumber is shown in Figure 4C.

Figure 5 shows the wiring of the loop. I used 50 conductor ribbon cable, although one continuous loop of #26 (or so) enameled wire could be used as well (it takes more than 600 feet of wire per loop for this approach!). You can also use 60 or 64 conductor cable. The sensitivity of the loop is improved with more turns

or a larger length per side. You can, for example, build a four-foot or five-foot loop, or use multiple runs of 50 conductor ribbon cable. In one case, a whistler/spheric hunter used 126 conductors made from intercom cable.

If you opt for the simpler ribbon cable method, then cross connect adjacent turns so that one continuous loop is formed. This is a tedious chore, but it's made a lot easier if you use printed circuit perf-board (or some of the project boards from RadioShack) to make the connections. It is okay to lay the N-S and E-W loops over one another because their orthogonal geometry makes them minimally interactive.

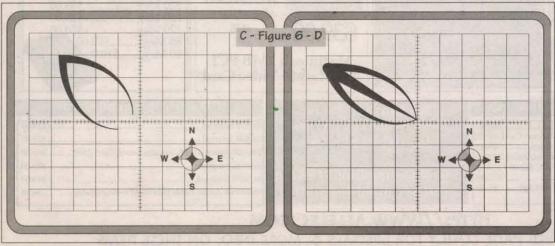
Results to Expect

The original article claimed detection to distances of 500 miles, but I doubt that figure is practical. I would more likely guess tens of miles, or 100 miles, but further experimentation is needed to confirm the longer distance claim. Figure 6 shows typical patterns. These patterns are representations of what is observed, but are a bit more distinct and less ragged than actual 'scope photos (I am no longer able to pho-tograph 'scope screens ... until I find a new hand-held Polaroid 'scope camera). I was able to create the patterns in Figures 6A and 6B, but those of Figures 6C and 6D are cribbed from the Leary article cited

The pattern in Figure 6A is what to expect when there is no Z-axis input to receive the vertical sense antenna signal. It shows the line of the storm, but has the directional ambiguity found on loop antennas. In other words, the storm could be in either direction from the loop. Figure 6B shows the pattern to expect when the sense antenna is used, and the Z-axis intensity is correctly adjusted. This is essentially the same concept as a sense antenna producing a cardioid pattern on a radio direction finding (RDF) antenna. The actual pattern will be a lot more ragged than shown here.

Leary claims that patterns like Figure 6C are produced with horizontally polarized cloud-to-cloud discharges (the others were essentially groundwave signals). The pattern in Figure 6D represents what might be seen when a groundwave and cloud-to-cloud pattern co-exist. I was not able to confirm these patterns, but that might be the particular thunderstorm I observed several years ago when I was active in building loops while researching a forthcoming book (Joe Carr's Loop Antenna Handbook, Universal Radio Research, Reynoldsburg, OH). NV

A - Figure 6 - B N N S S S



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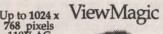
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Help! I'm Lost!

Being lost is frustrating. It happens to most of us; lost in the country, driving for miles through endless grids of farmland, or lost in an unfamiliar big city, wandering through

address. Figure 2 illustrates the basic software components and their interaction in a typical system.

Vehicle Positioning

Data comes in from various

correlation to a set of map coordi-

There are several common vehicle speed and direction sensors used for position calculation. The most common of these are gyroscopes, wheel speed sensors, odometer

This article explains the inner workings of automotive navigation systems.

varies fairly dramatically with temperature. This drift translates directly into positioning error produced by the vehicle positioning module, since the gyro is used primarily to determine vehicle direction. The gyro output, to be accurate, needs to be frequently calibrated. GPS data is used for correcting the accumulated dead reckoning error.

Just knowing when and how fast a vehicle is turning isn't enough to determine position. The vehicle positioning module needs to know the distance traveled over a period of time. That's where wheel pulse sensors and odometer pulses come in. Wheel pulses come from one or two wheels, and are usually the output of Hall-Effect switches. The incoming pulse rate is proportional to wheel speed, which is proportional to vehicle speed.

Wheel pulses can even be used

Automotive Navigation

deserted, and possibly dangerous, city blocks. All the time being low on gas. Being lost may soon become an unpleasant memory with the emerging availability of automotive navigation systems.

Automotive navigation systems require sophisticated hardware and software and are somewhat expensive, but I believe they'll be as common as air conditioning in the vehicles of the near future. This article examines and explains the major software components of a typical automotive navigation system.

Navigation System Components

There are six major components in a automotive navigation system. These components include a vehicle positioning module, a map matching module, a digital map database, a dynamic route guidance module, a static route planning module, and a user interface. These components are listed in more detail in Figure 1.

Automotive navigation systems do a lot of work when they're running. Global Positioning System (GPS) receivers intercept and condition GPS satellite signals, A/D converters digitize analog signals from gyroscopes or accelerometers, and buffers hold direct digital speed pulse data. On-board digital map databases and route guidance software prompt the driver to stay on course, and route planning engines calculate a route from a vehicle's starting position to a destination

by Jeff Stefan

vehicle motion sensors to a Vehicle Positioning module. Within the Vehicle Positioning module, software reads the conditioned signals. keeps track of time, and performs a form a navigation called dead reckoning. The output of the Vehicle Positioning module is the current position of the vehicle, along with the rate of speed and heading. In the simplest case, dead reckoning can be accomplished with a watch, a compass, and a known speed. Time, speed, and direction are recorded at periodic intervals. With a known speed, direction, and starting point, it's easy to determine the distance traveled and make a crude

Where It's At and Where It's Going

pulse indicators, and GPS receivers. Gyroscopes, or turn rate sensors, are classed as inertial sensors, as are accelerometers. A quartz resonance gyro outputs a tiny voltage proportional to its input axis rotation. If a vehicle is making a sharp, fast turn, then the output is higher than when the vehicle is making a slow, widely arcing turn. Gyroscopes are great for dead reckoning, but have a few

The major problem with inexpensive quartz resonance gyros is temperature sensitivity. The output

to detect turns. If the vehicle is making a left turn, then a right wheel travels a greater distance than a left wheel. Wheel pulses vary with tire pressure and slippage which, in turn, create positioning errors. Odometer pulses generally come from an existing in-vehicle computer. There are typically a fixed number of pulses per mile or kilometer. so the distance traveled is simply a matter of counting pulses. Error is still accumulated with slippage, but not as severely as with wheel puls-

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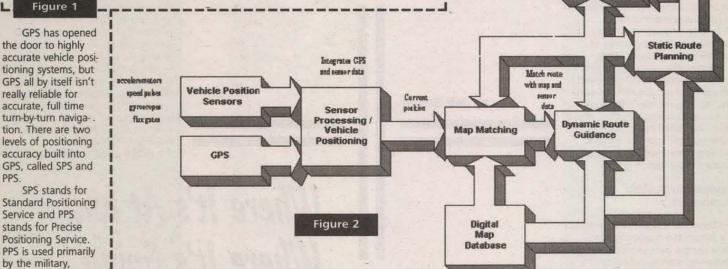
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Navigation System Components Vehicle Dynamic Route Determines current Monitors current route Positioning Guidance vehicle position being traversed Static Route Matches vehicle Calculates route from current **Map Matching** position to digital map Planning position to destination address database coordinates **Digital Map** Displays maps, turn icons, Contains map data User Interface Database and accepts commands for coverage area from driver

around the buildings then enter the receiver, giving erroneous position readings. This is called multipath error. As it stands now, for robust and consistent navigation, GPS is

the map matching module. Map matching consists of matching the position received by the positioning module to a road segment position from a digitized map database. The digitized map database contains road segment information, such as the latitude and longitude, the type of road, the shape of the road segment, and speed and direction

User Interface



Service and PPS stands for Precise Positioning Service. PPS is used primarily by the military, where SPS is used for civilian applica-

tions. Originally, SPS turned out to be very close to the positional accuracy of PPS, so to widen the performance gap, SA, or Selective Availability, was introduced. SA intentionally degrades the GPS positioning accuracy to 100 meters horizontally and 160 meters vertically.

This means that in a vehicle, there is an inherent 300 foot error in any GPS positional reading, and that makes map matching a lot tougher.

GPS signals are also often blocked by trees and foliage. In a city with tall buildings, GPS may be blocked, or the signals may bounce used as a calibration source for dead reckoning and is not the central source of vehicle position information.

Map Matching

The next major component is

attributes. An automotive navigation system is essentially worthless without a good digital map database.

Map matching itself is a form of positioning. If the positioning module reports a position that is reasonably close to a road segment, then the position is corrected to the



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digital map position, and not to the position reported by the positioning module.

There are four "truths" regarding position, and only one of them is really true. The vehicle speed and direction sensors report one positional truth, GPS reports another, and the map matching module reports yet another. All of them are inaccurate to a certain degree with respect to where the vehicle is at any given moment, which is the real positional truth.

Route Guidance

The next module is Route Guidance. Route Guidance monitors the vehicle and map matched position and determines if the vehicle is correctly traversing a pre-planned route. It does this by checking whether the current road segment being traversed matches the current segment in the pre-calculated route. Figure 3 illustrates the output of a typical automotive navigation system map display. The triangle icon indicates the

The actual reported position may not be exactly on the current road segment of Normandy Road, but it is close enough to snap the vehicle icon onto the road display. It's annoying to a driver to see the icon travel along a route next to the road, but not on the road. Many navigation systems allow the driver to manually adjust the icon.

The Route Guidance module's main responsibility is to present upcoming maneuver data to the User Interface. The next maneuver such as a right turn or left turn - is presented to the User Interface at a threshold distance from the maneuver. If the maneuver is missed, then at another threshold distance, an error is announced. The driver then

has the option of canceling the route, or calculating a new route from the vehicle's current position.

Route Planning

The Route Planning module is



responsible for generating a list of road segments to traverse from the vehicle's current position to a destination. The driver enters a destination address using optional criteria, such as least use of freeways, shortest distance, or shortest time, among others. The Route Planning software links together the road segments into a list based on the driver's preferences and makes this list available to the Route Guidance module.

Route planning, which is essentially a search problem, has its roots in classical computer science and artificial intelligence. Roads and intersections can easily be modeled as graphs, which are commonly used in computer science.

Graph theory is used to illustrate and solve many computer science related problems, from network development to operating system deadlock detection. A typical graph

is shown in Figure 4. The nodes, or circles, are called vertices, and the lines that connect them are called edges. The words node and vertice are used interchangeably.

A method called Dijkstra's Algorithm systematically determines the least-cost path in any graph, given a source and destination node. It can reliably calculate the least-cost path from any node to any other node. It's not a giant leap to translate vertices to intersections and edges to roads.

Note that in Figure 4, the leastcost path from vertice A to vertice E is through the path A to B to D to E, and not from A to C to E. Geometry has nothing to do with it; everything is dependent on the cost value, or weight, assigned to the edges. In a

if the search could be sped up if additional information was known ahead of time? This is called a heuristic search, and falls within the domain of artificial intelligence. A heuristic - or rule-of-thumb - helps in making a decision. A simple example of a heuristic is deciding which checkout line to go to in a store. A short line at a checkout usually equates to getting through the line faster. This isn't necessarily true if someone in a short line has a lot of items to buy but, in general, a shorter line means a faster exit

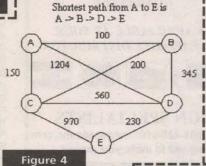
Heuristics are used with the best-first search algorithm. Best first searches revolve around searching nodes that are estimated to be close to the destination node. In the case of the checkout line, using the heuristic that a shorter line means a faster exit, we would scan all of the lines to determine which line was shorter.

We're looking for the shortest, least-cost distance to our goal, which is getting out of the store in the minimal amount of time. There's no guarantee that the decision will be correct, but it will be correct most of the time.

The heuristic applied to route planning estimates the distance

from a source node to a destination node. What best-first search really does is restrict the search space. Where Dijkstra's Algorithm is able to search a complete network, best-first search restricts the search to a single source and destina-

Figure 5 tion. This translates into less processing time and returning a route to the driver much faster.



Dest

in

1.2 mi

Turn Right onto

Woodward Ave

road network, the cost value can be based on speed limit, type of road, or some other criteria that would affect traveling down the road.

Dijkstra's Algorithm blindly

and systematically searches for the least-cost path from any source node to any destination node. What



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7411	.55	.52	.47	
7414	.27	.26	.23	
7420	.24	.23	.21	
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User Interface

Finally, the User Interface accepts commands and presents the navigation data to driver. Maps are displayed with a vehicle icon, as shown in Figure 3, and turn-by-turn maneuver icons are usually shown when traversing a pre-planned route. A right turn icon is shown in Figure 5. As the vehicle approaches an intersection, a maneuver icon pops up on the display, informing the driver that a maneuver needs to be executed. More than simply right or left turns, the navigation computer may inform the driver to bear right. bear left, stay straight, or execute a series of maneuvers.

Another vital feature of the User Interface is speech output. Driving is inherently hazardous, especially when a driver is continually looking at the navigation system and not at the road ahead. Speech output helps to minimize this potentially dangerous and litigious situation. In the simplest case, canned phrases are enunciated. Canned phrases do not recognize road names. To announce the maneuver in Figure 5, canned phrase software will say something like "right turn ahead." More sophisticated text-tospeech software will actually announce the road name. A text-tospeech module will actually say "turn right onto Woodward Avenue.'

There are some inherent difficulties with text-to-speech. One major problem is storing the road name in the form that a text-to-speech module understands. It generally can't be simply the English spelling of the road name. Chances are the road name will be mispronounced. The road name needs to stored as a phoneme.

A phoneme is not so much the way a name is spelled, but how it sounds. This adds more data to an already dense database. Pronunciation is also difficult, since road names are predominately proper nouns. Canned phrases simply involve comparing a key word, such as "right" or "left," and indexing into a ROM location to extract the phrase.

Driver input needs to be minimized so the driver isn't too distracted from keeping his or her eyes on the road. Speech recognition is ideal, but very expensive. Touch screens are good, as are a simple and intuitive button layout.

The Future of Intelligent **Transportation Systems**

What happens when an accident occurs somewhere on the route you're traveling? Even if you know about the accident, how do

you re-route around it? This is where real-time traffic information and server based navigation comes into play. Similar to an Internet service provider, a vehicle information service provider can monitor traffic and provide real-time traffic updates to the subscribers. If an accident occurs on your route, the service provider can alert your vehicle and download a new route, avoiding the obstacle or accident. Vehicles can even be used as traffic probes. A service provider can call your vehicle, determine its position, and compare the vehicle's speed to the speed on the road segment it's currently on.

If the road segment speed is supposed to be 65 mph, and the vehicle is only going 5 mph, then there is a possibility of traffic incident or construction. If many vehicles on the same road segment are stopped or moving slowly, then the probability of an incident is extremely high, and real-time traffic notifications can be broadcast to other vehicles. If your vehicle is involved in a traffic incident or simply breaks down, then the information service provider can provide emergency and breakdown services, ranging from calling an ambulance or tow truck. These features and services fall under the umbrella of Intelligent Transportation Systems, or ITS.

Think of the early days of aviation. You would pull an old plane out of the hanger, gas it up, check the wind direction, and look up to see if any other air traffic was around. If the sky was clear, you'd take off. No flight plan, very few instruments, and a compass and a map in your lap. There's a certain glamour and appeal to the unrestrained freedom that early aviation offered. That's the way driving is today, without a supporting information infrastructure, and essentially autonomous and unrestrained.

Traffic information systems of the future will offer important driver information, but at a cost. With the increased security and convenience comes a loss of autonomy. Opening a vehicle to allow two-way communications with the outside world opens the door to malevolent hacking. If an information service provider can remotely unlock your car doors, so can a hacker. Hacker proofing a vehicle requires data encryption technology which increases cost and complexity, and there are always back doors to everything.

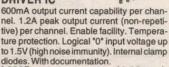
The road to the future via ITS is bright, but there are a few technological potholes along the way. Being aware of the problems and benefits - both potential and real can help designers and drivers develop and use reliable, practical, and safe intelligent transportation systems. NV



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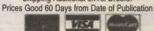
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ELECTRONICS

Q&A

• • • • • • With TJ Byers

In this column, I answer questions about all aspects of electronics, including computer hardware and software. This column doesn't replace the Tech Forum that you've grown to love and support. Instead, it will supplement it, so feel free to participate as always with your questions and answers. You can reach me on America Online at TJBYERS, on the Internet at TJBYERS@aol.com, or by snail mail at Nuts & Volts Magazine, 430 Princeland Ct., Corona, CA 91719.

What's Up: Two different 12V DC-to-DC voltage converters, two new alarm circuits, and two battery monitor/testers. A reliable fixed-frequency, variable duty cycle pulse generator. And many more web sites to visit, including an interesting look at GeoWorks. Finally, our readers talk back about hard disk fixes and noisy A/D converters. Enjoy!

More Solar Stuff

Q. In your Dec. '98 column, you showed how to trickle-charge a battery from a solar panel using nothing but a diode. What size diode should I use for my solar panel which has a 1-amp output?

Carl Zajac via Internet

A. Let me reiterate my Dec. '98 answer first: If the charging current is less than 1/10 the capacity of the battery under charge, a charge controller isn't needed. Translated, that means that your 1A solar panel can trickle-charge any battery of 10 AH (amp-hours) or bigger using a simple diode to prevent discharge when the sun doesn't shine. How big is the diode? If you have a 1-amp solar panel, a 1-amp diode like a 1N4001 works. If you have a 3-amp solar array, then the answer is a 1N5400. Both are available from RadioShack for under a buck.

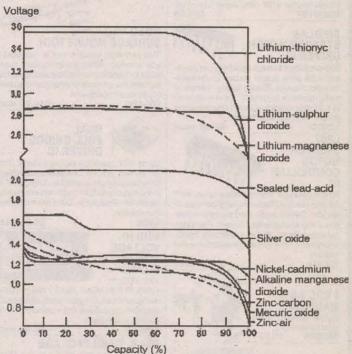
Battery Testing

Q. I'd like to use a voltmeter to check the condition of my 'AA' batteries, but I feel the need to put a load on them while testing. Can I just put a resistor across the battery when I test it? If so, what value of resistor should be used? Also, if I want to discharge NiCd batteries before recharging them, can I put a resistor across them to discharge them completely? What value should I use?

Thomas Wallenmaier Southfield, MI

A. You're quite right. Measuring the open-circuit voltage (OCV) of a battery to determine the amount of service life will yield but a rough estimate. A more accurate method is to measure the closed-circuit voltage (CCV) of the battery. This is accomplished by putting the battery

under load for one to two seconds, then measuring the CCV. The load is determined by the size and type of battery. In the case of a 'AA' cell, the load should be approximately 8 ohms. A 'D' cell needs a 4-ohm load, and a 9-volt battery is best tested with a 50-ohm load. For an alkaline or carbon-zinc single cell, the cutoff point is 0.9 volts. For example, if the battery voltage is 1.1 volts, the battery has approximately 20% of life left. Different batteries have different discharge profiles, as shown below.



Battery Size	Lamp	
AAA	222	
AA	PR5	
C	PR5	
D	PR2	
6V lantern	1888	
9V	1892	

Personally, I prefer to use a flashlight bulb for the load when I test my batteries. In addition to getting a voltage reading of remaining capacity, you get a visual look-see that strikes closer to home. Here's a list of the bulbs that I-use for the various batteries — and to drain a NiCd battery for recharging.

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Cracking The BIOS Code

Q. I recently acquired a working Gateway 2000 with a 486 motherboard. The trouble is that it didn't come with a manual, and I'm not able to access the BIOS settings with key press(es) on Power-Up. I've tried pressing the keys that usually work, like , F2, and <Esc>/<Enter>, with no luck. The only way I've been able to access the BIOS settings is to unplug the hard drive and then power-up. I would really rather do it via the keyboard. Do you know the secret code?

John McMichael via Internet

A. It's no secret. The combination is pressing <F1> (sometimes repeatedly) when you see the first boot screen. You may have to turn on the monitor before you boot to make sure you don't miss your window of opportunity. Need a manual? No problem! Download it from Gateway's Web site at http://www.gateway2000.com/support/tec hdocs/manuals/index.html

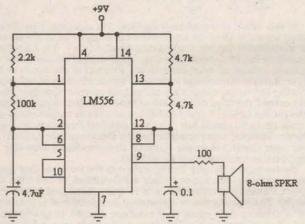
By the way (BTW), this is a message to any reader who is having a problem accessing the PC's BIOS. The answer is to unplug the (bootable) hard disk's power plug and take it from there. Been there done that often; it brings up the BIOS screen virtually every time.

Beep Me

Q. I'm working on a project for a restaurant that requires an audio alarm that will have a sound similar to that of a beeper (or the chimes of a doorajar auto alarm). I don't want to use the high-pitched piezo buzzers avail-able everywhere, because they would be very annoying to both employees and customers, but my efforts to find a beeper sound module or even surplus damaged beepers that I can use for this project have hit a stone wall. There are transducers available that would probably work, but I have no idea how to build a suitable driver circuit. Please help!

Thomas via Internet

A. For a beeper sound, I'd use this circuit.



It uses a 556 chip, which houses two 555 timers. The second 555 timer (right side of the chip) is a 1-KHz, squarewave oscillator. This oscillator is controlled by the first 555 timer, which is basically an astable pulse generator that connects to the reset pin (pin 10) of the 1-KHz oscillator. When this pin goes high, the speaker sounds for a

short time every couple of seconds. The frequency of the tone can be adjusted by the size of the 0.1uF capacitor: a higher value lowers the tone, and a smaller value raises it. Likewise, the 2.2K resistor and 5uF capacitor can be changed to generate different on/off times for the beeper. The volume is controlled by the 100-ohm resistor; to increase the volume reduce the resistance to 47 ohms, to make it softer, use a 220 ohm resistor. 330-ohm resistor. A piezo transducer will work in place of the speaker. For a chime sound, this circuit is cheap and easy to build.

UIC ITIA IIIB R2 100 4049 C1 0.01 R1 68k 8-ohm SPKR UID UlE 1N4001 10% 2N2222A 1N4001 10oF luF 47k

As in the beeper circuit above, it takes two oscillators to produce the sound. U1A and U1B generate the basic tone, while resistor R1 and capacitor C1 determine the frequency of this squarewave oscillator. U1C is a buffer/amplifier that drives the speaker (or piezo device). The volume is determined by R2 – with a lot of help from U1D and U1E. When power is applied, this duo oscillates and slowly charges the 10uF capacitor on the base of the 2N2222A transistor. As the voltage across the capacitor increases, the volume decreases, producing the chime tone. Unlike the beeper circuit above, which produces a continuous beeping after power is applied, this a one-time event. To make repeated chimes, you need to interrupt the power source with a momentary-ON push-button switch.

If this sounds too ambitious, check the ads in our pages under "Kits." Gateway Electronics (1-800-669-6810; http://www.gatewayelex.com), for example, sells all kinds of sound boards ranging in price from \$7.95 to \$29.95.

DC to DC Conversion ...

Q. While most people wish to convert 12-volts DC to 115-volts AC, I would like to raise a 12-volt car battery to the following higher DC voltages.

1 - 13 volts, 2.5 amps

2 – 19 volts, 2 amps 3 – 24 volts, 1 amp

I need to select any one of the voltages with a switch. Can this be done with a simple conversion circuit?

Fred Batin via Internet

A. What you ask for is easily done using an LM2577 step-up voltage

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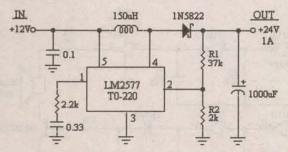
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regulator, which you can buy from Digi-Key (1-800-344-4539; http://www.digikey.com) or QuestLink (http://www.questlink.com) for under \$10.00. (I recommend the LM2577T-ADJ version in a TO-220 package for ease of use.) This regulator is unique in that it has an input voltage range of 3.5 volts to 40 volts, an adjustable voltage output of up to 60 volts at up to 3 amps (at the lower voltages), current limiting, thermal shutdown (in case it gets too hot), and requires only eight external components. Here's the 24-volt version of the DC-to-DC converter you asked for.



The circuit operates in what's called the "boost" mode, where a magnetic field is built up in an inductor, then allowed to collapse. As the field collapses, it generates a high voltage spike, or kick. This is exactly how the ignition system in your car turns 12 volts into 50KV to fire the spark plugs. On a smaller scale, the LM2577 regulates the boosted voltage between 5 volts and 60 volts. The regulated voltage is determined by the ratio between R1 and R2. Resistors R1 and R2 divide down the output voltage so that it can be compared to the internal 1.23-volt reference. For a given output voltage select the ratio

$$\frac{R1}{R2} = \frac{Vout}{1.23V} - 1$$

That is, the voltage drop across R2 at the desired output voltage must equal 1.23 volts. Here's how the values of R1 and R2 for a 24-volt output were calculated. Set R2 at 2.0K, then calculate the current needed to produce a 1.23-volt drop.

$$I = \frac{E}{R2} = \frac{1.23}{2000} = 0.615 \text{ mA}$$

Next, calculate the total resistance needed to generate a 0.6-mA current across a 24-volt source.

$$R = \frac{E}{I} = \frac{24}{.000615} = 39K$$

Finally, subtract for R2 to get the value of R1.

$$R1 = R - R2 = 37K$$

You can follow the same procedure for the 19-volt source, or 15 volts, and whatever. The important thing is that R2 has to generate 1.23 volts across it to output the desired voltage. You may have to juggle the values of R1 and R2 to achieve a ratio that equals a standard resistor value, but don't knock yourself out. A 37.4K resistor is plenty close enough for this example. Finally, the input voltage (Vin) can't exceed the boosted output voltage (Vout) - this is a step-up regulator remember? It can't reduce 12 volts to 5 volts, which is why you should get the 13-volt source directly from the 12-volt battery. With a full charge a car battery will measure 12.6 volts; when



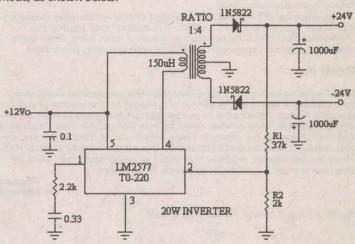
charging, the voltage is 13.1 volts. A simple rotary switch will let you select between the sources. For detailed information on designing DC/DC converters with the LM2577, download its data sheet from the National Semiconductor Web site at http://www.national.com/pf/LM/LM2577.html.

... DC to DC Conversion, Again

Q. I'd like to use an LM1875 20W IC power amp in an auto audio amplifier. How can I make a bipolar +24VDC/-24VDC power supply from the car's 12-volt power source?

William Silvis via Internet

A. Like the query above, you, too, can use an LM2577 step-up voltage regulator. For this application we'll use the LM2577 in the flyback mode, as shown below.



In this mode, a transformer replaces the inductor. This time, the energy stored in the primary inductor is transferred to the secondary of a transformer, where - unlike the boost mode - it is transformed to a higher or lower voltage. The amount of energy transfer, that is the resultant voltage at what current, is a product of the two - or total power. Raising the voltage lowers the available current, whereas reducing the voltage increases the output current. Together, the two van't exceed the total dissipation of the IC's output stage — about 30 watts for the LM2577. (An LM2587, a pin-for-pin replacement, can operate up to 60 watts, but runs at a different frequency and uses different inductor and capacitor values. Download the LM2587 data sheet from QuestLink or the National Semiconductor web site (http://www.national.com) for details)

Basically, the flyback configuration is the same as that used in your monitor to increase or reduce a DC voltage. In this case, the flyback transformer takes the car's 12-volt source and increases it to +24VDC. The transformer is a standard center-tapped secondary type with a winding ratio equal to the voltage desired. In your case, you need 48 volts total (24V + 24V) from a 12-volt source, a 1:4 ratio.

Should you want to change the voltage to ±5 volts, the ratio would be



1:0.8 (10V/12V; quiz later).

As before, resistors R1 and R2 set the output voltage. The output voltage for the bipolar output is derived from the positive leg of the output, which means the outputs aren't tracking. In other words, only the positive output is regulated. If there is a heavier, or lighter, load on the negative supply, its voltage may go above or below the positive. In your case, where you're using a symmetrical Class-B op amp, I wouldn't worry about it. However, if you plan to add single-supply devices, like indicator lamps or a preamp, make sure you hang them on the positive side - the regulated line - to keep the LM1875 in balance. Better yet, use the +12-volt source if you can. (BTW, are you aware that you can operate the LM1875 from a single-polarity (+32V to +60V) power supply)?

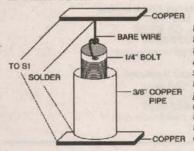
Don't Tread On Me Alarm

Q. I have a theft problem that I think could be solved with an inexpensive motion-activated alarm, somewhat like the alarms that go off when you bump into a car. Do you have any advice on appropriate sensors/circuits/sounders?

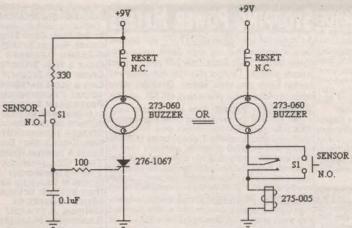
Steve Scott via Internet

A. What you want is a vibration detector, like RadioShack's 49-406 (\$12.99). This is a 120dB siren that attaches to a door or window and screams its head off when it detects an abrupt shock or vibration.

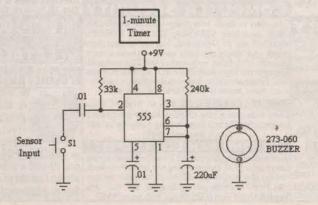
Want to make one yourself? Follow me. It begins with a plumb device, like a 1/4-inch bolt, suspended inside a 3/8-inch copper water pipe, as shown below.



This device is identical to those used in pinball machines to trigger the "tilt" alarm. Bump it too hard, and the pendulum hits against the metal guard and sounds the alarm. The sensitivity is adjusted by the size of the pipe, the length of the bare (copper) wire, and the weight of the bolt. The heavier the bolt, the more force it takes to trigger the COPPER circuit, which is shown below.



I made it simple, on purpose. Once triggered, you have to get your butt out of bed and reset the alarm. If you only want it to scare the thief away and keep warm under the blankets while the alarm does its job, you need an automatic turn-off timer circuit like this.

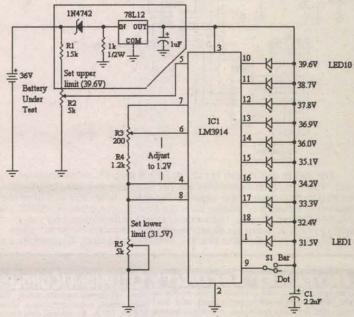


Battery Gas Gauge Does 36 Volts

Q. I have purchased all of the necessary components, including the printed circuit board, needed to build the "Battery Gas Gauge" that you described in the July '97 issue. It's my intention to use the gas gauge across two of the 6-volt batteries in the golf cart, which is used as mobility for the disabled, to get a general idea of the charge on battery pack. The thought has come to mind that it may be possible to reconfigure this schematic so that the gauge could be used across the entire bank, which contains six batteries for a total of 36 volts. Can it be done easily?

Joe Dunnett via Internet

A. This is an easy order to fill. All you have to do is separate the power source from the battery under test. Because it's been a while since we published this circuit, and there still seems to be a great deal of interest in it, here it is again with the modification for 36-volt opera-



The changes are highlighted in gray. Basically, you need to change the value of R1 and reduce the 36-volt input to 12 volts via the new 78£12 voltage regulator and its related components. Other than that, it's the same circuit. Make sure that you cut the copper trace on the PC board to pin 3 of the LM3914 and reroute it to the LM78L12 "out" when making this modification. Here's a new table showing the 36-volt battery voltage and charge levels.

Battery Voltage	LED Color	Description
39.6	Green	About 100% of charge remains
38.7	Green	About 80% of charge remains
37.7	Green	About 70% of charge remains
36.9	Green	About 55% of charge remains
36.0	Green	About 40% of charge remains
35.1	Yellow	About 25% of charge remains
34.2	Yellow	About 10% of charge remains
33.3	Red	Caution!
32.4	Red	Danger!
31.5	Red	Dead!

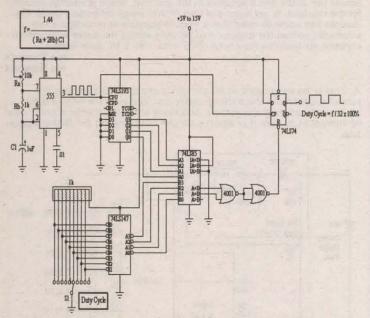
To calibrate the battery monitor, first set the voltage across pins 4 and 6 to 1.2 volts using R3. Apply 31.5 volts to the input and adjust R5 so that LED1 lights. If you don't have a 31.5-volt source, you can measure the battery-under-test voltage with a DMM (digital multimeter) and rotate R5 until that lamp lights with S1 in the dot mode. Now your ambulatory-impaired friends can get to the mall and shop 'til they drop before the golf cart drops dead.

Fixed-Duty Cycle Pulse Generator

Q. Please reference your Sept. '98 article about the LM558: Forrest Mims in his Engineer's Notebook shows a variable-pulse generator with a fixed duty cycle that uses two of these timers and a control voltage. This is a very useful circuit, but myself and others find it difficult to start. Would a 556 with a paralleling of the control inputs work better?

S. Chris Early via Internet

A. You, too? I've never been able to make that circuit work short of a swift kick in the rear. Here's a design that I ran across (and slightly modified to include S1), but have never tried. It looks very solid because it uses digital logic to vary the duty cycle, which should make it quite stable.



The key to this design is the 74LS85, a magnitude comparator chip. The 555 clock increments the 74LS193 counter, which outputs its binary BCD code to the digital comparator. When the output of the counter is equal to or greater than the binary equivalent on B0-B3, the 74LS74 flip-flop is reset. The value of B0-B3 is determined by the setting of S1, a rotary (or slider) switch that encodes decimal values of 10%, 20%, etc. into BCD that the 74LS85 recognizes. To generate a

squarewave; for example, simply set S1 to 50% (middle position). While the circuit looks complex, most of the lines are just wires going from one IC pin to another. Total cost is under \$10.00. Like I say, I've never tried this and would appreciate your feedback. In particular, I'm not sure the IA<B and A<B blocks are properly placed; you may have to exchange the two blocks (six pins in all) to make it work. I recently ran across a single IC function generator, the MAX038 from Maxim (408-737-7600; http://www.maxim-ic.com), that claims to have a variable duty cycle pulse generator that's independent of frequency. I haven't looked at it closely, but I suspect it's an upgrade of the venerable Exar XR-2206. Stay tuned for more on this chip.

More POWER!

Q. I plan to build one of your 25-watt inverters shown in the Dec. '98 column, but would like more power, too. Do you have any circuits for 3-4

> Jim Rudholm via Internet

A. Sure, but not anything you want to tackle unarmed. Once you exceed a couple hundred watts, you can't use a simple squarewave output. You have to use a modified (staircase) wave or a pure sinewave, which needs at least eight power FETs, which generate a lot of heat, which require special heatsinks, which means you need a drill press, which ... (sorry, sometimes I like playing with words as much as wires) ... makes it cheaper to buy than build. My suggestion? Check out the following retailers.

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GeoWorks Still Lives

Q. In his article "Secrets of Making Attractive Rack Panels" in the Dec. '98 issue, Thomas Henry mentions GeoDraw (Geoworks Ensemble package) as his favorite drafting program software. After checking around the Internet, CompuUSA, and local computer shops, I still haven't found a source for GeoDraw. Any suggestions?

Lee Markmann San Antonio, Texas

A. First, let me say that GeoDraw runs under the GeoWorks operating system, and isn't a Windows, DOS, or Mac program. GeoWorks, formerly known as GEOS is now sold under the name NewDeal, is like Windows 3.1 in many respects. It's an object-oriented operating system which today we call a GUI (Graphics User Interface) - or Windows. And like Windows, it runs under DOS, and the applications - like GeoDraw - are GEOS specific. In other words, the applicatlon programs for GEOS work only with GEOS. Now that you're thoroughly confused, let me say that NewDeal can be installed over Windows, Atari, Commodore, and Apple operating systems. To sort all this out, I suggest you look at James D. Bearden's FAQ (frequently asked questions) on this subject. You can find it at http://www.cis.ohio-state

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MAILBAG

Dear TJ Byers:

I just read your item in the Nov. '98 issue concerning "Hard Disk Fixes." In my business, I have run into these problems you stated on many occasions, and while you are right on target with the "stickism" problem (we call it "sticktion"), I thought I would share my two cents

with you on the third possibility you mentioned.
You stated "... the controller board has died. Unfortunately, there are no fuses to replace." Actually, I have fixed a large number of drives (read many dozens) which have a pico fuse on the controller board. They look like resistors, either standard leads or surface mount, but they are there -most near the power connectors - and they're often totally open.

John Hoyt South Carolina

Response:

misses the mark in several places. First, dithering the clock oscillator for a 20-bit ADC is a mistake

because it introduces errors into

the conversion. To maintain 20-bit

(1 ppm) resolution in amplitude, you must also maintain about 1

ppm resolution in time. For a 50-KHz sample rate, the clock should be stable to 20 picoseconds. Second, the original question is misleading. There are a couple of interpretations. The literal

interpretation is the 20-bit ADC is working fine except that the 2-MHz

clock causes a lot of radio interference to other equipment. In

1/16 inch aluminum shield provides more that 150dB of

absorption loss. Filtering the

this interpretation the column's advice about quieter clocks makes sense, but lacks some better advice. Shielding is very effective at killing 2-MHz radiated noise — a

Yep, they are there, indeed, and I knew it. I guess what I should have said is: "If you hear the motor running but can't access the data, then use a DMM to probe the controller board for a voltage any voltage. If absent, suspect the input fuse, if you can find it. If the voltage is there, then the board is dead." I'm happy to hear that you have repaired dozens of hard disks this way, but I've never been that lucky (sigh ... not even one). Thanks a lot for the input!

The advice in Oct. '98 Electronics Q & A about quiet 2-MHz clocks

TJ Byers Q & A Editor power supply and using bypass capacitors are also important.

A second (and more reasonable) interpretation is the 20-bit ADC outputs a lot of noise and the analog signals show a lot of sharp edges that coincide with the 2-MHz clock. In other words, Steve's project doesn't have the performance he wants. This interpretation is more likely, and it means there is nothing wrong with the 2-MHz clock. The clock and its harmonics are out of the ADC's input band. In this interpretation, the problem is inadequate isolation between the digital an analog parts of the circuit.

For good performance, the analog and digital circuits must be isolated. Otherwise digital currents flowing in the analog parts of the circuit will create IR voltage drops that look like noise. The circuit design needs separate analog and digital supplies, separate analog and digital ground planes, and a single point ground connection between the two systems. The ground plane cuts need careful thought. In addition to isolating the supplies, the designer must also minimize electrostatic and electromagnetic coupling.

In particular, you must keep the digital signals away from the analog signals. Assume that an output bit of the ADC toggles at 16 KHz. If that bit is close to an analog node (say close enough to have 1pF of coupling capacitance), then the capacitive impedance between the two nodes is 10 megohms. Finally, if the analog node impedance is 10K, then the 5-volt digital signal will couple 5mV of noise to the analog node. That 20-bit ADC (whose LSB is about 5 microvolts) just became a 10-bit ADC. To kill the noise, separate the analog and digital traces and use guard rings or other shields to minimize coupling capacitance. Use low impedance circuits (10K is too large).

Gerald Roylance Mountain View, CA

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TEK P6202A 500 MHz 10X FET Probe	\$250.00	Meter, 12
TEK P6201 900 MHz 1XV10XV10X FET Probe TEK P6202 500 MHz 1XV10XV10X FET Probe TEK P6202A 500 MHz 10X FET Probe TEK P6202 I GHz 10X Active Probe, for 11000 series TEK P6701-opt.02 O/E Converter,	\$175.00	STANDA
450-1050 nm/0-1 mW: DC-700 MHz, ST conn.		E.S.I. DB62- 0-11,111.
CALIBRATION	1	E.S.I. SR101
TEK SG503 Level Generator,	\$600.00	Standard E.S.I. SR105
		Standard.
WAVEFORM GENERATOR	RS	GR 1404-A 1 GR 1406 Sta
FUNCTION		GR 1432-U 4
FUNCTION HP 3310A 5 MHz Function Generator	\$250.00	0-111.10 GR 1433-G
HP 3310A 5 MHz Function Generator	\$325.00	0-1.111,1
monocycle & var.phase trigger	\$600.00	GR 1433-J 4
monocycle & var.phase trigger HP 3312A 13 MHz Function Generator HP 3325A 21 MHz Synthesized Function Generator, HPIB HP 3325A-002 21 MHz Function	\$1,000.00	0-11,110 GR 1433-K
HP 3325A-002 21 MHz Function	\$1,500.00	0-1,110 (
Generator, high voltage output option HP 8165A-002,003 Prog. Signal Source,	\$1,750.00	GR 1433-L 4 0-111,10
1 mHz-50 MHz, log sweep, rear out		GR 1433-N
TEK AWG5102 Arb.Waveform Gen., 20 MS/s,12 bits,50ppm synthesis <1MHz	\$900.00	0-11,111 GR 1433-X
TEK AWG5105-opt.02 Arbitrary Waveform	\$1,250.00	to 111,11
Generator, dual channel option TEK DD501 Digital Delay & Burst Gen.,	\$27E 00	GR 1482-se
for function & nulse nen's		VALHALLA: Resistan
TEK FG501 1 MHz Function Generator, TM500 series	\$225.00	HI & LO
TEK FG503 3 MHz Function Generator, TM500 series	\$250.00	HP 4328A N
TEX FQS01 1 MHz Function Generator, TM500 series	\$175.00	CURVET
Function Generator, GPIB	\$750.00	TEK 577D2/
PULSE		T.D.R.
BERKELEY NUCLEONICS 7085B Digital	\$750.00	TEK 1502-og Reflector
Delay Generator 0-100 mS 1 nS res 5 Hz-5 MHz		TEK 1503-0
HP 8007B 100 MHz Pulse Generator HP 8012B 50 MHz Pulse Generator, variable transition time HP 8015A-002 50 MHz Dual Output	\$600.00	0-50,000
HP 8080A/81A/83A/84A 300 MHz Word Generator	\$800.00	
HP 8080A/91A/92A/93A 1 GHz Single Channel Pulse Generator	\$950.00	SINGLE
HP 8111A-001 Pulse / Function Generator,	\$1,200.00	HP 6002A-0 Watts ma
1 Hz-20 MHz; burst option		HP 6010A A
HP 8115A 50 MHz Dual Channel	\$2,750.00	A Power
TEK PG502 250 MHz Pulse Generator,	\$600.00	HP 6011A A A Power
Tr<1nS, TM500 series TEK PG505 100 kHz Pulse Generator,	\$275.00	HP 6200B D
80 V peak, TM500 series		0-20 V 0- HP 6201B 0
TEK PG508 50 MHz Pulse Generator, TM500 series	\$500.00	HP 6207B 0
TOTAL PER CONTROL OF THE POST	3300.00	HP 6256B 0 HP 6260B-0
VOLTAGE & CURRENT		A CV/CC
		HP 6261B-0 A CV/CC
VOLTMETERS	A	HP 6263B 0
FLUKE 845AR High Impedance		HP 6266B 0
HP 3456A 6-1/2 Digit Voltmeter	\$500.00	HP 6269B-0
HP 3456A 6-1/2 Digit Voltmeter HP 3476A 5-1/2 digit Multimeter, HPIB KEITHLEY 181 6-1/2 digit Nanovoltmeter,	\$900.00	HP 6271B 0
		HP 6281A 0
SOLARTRON 7081 8-1/2 digit Voltmeter	\$225.00	HP 6289A 0
CALIBRATION		HP 6299A 0 HP 6384A 4
FLUKE 510A AC Reference Standard, 10 VRMS, 0-10 mA	\$450.00	HP 6434B 0
FLUKE 515A Portable Calibrator, DC/AC/Ohms, line & battery power	\$900.00	HP 6443B 0 HP E3610A
DC/AC/Ohms, line & battery power- FLUKE 5220A Transconductance	\$3,000.00	Power St
Amplifier, DC-5 kHz, 0-20 A		HP E3617A KEPCO ABO
FLUKE 731B DC Reference Standard	\$400.00	KEPCO ATE
		KEPCO ATE
VALHALLA 2703 AC Volt.Std.	\$1,750.00	SORENSON
0.5-1200 V, 20 H2-30 MH2 VALHALLA 2703 AC Volt.Std., 0-120V/10 Hz-100 kHz;120-1200V/10 Hz-1 kHz VOLTAGE SOURCES		600-0.75
VOLTAGE SOURCES HP 6115A Precision Dual Range	TO STREET, STORY OF STREET	SORENSON
III or ion I receive out trange		TEK PS501-
Power Supply, 50V 0.8A / 100V 0.4A		
KEITHLEY 228 Programmable Voltage/Current Source	\$2,500.00	0-20 V, 2
Power Supply, 50V 0.8A / 100V 0.4A KEITHLEY 228 Programmable Voltage/Current Source CURRENT METERS & SOURCES HP 4140B Picoammeter / DC Voltage Source, without test fixture.	waters les	MULTIPL HP 6205C D

530	Compton	St.,	Unit	#C,	В
HP 6177C D HP 6181C D HP 6186B D HP 6186C D KEITHLEY 2	C Current Source, to 50 V, C Current Source, to 100 V, C Current Source, to 300 V, C Current Source, to 300 V, 25 Current Source, 50 mA, 10-100 V compliano	500 mA 250 mA 100 mA		\$500.00 \$500.00 \$300.00 \$750.00 \$500.00	
KEITHLEY 2 KEITHLEY 2 TEK AM503 TEK CT-5 -o Transform TEK P6022	27 Current Source, 1 uA-1 261 Picoampere Source	A, 0-50 V coment Probe Sys	npliance		
The Party of the P	A STATE OF THE STA	Wild No.	IENT T	EST	
L.C.R. BOONTON	52AD 1 MHz Inductance Me 72BD 1 MHz	ter, 2-2000 ul	н	\$550.00	
Capacita	nce Meter, 3-1/2 digit displa 5 digit LCR Meter, 12 Hz-10 01 3-1/2 digit LCR	y			
STANDA	0 Hz/ 1 kHz/ 10 kHz test, H	PIB			
0-11.111	10 Ohms, 0.01 Ohm res. 0 Resistance Transfer				
Standard	s, 1 Ohm-100 K/step			0 000 00	
E.S.I. SR105 Standard	O-1M Resistance Transfer . , 1 Megohm/step			2,000.00	
GR 1404-A	Megohm/step Megohm/st	d Capacitor 00 connector,	0.1% acc	\$700.00 \$375.00	
GR 1432-U 4	4-Decade Resistor,			\$100.00	
GR 1433-G	Ohms, 0.01 Ohm resolution 7-Decade Resistor,			\$275.00	
GR 1433-J 4	-Decade Resistor			\$150.00	
0-11,110 GR 1433-K	Ohms, 1 Ohm resolution 4-Decade Resistor,			\$150.00	
0-1,110 (Ohms, 0.1 Ohm resolution				
0-111.10	O Ohms, 10 Ohms resolutions-Decade Resistor,	n		\$200.00	
0-11,111	Ohms, 0.1 Ohm resolution 3-Decade Resistor,				
to 111,11	1.0 Ohms, 0.1 Ohm res. ries Standard Inductors				
VALHALLA 2	ries Standard Inductors 2724A Programmable ce Standard, 0-11 Gigaohm		\$	\$200.00 1,250.00	
	RESISTANCE			4 000 00	
	Illiohmeter		\$	1,200.00	
	177 Curve Tracer, with stan	dard test fixtu	re\$	1,850.00	
TEK 1502-og	ot.04 Time Domain	corder	\$	1,400.00	
TEK 1503-00 0-50,000	neter, 0-2,000 feet, chart re ot.04 Time Domain Reflecto feet,chart recorder	meter,	\$	1,400.00	
H.	POWER S	UPPLI	ES	ME.	
	ОИТРИТ			6750.00	
HP 6002A-0 Watts ma	01 0-60 V/ 0-10 A/ 200 ix. Autoranging Power Supp utoranging 0-200 V 0-17	ly		\$750.00	
A Power	Supply, 1000 W max.				
HP 6011A A	utoranging 0-20 V 0-120 Supply, 1000 W max.		\$	1,400.00	
HP 6200B D	ual Range Supply,	00		\$200.00	
HP 6201B 0	1.5 A/ 0-40 V 0-750 mA CV -20 V 0-1.5 A CV/CC Power	Supply		\$175.00	
HP 6207B 0 HP 6256B 0	-20 V 0-1.5 A CV/CC Power -160 V 0-200 mA CV/CC Power -10 V 0-20 A CV/CC Power -27 0-10 V 0-100	Supply		\$250.00	
HP 6260B-0 A CV/CC	27 0-10 V 0-100 Power Supply, 208 VAC line	9	***************************************	\$675.00	
HP 6261B-0	27 0-26 V 0-50	n		\$675.00	
HP 6263B 0	20 V 0-10 A CV/CC Power	Supply		\$400.00	
HP 6267B 0	-40 V 0-10 A CV/CC Power S	Supply		\$500.00	
HP 6269B-0 HP 6271B 0	28 0-40 V 0-50 A CV/CC Po -60 V 0-3 A CV/CC Power S	wer Supply; 2 upply	30 VAC line	\$400.00	
HP 6281A 0 HP 6284A 0	7.5 V 0-5 A CV/CC Power S 20 V 0-3 A CV/CC Power S	Supply		\$150.00	
HP 6289A 0	40 V 0-1.5 A CV/CC Power	Supply		\$175.00	
HP 6384A 4	0-5.5 V at 8 A CV/CL Powe	r Supply		\$125.00	
HP 64348 0 HP 64438 0	-40 V 0-25 A CV/CC Power -120 V 0-2.5 A CV/CC Power	Supply or Supply		\$450.00	
HP E3610A Power St	Power Supply: 208 VAC lin 27 0-29 V 0-5 50 Power Supply: 208 VAC lin 20 V 0-10 A CV/CC Power 40 V 0-5 A CV/CC Power 5 40 V 0-10 A CV/CC Power 22 0-40 V 0-50 A CV/CC Power 5 20 0-40 V 0-50 A CV/CC Power 5 20 V 0-3 A CV/CC Power 5 20 V 0-3 A CV/CC Power 6 V 0-50 V 0-50 V 0-60 V 0-750 MA CV/CC Power 100 V 0-750 MA CV/CC Power 100 V 0-750 MA CV/CC Power 100 V 0-25 A CV/CC Power 120 V 0-8 V 0-3 A / 0-15 V 0/60 V 0-25 A CV/CC Power 100 V 0-8 V 0-3 A / 0-15 V 0/60 V 0-8 V 0-3 A / 0-15 V 0/60 V 0-8 V 0-3 A / 0-15 V 0/60 V 0-8 V 0-8 V 0-3 A / 0-15 V 0/60 V 0-8 V 0-8 V 0-9 A / 0-15 V 0/60 V 0-8 V 0-9 V 0	-2 A		\$175.00	
HP E3617A KEPCO ABO	JDDI), US V 0-2 A C V/CC Power C-1500M 0-1500 V 10 mA C 36-30M 0-36 V 0-30 A CV/CC DCR 20-25B 0-20 V 0-25 A DCR	Supply	Sinnly	\$175.00	
KEPCO ATE	36-30M 0-36 V 0-30 A CV/	CC Power Su	pply	\$900.00	
SORENSEN	DCR 20-25B 0-20 V 0-25 /	CV/CC Power	er Supply	\$550.00	
SORENSON	I SRL 20-12 0-20 V 0-12 A 0 I SRL 60-8 0-60 V 0-8 A CV 1 Power Supply,	CV/CC Power	Supply	\$400.00	
TEK PS501-	1 Power Supply,	To rower Si		\$175.00	
	mV res., 400 mA, TM500 s E OUTPUT	enes			
	tual Output Supply, 0-40 V 3	00 mA or 0-2	0 V 600 mA	\$300.00	

Broomfield, Colorado 800	020
HP 6227B Dual 0-25 V 0-2 A CV/CC Power Supply	\$450.00
HP 6236B Triple Output Supply, to +/-20 V 0.5 A & 0-6 V 2.5 A	\$375.00
HP 6253A Dual 0-20 V 0-3 A CV/CC Power Supply	\$450.00 \$450.00
LAMBDA LPT-7202-FM Triple Output Power Supply	\$450.00 \$650.00
Triple Power Supply, TM5000 series TEK PS503A Dual Power Supply, TM500 series	
MISCELLANEOUS	9200.00
ACME PS2L-500 Programmable	\$350.00
Load, 0-75 V / 0-75 A / 500 Watts max. ELGAR 1751B/461 AC Power Source, 0-135 VAC, 1750 Watts, fixed freq.osc.	\$2,000.00
HP 59501B HPIB Isolated DAC/Power Supply Programmer	\$175.00
HP 59501B HPIB Isolated DAC/Power Supply Programmer HP 6825A Bipolar Power Supply/ Amplifier, +f-20 V 2 A HP 6827A Bipolar Power Supply/ Amplifier, +f-100 V 0.5 A KEPCO BOP 20-20M Bipolar Op.	\$800.00
Amp/Power Supply, to 20 V 20 A	
KEPCO BOP 36-5M Bipolar Op	\$400.00
Amp/Power Supply, to 36 V 5 A KEPCO BOP 50-2M Bipolar Op Amp/Power Supply, to 50 V 2 A	\$400.00
TRANSISTOR DEVICES DAL-50-15-100	\$200.00
TIME & FREQUENCY	100
UNIVERSAL COUNTERS	
HP 5315A-001 100 MHz/100 nS Universal	
HP 5315A-003 100 MHz/100 nS Univ	
HP 5316A 100 MHz/100 nS Universal Counter————————————————————————————————————	\$500.00
HP 5316A-001,003 100 MHz/ 100 nS	\$750.00
Univ. Counter, HPIB, TCXO, 1 GHz C-ch. HP 5316B 100 MHz/ 100 nS Universal Counter, HPIB	\$750.00
Univ. Counter, HPIB, TCXO, 1 GHz C-ch. HP 5316B 100 MHz/ 100 nS Universal Counter, HPIB	\$200.00 \$750.00
Univ Counter: OCXO DVM 1.3 GHz C-ch rear in	
HP 5334B-010,060 100 MHz Universal Counter, HPIB, OCXO HP 5335A 200 MHz Universal / Statistical Counter HP 5364A Microwave Mixer /	\$500.00
Detector, for modulation domain an.	
TEK DC5004 Programmable	
TEK DC5009 Programmable	
TEK DC5010 350 MHz / 3.125 nS Universal Counter, TM5000 series	
TEK DC503A 125 MHz/100 nS	\$275.00
Universal Counter, TM500 series TEK DC509 135 MHz/ 10 nS Universal Counter, TM500 series . FREQUENCY COUNTERS	\$275.00
EIP 575 18 GHz Source Locking Counter, GPIB	\$1,500.00
FLUKE 7220A-010,131,351 1.3 GHz	\$500.00
Counter; battery power, OCXO, and res. mult. HP 5340A 18 GHz Frequency Counter HP 5342A 18 GHz Frequency Counter HP 5342A-001,011 18 GHz-Frequency	\$450.00 \$500.00
Counter, OCXO reterence & HPIB	
HP 5342A-003 18 GHz Freg Counter	\$600.00
+22 dBm, -20 dBm dynamic range HP 5343A-001 26.5 GHz Frequency Counter, OCXO reference	\$3,500.00
HP 5345A/5355A/5356B 26.5 GHz CW/Pulse Frequency Counter	. \$3,500.00
TEK DP501 1.3 GHz Prescaler, divide by 16, TM500 series	\$225.00
STANDARDS HP 105B Quartz Oscillator 0.1/1.0/5.0 MHz, hattery nower	\$1.500.00
HP 105B Quartz Oscillator, 0.1/ 1:0/ 5.0 MHz, battery power HP 5087A-opt.033 Distribution Amplifier; 12 outputs at 10 MHz	\$1,750.00
AUDIO & BASEBAND	28.00
SPECTRUM ANALYSIS	
HP 3586C Selective Level Meter,	\$1,500.00
TEK 7L5/L3/R7603 Spectrum	\$1,500.00
Analyzer, 20 Hz-5 MHz, 10 Hz min. res., w/frame DISTORTION ANALYZERS	
HP 339A Distortion Analyzer, built-in low distortion osc	\$750.00
20 Hz-100 kHz; rear panel input HP 8903B-001,013,051 Audio Analyzer,	
20 Hz-100 kHz: C-message, CCITT	
TEK DA4084 Programmable Distortion Analyzer	\$750.00
FLUKE 8920A True RMS Voltmeter,	\$450.00
180 uV-700 V, 10 Hz-20 MHz FLUKE 8922A True RMS Voltmeter, 180 uV-700 V, 2 Hz-11 MHz	\$450.00
OSCILLATORS HP 209A Sine/Square Wave Generator,	\$225.00
A LIN O ARLIN E VIDARO MANY	
HP 3336C Synthesizer/ Level Generator, 10 Hz-21 MHz TEK SG5010 Programmable Oscillator, 10 Hz-163.8 kHz	\$2,750.00
TEK SG502 Sine/Square Osc. 5 Hz-500 kHz, 70 dB step atten.,TM500	\$200.00
MISCELLANEOUS	\$125.00
HP 461A Amplifier, 20/40 dB, 1 kHz-150 MHz, 0.5 V/50 Ohms KROHN-HITE 3103 High/Low	\$350.00
Pass Filter, 10 Hz-3 MHz, 24 dB/octave	_



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KROHN-HITE 3202 Dual HP/LP/BP/BR	\$450.00	HP 86230B RF Plug-in, 1.8-4.2 GHz, +10 dBm unlevelled	\$400.00	HP K382A WR42 Direct Reading	\$2,900.00
Filter, 20 Hz-2 MHz, 24 dB/octave KROHN-HITE 3342R Dual HP/LP Filter,	\$900.00	HP 86240C RF Plug-in, 3.6-8.6 GHz, +16 dBm levelled	\$700.00 \$300.00	Attenuator, 0-50 dB, 18-26.5 GHz HP K422A WR42 Flat Broadband Detector, 18.0-26.5 GHz	\$350.00
0.001 Hz-99.9 kHz, 48 dB/octave		HP 86242D-004,008 RF Plug-In,	\$300.00	HP K532A WR42 Frequency Meter, 18.0-26.5 GHz	\$450.00
KROHN-HITE 3750 LP/HP/BP/BR Filter,	\$600.00	5.9-9.0 GHz, +10 dBm levelled HP 86250D RF Plug-in, 8.0-12.4 GHz, +10 dBm levelled	\$500.00	HP K870A WR42 Slide Screw Tuner, 18.0-26.5 GHz	\$275.00 \$300.00
KROHN-HITE DCA-10R 10 Watt	\$450.00	HP 86260A RF Plug-in, 12.0-18.0 GHz, +10 dBm unlevelled	\$500.00 \$500.00	HP Q752D WR22 Directional Coupler, 20 dB, 33-50 GHz	\$650.00
Amplifier, 20 dB gain, DC-1 MHz, 600-1000 Ohms ROCKLAND 852 Dual Highpass/	\$900.00	HP 86260A-H04 RF Plug-in,		HP R382A WR28 Direct Reading	\$2,000.00
Lowpass Filter, 0.1 Hz-111 kHz TEK AM502 Differential Amplifier,	\$475.00	HP 86290A RF Plug-in, 2.0-18.0 GHz, +7 dBm levelled	\$1,750.00 \$2,250.00	HP R532A WR28 Frequency Meter, 26.5-40 GHz HP R752A WR28 Directional Coupler, 3 dB, 26.5-40 GHz	\$500.00 \$450.00
0.1 Hz-1 MHz, TM500 series		WAVETEK 962 Sweep Generator,	\$1,250.00	HP R914B WR28 Moving Load, 26.5-40 GHz	\$250.00
DE 8 MICDOWAVE		1.0-4.0 GHz, markers, +12 dBm unlvld. WILTRON 6619A Sweep Generator,	\$1,500.00	HP V365A WR15 Isolator, 25 dB, 50-75 GHz HP V752D WR15 Directional Coupler, 20 dB, 50-75 GHz	\$900.00 \$650.00
RF & MICROWAVE	A LIVE	2-8 GHz, +10 dBm levelled	.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	HP X870A WR90 Slide Screw Tuner	\$150.00
SPECTRUM ANALYZERS		POWER METERS	*****	HUGHES 45712H-1000 WR22 Frequency Meter, 33-50 GHz HUGHES 45721H-1000 WR28	\$900.00 \$900.00
HP 11517A/18A/19A/20A Mixer Set,	\$600.00	ANRITSU MA72B Power Sensor, -20 to +20 dBm, 0.01-18 GHz	\$200.00	Direct Reading Attenuator, 0-50 dB, 26.5-40 GHz	
12.4-40.0 GHz, for HP 8555A/8569A HP 11970A WR28 Harmonic Mixer, 26.5-40 GHz	\$1,100.00	ANRITSU MP-81B/ML-83A Power Meter,	\$2,500.00	HUGHES 45732H-1200 WR22 Level Set Attenuator, 0-25 dB, 33-50 GHz	\$250.00
HP 11970K WR42 Harmonic Mixer, 18.0-26.5 GHz	\$1,100.00	75-110 GHz (WR10), -20 to +20 dBm BOONTON 4200-01A,03/&-4A x2 Dual	\$950.00	HUGHES 45772H-1100 WR22	\$400.00
HP 11970Q WR22 Harmonic Mixer, 33-50 GHz HP 11970U WR19 Harmonic Mixer, 40-60 GHz	\$1,400.00 \$1,400.00	Channel Microwattmeter, w/(2) 1 MHz-7 GHz sensors	\$375.00	Thermistor Mount, -20 to +10 dBm, 33-50 GHz HUGHES 45775H-1100 WR12	\$800.00
HP 8444A-059 Tracking Generator, 0.5-1500 MHz, for 8554,8568,etc.	\$1,250.00	BOONTON 42B/41-4B Analog Power Meter, with 1 MHz-12 GHz sensor		Thermistor Mount, -20 to +10 dBm, 60-90 GHz HUGHES 47316H-1111 WR10	\$600.00
HP 853A-001 Spectrum Analyzer	\$1,250.00	BOONTON 42B/41-4E Analog Power Meter,	\$500.00	Tuneable Detector, 75-110 GHz, positive polarity	
Display, bench/rack mount config. HP 8565A-100 Spectrum Analyzer,	\$4,500.00	GENERAL MICROWAVE 476/4240A	\$300.00	HUGHES 47323H-1211 WR19 Flat Broadband Detector, negative, 40-60 GHz	\$650.00
10 MHz-22 GHz, 100 Hz min. res.		Power Meter & Sensor, 0.01-18 GHz, -35 to +10 dBm HP 435B/8481A Power Meter,	\$900.00	HUGHES 47974H-1000 WR15 SPST PIN	\$375.00
HP 8566B Spectrum An., 100 Hz-22 GHz,	\$25,000.00	-30 to +20 dBm, 10 MHz-18 GHz		Switch, 250 MHz speed, 60-62 GHz response M/A-COM 3-19-300/10 WR19	\$450.00
HP 8569B Spectrum Analyzer,	\$7,500.00	HP 435B/8482B Power Meter,	\$1,750.00	Directional Coupler, 10 dB, 40-60 GHz	
10 MHz-22 GHz, 100 Hz min.res.bw. TEK 7L14-039/7603 Spectrum Analyzer,	\$2,500.00	HP 435B/8482H Power Meter,	\$900.00	MIDWEST MICROWAVE 3537 DC Block,	\$40.00
1 kHz-2.5 GHz, 30 Hz min. res. bw.	\$950.00	-10 to +34 dBm, 100 kHz-4.2 GHz HP 436A-002,022/8481A Power Meter,	\$1,250.00	MINI-CIRCUITS ZFDC-20-4 Directional	\$25.00
TEK TR502 Tracking Generator,		HP 8477A Power Meter Calibrator, for HP 432 series	\$500.00 \$350.00	Coupler, 19.5 dB, 1-1000 MHz, SMA(I) MINI-CIRCUITS ZHL-42 Amplifier,	\$400.00
TEK TR503 Tracking Generator, 0.1-1800 MHz, for 492/4/5/6 TEK WM782V WR15 Harmonic Mixer, 50-75 GHz	\$850.00 \$1,500.00	HP K486A WR42 Thermistor Mount,	new British and the	30 dB gain, 0.7-4.2 GHz, +28 dBm, 15V, SMA NARDA 3000-SERIES Directional Couplers	\$150.00
NETWORK ANALYZERS	91,000.00	HP Q8486A Power Sensor,	\$1,500.00	NARDA 3024 Bi-Directional Coupler, 20 dB, 4-8 GHz	\$300.00
HP 08748-60010 8748A Reference	\$375.00	33.0-50.0 GHz, WR22, for 435/6/7/8 HP R486A WR28 Thermistor Mount,	\$350.00	NARDA 3090-SERIES Precision High Directivity Couplers	\$225.00
Plane Extension Cables (set of 6)	\$250.00	26.5-40 GHz, for 432 series HP R8486A WR28 Power Sensor.	\$1,500.00	NARDA 368BNM Coaxial High	7. 10
HP 08748-60011 8748A-H26		26.5-40 GHz, for HP 435/6/7/8	\$1,500.00	NARDA 3752 Coaxial Phase Shifter, 0-180 deg./GHz, 1-5 GHz	\$1,000.00
HP 11650A Network Analyzer Accessory Kit, APC7	\$600.00	RF MILLIVOLTMETERS		NARDA 3753B Coaxial Phase Shifter,	\$1,000.00
HP 35676A Reflection/Transmission	\$1,000.00	BOONTON 928-opt.05 RF Millivoltmeter,	\$500.00	0-55 deg./GHz, 3.5-12.4 GHz NARDA 4000-SERIES SMA Miniature Directional Couplers	\$75.00
Test Kit, 5 Hz-200 MHz HP 8405A Vector Voltmeter, 1-1000 MHz	\$450.00	RACAL 9303 TRMS Level Meter,	\$875.00	NARDA 4245-10 Directional Coupler, 10 dB, 4-12 GHz, SMA(f)	\$100.00
HP 85020A Directional Bridge, 10-4300 MHz, N(f) test port	\$650.00	10 kHz-2 GHz, -77 to +23 dBm, GPIB		NARDA 4799 Level Set Attenuator, 0-15 dB, 4-18 GHz, SMA(I) NARDA 5070-SERIES Precision Reflectometer Couplers	\$135.00 \$300.00
HP 85021A Directional Bridge, 0.01-18 GHz, APC7 test port HP 85021C Directional Bridge,	\$1,000.00 \$1,000.00	AMPLIFIERS, MISCELLANEOUS AMPLIFIER RESEARCH 1W1000	\$650.00	NARDA 765-10 10 dB Attenuator, 50 Watts, DC-5 GHz, N(m/f).	\$135.00
0.01-18 GHz, N(f) test port		Amplifier, 30 dB gain, 1-1000 MHz, 1 Watt output		NARDA 769-30 30 dB Attenuator, 150 Watts, DC-6 GHz, N NARDA 792FF Variable Attenuator, 0-20 dB, 2.0-12.4 GHz	\$275.00
HP 85027A Directional Bridge, APC7 test port, 10 MHz-18 GHz	\$2,000.00	BOONTON 82AD-opt.01A Modulation	\$750.00	NARDA 794FM Direct Reading	\$375.00 \$375.00
HP 8502A-H26 Reflection/	\$600.00	HP 415E SWR Meter	\$200.00	Variable Attenuator, 0-40 dB, 4-8 GHz OMNI-SPECTRA 2085-6010-00 Crystal	\$50.00
Transmission Test Set, 4-2600 MHz HP 85044A Reflection/	\$1,500.00	HP 465A Amplifier, 20/40 dB, 5 Hz-1 MHz, 1/2 Watt/50 Ohms HP 8447A Amplifier, 20 dB,	\$125.00 \$375.00	Detector, 1-18 GHz, negative polarity, SMA(m/f)	\$250.00
Transmission Test Set, 300 kHz-3 GHz	A SHARE WAS A SHAR	0.1-400 MHz, 5 dB NF, +6 dBm output		PAMTECH KYG1014 WR42 Junction	
HP 85046A S-Parameter Test Set,	\$3,500.00	HP 8447E Amplifier, 22 dB, 0.1-1300 MHz, +13 dBm output HP 8447F Preamplifier / Power Amplifier, 0.1-1300 MHz	\$750.00	SONOMA SCIENTIFIC 21A3 WR42	\$75.00
HP 8756A Scalar Network Analyzer	\$2,500.00	HP 8901A Modulation Analyzer, 150 kHz-1300 MHz	\$2,500.00	Circulator, 20 dB, 20.6-24.8 GHz SPACEK LABS K-2X Frequency	\$350.00
HP R85026A WR28 Detector,	\$1,200.00	HP 89018-1,2,3 Modulation An., 0.15-1300 MHz, rear input, OCXO, ext.LO	\$3,000.00	Doubler, 9.0-13.25 GHz in/ 18.0-26.5 GHz out SPACEK LABS KA-3X Frequency Tripler,	\$350.00
SIGNAL GENERATORS		HP 8970A Noise Figure Meter	\$5,000.00	8.83-13.33 GHz in/ 26.5-40.0 GHz out	
FLUKE 6060A Synthesized Signal Gen., 0.1-1050 MHz, 10 Hz res., GPIB	\$2,500.00	HUGHES 1177H02F000 TWT Amplifier, 4.0-8.0 GHz, 10 Watts output	\$1,500.00	TRANSCO 705C90100 Latching DPDT Transfer Switch, DC-26.5 GHz, 28 V	\$150.00
FLUKE 6060A/AN Synthesized Signal Gen.,	\$1,500.00	MICROWAVE SEMI.CORP. MC5112	\$175.00	TRG B528 WR22 Direct Reading	\$1,250.00
10 kHz-520 MHz, 10 Hz res.,GPIB FLUKE 6062A Synthesized Signal Gen.,	\$5,000.00	Noise Source, 25.5 dB ENR, 1.0-12.4 GHz, N(m), +28 VDC ROHDE & SCHWARTZ ESH2 Test	\$5,000.00	Phase Shifter, 0-360 deg., 33-50 GHz TRG V551 WR15 Frequency Meter, 50-75 GHz	\$600.00
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Source, 10-18 GHz, 1 MHz res., GPIB GIGATRONICS 600/6-12 Synthesized	\$2,500.00	AMERICAN NUCLEONICS AM-432	\$95.00	2-Way, DC-18 GHz, SMA(m/f/f) WEINSCHEL DS109 Double	\$150.00
Source, 6-12 GHz, 1 kHz res., GPIB		Cavity Backed Spiral Antenna, LHC, 2-18 GHz, TNC(f) "NEW" AVANTEK AMT-400X2 WR28 Active	\$450.00	Stub Tuner, 1-13 GHz, N(m/l) WEINSCHEL DS109LL Double	\$150.00
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GIGATRONICS 875/86 Levelled Multiplier,	\$3,750.00	CONTINENTAL MW. RAE28-K-M WR28 x K(m) Endfire Adapter	\$650.00 \$225.00 \$125.00	COMMUNICATIONS	
26.5-40.0 & 50.0-75.0 GHz outputs GIGATRONICS 900/2-8 Synthesized	\$2,500.00	FXR/MICROLAB S3-02N Triple	\$125.00	COMMUNICATIONS	
Signal/Sweep Gen., 2-8 GHz, 1 MHz res.,GPIB HP 11720A Pulse Modulator, 2-18 GHz, 80 dB on/off ratio	\$450.00	GR 874-LTL Constant Impedance	\$400.00	HP 3762A/3763A BER Test System, 1 kHz-150 MHz	\$1,250.00
HP 85100V Frequency Mult.,	\$3,750.00	Trombone Line, 0-44 cm, DC-2 GHz GR 900-Q GR900 14mm Interseries Adapters	\$125.00	HP 4935A-003 Transmission	\$1,250.00 \$600.00
10-15 GHz in / 50-75 GHz out >0 dBm HP 8640B-001 Signal Generator.	\$1,000.00	HP 11590A-001 Bias Network, 1.0-18.0 GHz, APC7	\$450.00	Test Set, 20 Hz-110 kHz, battery power HP 59401A HPIB Bus Analyzer	\$700.00
0.5-512 MHz, AM, FM, var. audio osc.	AND ANACHASTA	HP 11692D Dual Directional Coupler, 22 dB, 2-18 GHz	\$800.00 \$475.00	TEK 1410R NTSC Gen., w/SPG2 sync. generator, TSG7 color bars	\$800.00
HP 8640B-002,003 Signal Gen., 0.5-1024 MHz, AM, FM, reverse power prot.	\$1,750.00	Atten., 0-70 dB, DC-26.5 GHz, 3.5mm		TEK 1411R PAL Gen.,w/SPG12 sync;	\$750.00
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0.1-1040 MHz, 10 Hz res., HPIB		HP 777D Dual Directional Coupler, 20 dB, 1.9-4.1 GHz HP 778D Dual Dir. Coupler, 20 dB, 100-2000 MHz, N test port	\$275.00 \$450.00	TEK 1411R PAL Test Gen.,	\$1,100.00
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Generator, 2-26 GHz, >+8 dBm output	\$3,500.00	10 MHz-18 GHz, neg.pol., SMA		MISCELLANEOUS	187 D E
HP 8684B Signal Generator, 5.4-12.5 GHz, AM, WBFM, Pulse	40,000.00	HP 8494A-001 Step Attenuator, 0-11 dB, DC-4 GHz, N(I/I) HP 8494B-002 Step Attenuator, 0-11 dB, DC-18 GHz, SMA(I/I)	\$350.00 \$450.00	WISCELLANEOUS	
SWEEP GENERATORS		HP 8494G-002 Programmable	\$350.00	P.A.R. 5206-95,98 Two-Phase Lock-in Amp.,	\$1,500.00
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While there are a number of programs that let computers multi-task, Talking E-mail lets people multi-task. Without interfering with your other work, Talking E-Mail will talk to you, letting you know who is trying to contact you, and what they have to say. You'll hear immediately if your incoming E-Mail is important enough for you to interrupt what you're doing, or if you can respond to it routinely later. When an E-Mail message arrives, an animated cartoon character pops up on the screen and starts reading the message. Talking E-Mail is highly customizable, allowing you to specify if you want to hear who sent the message, its subject, and how many lines of the message should be read. You can stop the cartoon character at any time, or keep listening while you are working. You can even launch your default e-mail program and reply to the message.

Talking E-Mail's rules system allows you to specify the behavior of the char-

Talking E-Mail's rules system allows you to specify the behavior of the charlaiking E-Mair's rules system allows you to specify the behavior of the character and what he will say when a message arrives from a specific individual. A variety of animations, sounds, and other settings are available, adding fun and practicality. Talking E-Mail uses Microsoft Agent technology ™ to achieve its natural-sounding, understandable voice quality.

In addition to its entertainment value, Talking E-Mail has some very practical uses. You can schedule Talking E-Mail to check your inbox at any time interval, and have the program read your messages aloud, ensuring that critical E-Mails are brought to your attention immediately. It automatically checks for your

are brought to your attention immediately. It automatically checks for your incoming mail, and makes it easy to hear from your friends and colleagues, with-

out having to stop other activities.

Talking E-Mail costs \$14.95 and can be ordered online from http://www.4developers.com/talkmail/. Site licenses are available. You can also download a trial version of Talking E-Mail from http://www.4developers.com

For more information, contact:

4Developers LLC

912 E. Evelyn Avenue Sunnyvale, CA 94086 E-Mail: sales@4developers.com

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Mainstay Releases JustEdit™ **Browser-Based Text Editor Speeds Up Web Page Edits**

Camarillo, CA — Mainstay today began shipping JustEdit™, a quick and painless way to edit web pages anytime, anywhere, using only a web browser. JustEdit is a Java applet that need only be included in a single web page of a site. A user simply brings up the JustEdit page, enters the path to any web page to edit and clicks "Open." A text editor window opens — displaying HTML code, ready for editing. After making changes, the user clicks "Save" and their web page is modi-

field. JustEdit works on any website and requires no server-side applications, scripts, CGIs, or plug-ins.

JustEdit enables the user to correct a typo, update a headline, price, or date, and even correct a broken or changed link, on the fly, right in a browser. Using JustEdit, there's no need to start an FTP application, find a source file, or download the file from the year at the server of the proper start the server of the serve load the file from the web, start a web page editor, make the changes, save the changes, then re-upload the file.

Web pages can be changed from anywhere in the world using nothing more than a web browser. JustEdit eliminates the time wasted "round-tripping" web files back and forth to the web server, or needlessly searching for HTML files on a local hard disk. It also eliminates the frantic call back to the office, trying to talk

someone through making a simple change.

JustEdit maintains the same level of security enjoyed by web pages today. In fact, JustEdit can be thought of as a transparent FTP client embedded in a web page. Like all FTP clients, both a name and a password are necessary for

read/write access to web pages.

JustEdit is now available directly from Mainstay. The special introductory price is \$49.95. JustEdit can be purchased with immediate electronic delivery at:

http://www.mstay.com. JustEdit works with Windows 95/98/NT, Macintosh and Unix. A free promotional version is also available from www.mstay.com and most popular download sites.

Mainstay 591-A Constitution Avenue Camarillo, CA 93012 http://www.mstay.com

Build an Inexpensive Temperati

by Mike Keryan

build an inexpensive circuit that measures temperatures and humidities. The sensor circuitry is unique in that it requires no calibration whatsoever. It is controlled by a PIC CPU chip that spends most of its time sleeping. Once every five minutes or so, it wakes up and samples the air, and transmits the data onto the house power line using an inexpensive X10 interface. You can place up to eight of these monitoring systems throughout your house, even in your attic and on your screened porch. Somewhere in your house, a PC - connected to an X10 receiver via RS-232 - collects and reports the data. The monitoring software can be extended to make decisions based on the data.

n this article, you will see how to

The THX10 remote monitoring system described in this article is inexpensive, accurate, and flexible. You can buy sensors that sample and report accurate temperature and humidity data, but they will probably set you back over \$100.00 apiece. And even if you had the money to buy enough of them to monitor most of the rooms in your house, and to purchase an expensive master monitoring station, you would still have to run a bunch of wires around your house to connect everything.

Or, you can build one or more of

on your house's power ne, and receive the formation on your

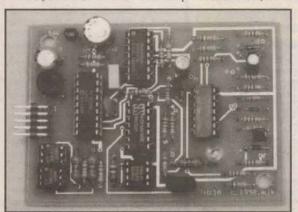
the sensor units described in this arti cle. You can pick up the X10 inte face equipment at your local RadioShack. With THX10, you won have to calibrate anything or string up any wires between rooms. And you can customize the monitor software yourself, because it is written in

In Part 1 of this twopart article, we'll talk a litabout humidity, describe how the circuit works, and how to build the sensor circuitry. In Part 2, we'll show you how to connect the sensor circuitry to an X10 interface, and how the X10 receiver and software works.

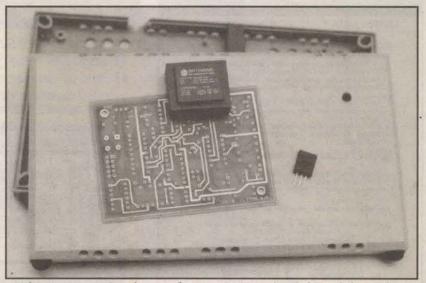
Why Bother to Measure **Humidity?**

Ever since we moved from up North to South Carolina several years ago, my family and I have not been able to adjust to the temperature. Not outside; the temperature outside s nearly always warm to hot and your body seems to become accustomed to that. The problem is inside, where the windows and doors are kept closed and the environment is supposedly controlled. Temperature fluctuations are kept to a minimum thanks to the heating and air-conditioning systems and programmable thermostats. However, it almost never feels ideal. Most of the time, it feels either too warm or too cool, even though the thermostats both upstairs and downstairs swear that the temperature hasn't changed. What they don't tell us anything about is the humidity.

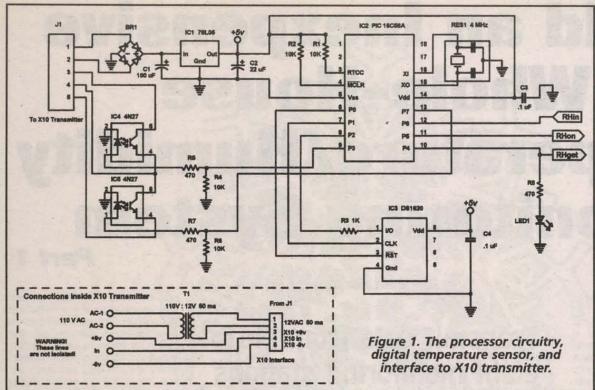
Our HVAC systems work very hard to maintain a constant temperature, because our bodies are greatly affected by the temperature. However, human bodies, as well as many other living and non-living things, are also greatly affected by the humidity. Our natural cooling system is dependent on our sweat



The THX10 circuit board with components installed.



The compact 12-volt transformer, THX10 circuit board, humidity sensor, and plastic enclosure. Note the many holes drilled into the enclosure for ventilation.



being able to evaporate. If the humidity is very high, the moisture we secrete out of our sweat glands tends to remain on our skin. There is no significant gradient between the moisture on our moist skin to the moist atmosphere, so we experience no cooling effect.

On the other hand, when the humidity is very low, moisture on our skin evaporates very quickly into the relatively moisture-free atmosphere. When this evaporation takes place, a certain amount of heat is given up from our skin to the environment, and our skin feels cool. When our skin feels cool, we feel cool.

Air at any specific temperature can only hold a finite amount of water vapor. When the air is forced to hold as much moisture as possible, it is said to be saturated. At higher temperatures, the air can hold larger amounts of water vapor, in fact, much larger amounts - it is an exponential relationship. Relative Humidity is defined as the amount of water vapor that is currently present in the air, divided by the maximum that the air can hold at that same temperature. Therefore, there is a lot more moisture in the air at 90° F, 90% RH, than at 80° F, 90% RH.

It Ain't the Heat, It's the Humidity!

We can generate what is known as the heat index, using both temperature and humidity. The heat index is probably a better indicator of how we feel than either temperature or humidity alone. The heat index accounts for the ability of moisture to evaporate (low humidity) or to not evaporate (high humidity). Table 1 shows the heat index for temperatures and humidities in 10°/% increments. Note the example above: 80° F, 90% RH feels like 88°, but 90° F, 90% RH feels like a whopping 122°!

Prolonged exposure and physical activity at a heat index of greater than 90 can cause heat exhaustion, while an index greater than 100 can lead to heat stroke. While the temperatures in our homes are not likely in this high a range, you can see from the chart that humidity does have an affect even at room temperatures, in the 60-90° F range. High humidities in the 80-90° F range make it feel five or more degrees warmer, while low humidities in the 60-70° F range make it feel five or more degrees cooler than a thermostat would say.

So why don't our thermostats measure heat index, rather than just temperature? One big reason is that monitoring and detecting water vapor is much more difficult than measuring other parameters, such as temperature, pressure, etc. Humidity sensors tend to have limited lifetimes, most are highly non-linear and highly temperature-depen-dent, and they typically have very high part-to-part tolerances, meaning they must be calibrated.

A typical calibration involves placing certain salt solutions in closed containers to give known humidity levels. This is not practical for most manufacturers, and probably nearly impossible for most home tinkerers.

The NH-03 Humidity Sensor

The circuitry in this article is designed around a humidity sensor distributed by Figaro USA, Inc. The NH-03 sensor contains two relative humidity sensitive elements, made from a stable high polymer impregnated in porous ceramic. The sensor also contains two printed NTC thermistors on an alumina ceramic substrate.

The network of humidity and temperature sensors provide temperature compensation, as well as a linear output. The sensor is provided in a small (10 mm x 12 mm x 4 mm) plastic package with three leads, spaced 0.1 inch apart. Figaro states the overall long-term accuracy of the sensor to be ± 10% for 0-40° C (50-104° F) and 30-80% RH, but when used in the self-calibrating circuit (see below), deviations greater than about 3% RH haven't been detected.

Humidity measurement is complicated by the fact that any DC volt-

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age applied to the sensor will degrade the humiditysensitive elements. In a typical humidity measuring operation, an AC voltage of precisely 1 volt, 1 KHz is supplied across pins 1 and 3 of the sensor. The output is an AC voltage across pins 1 and 2. This AC output voltage is nearly a linear relationship with the % Relative Humidity.

Due to the sensor network, the output is basically independent of fluctuations in temperature and frequency. However, the output is very sensitive to the actual level of input AC voltage, as well as our ability to accurately measure small AC voltages.

A self-calibration technique is used to overcome the problems with the small AC voltages. Circuitry is provided to change the output AC voltage to a DC voltage and then translate the DC voltage to a pulse width. The PIC CPU chip is able to make precise timing measurements of the pulse

width.

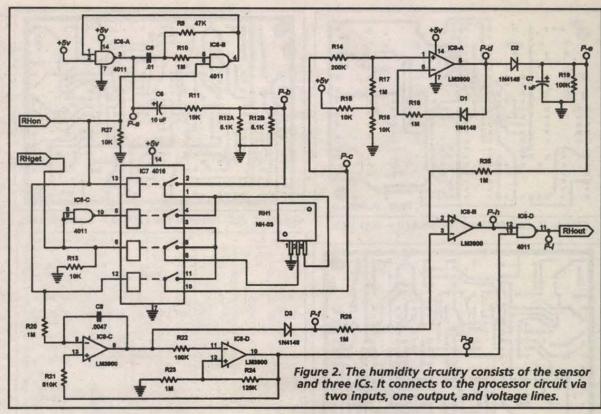
The measurement process is done twice; the first time measuring the results of the input voltage, the second time measuring the results of the output voltage. Both pulse widths are directly proportional to the corresponding AC voltages: the input AC voltage, a nominal one volt, and the output AC voltage which is a measure of the Relative Humidity and can vary anywhere between 0 volt to 1 volt. Dividing the pulse widths gives the same result as dividing the voltages. This software technique eliminates the need for calibration or for precise AC voltage generation and measurement equipment.

The DS1620 Temperature Sensor

If you read a lot of electronic and PIC literature and magazines. you've probably seen this temperature sensor made by Dallas Semiconductor described before. It is a truly digital chip; it measures the temperature by means of internal oscillators, and outputs data in digital format. It is accurate, stable, and is very easy to interface to a PIC chip. Since it requires no calibration, it is the perfect counterpart for the selfcalibrating humidity circuit. Dallas claims the accuracy of the chip to be ±0.5° C (about 1.0° F).

The CPU

PIC microprocessor chips are turning up everywhere nowadays. They are becoming as common as 555 timer chips. The PIC16C58A from Microchip used in this THX10 circuit communicates with the



humidity circuitry and with the tem-perature chip, and does some calculations to convert the data to °F and % RH. It then sends the data to an X10 transmitter as eight-bit binary sequences, and it communicates the findings on a single LED, used mainly for debugging.

Although any one of these tasks would not be a big problem, developing a circuit built up from discrete logic ICs to handle ALL these tasks would be impractical. The PIC chip

does it all easily, and spends more than 90% of the time in a low power sleep mode.

The Processor Circuit, Temperature Sensor, and Interface

Refer to Figure 1 for details of the processor circuit. The circuit receives a 12-volt AC power input at pins 1 and 2 of J1. BR1 rectifies it, producing a DC voltage that is

smoothed by C1, regulated by IC1, and filtered by C2, producing a 5-volt DC power supply. The total circuit draws at most 20 mA or so (most of the time much less), so the regulator runs cool. IC2 - the PIC CPU receives the 5-volt supply with an additional capacitor, C3, to reduce high-frequency fluctuations.

RES1 connects to pins 15 and 16 IC2 to provide a 4-MHz clock pulse. Unused pins 3 and 4 are pulled high by R1 and R2 to avoid

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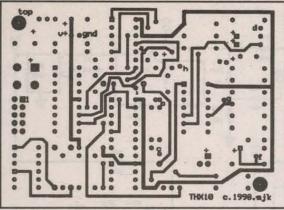


Figure 3. Foil Pattern for THX10 - top side.

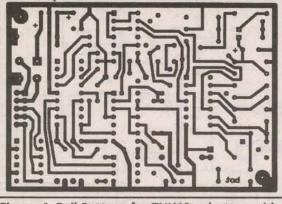


Figure 4. Foil Pattern for THX10 - bottom side.

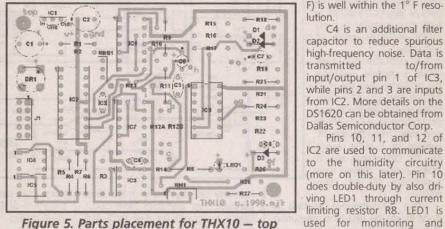


Figure 5. Parts placement for THX10 - top side of PC board.

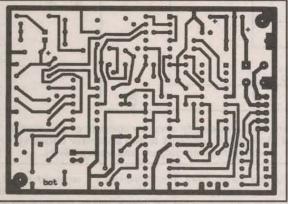


Figure 4a. Foil Pattern for THX10 - bottom side (inverted).

Program T_H_X10.BAS written in PBASIC for BASIC STAMP I

For programmed PIC16C58A-04, email mkeryan@pobox.com

SYMBOL Pulses = B9 SYMBOL I = B10 SYMBOL J = B11 SYMBOL ABit = B11 SYMBOL V0 = W1

SYMBOL V1 = W6

GOSUBS

8 bit register for counting pulses index for loop

temporary variable bit sent to relays

'pulse width for applied voltage to hum. sensor
'W1 overlaps B2 and B3
'pulse width for response voltage from hum. sensor
'W6 overlaps B12, B13 which are used during

spurious signals that could cause strange reactions. IC2, a programmed Microchip 16C58A PIC chip, uses the other lines to communicate with the temperature sensor, the humidity circuitry, and the

Pins 6, 7, and 8 are used to communicate to IC3, a Dallas DS1620 thermometer IC. This chip contains a builtin temperature sensor and digital circuitry that outputs the data in 0.5° C increments; this precision is approx. 1° F.

Typical error for a normal

environment (about 0 to 120°

F) is well within the 1° F reso-

capacitor to reduce spurious

high-frequency noise. Data is

input/output pin 1 of IC3,

while pins 2 and 3 are inputs

from IC2. More details on the

DS1620 can be obtained from

IC2 are used to communicate

to the humidity circuitry

(more on this later). Pin 10

does double-duty by also dri-

ving LED1 through current

limiting resistor R8. LED1 is

debugging, and as a human

Pins 10, 11, and 12 of

Dallas Semiconductor Corp.

C4 is an additional filter

to/from

X10 interface.

lution

transmitted

Dallas DS1620 Digital Temperature IC
Figaro NH-03 Humidity sensor and associated
circuitry giving a variable width pulse
single Led, used to display data
two relays, one for on-bit, one for off-bit
these control an X-10 control interface

The system grabs either temperature (from a digital temperature IC) or humidity (from a linear humidity-dependent resistive sensor) alternately every 5 minutes. Each one is updated every 10 minutes. 'The display is a single Led which blinks the appropriate number of times to count out each digit of the temperature or humid. data. Captured data is output to the X-10 controller as a series of 8 on or off bits. Temperature data is in deg. F., Humidity sent via 'X-10 is % relative humidity, with the last bit set (+128), so that receiving program monitoring X-10 line can tell which is which.

input/output pins SYMBOL RST = 0 SYMBOL CLK = 1 SYMBOL DQn = 2 SYMBOL DQp = pin2 SYMBOL RelayOn = 3 SYMBOL Led = 4 SYMBOL RHget = 4

Copyright 1998 Mike Keryan

input

input output

output

Interfaces:

SYMBOL RHon = 5 SYMBOL RHin = 6 SYMBOL RelayOff = 7

PINO is reset for DS1620 PIN1 is clock for DS1620

PIN2 is data i/o for DS1620

PIN2 is data to for DST020 PIN2 for inputting, outputting a bit PIN3 is relay output for on state PIN4 is output to Led PIN4 also used to switch between:

0 = applied voltage measured I = response voltage measured PIN5 high activates RH circuitry

PIN6 is input pulse for RH PIN7 is relay output for off state

data to DS1620; W0 overlaps B0, B1

'——variable storage SYMBOL DSout = W0 SYMBOL DSin = W0 SYMBOL DSDat = W0 SYMBOL BitOut = BIT0 SYMBOL Bitln = BIT8 SYMBOL SignBit = BIT8

and BITO-BIT7 data from DS1620; data in DS format; and BIT8-BIT15 output data one bit at a time input data one bit at a time data is negative (deg C) when this bit is set

8 bit counter for 2.3 second increments

SYMBOL CountSec = B4 SYMBOL WhichOne = B5 SYMBOL HumiData = B6 humidity, % RH temperature, deg F SYMBOL TempData = B6 SYMBOL LedData = B6 data to pulse out on LED

SYMBOL Unused = B7 SYMBOL DataOut = B8

1 = temperature, 0 = humidity

' data to send to relays

-constants SYMBOL WConfig = \$0C SYMBOL CPU = %10

SYMBOL OneShot = %0 SYMBOL StartC = \$EE SYMBOL RTemp = \$AA %01

LOW RST Pulses = 3

Humid:

code to write to configuration register configuration bit for thermometer mode ' configuration bit for one conversion only code to start conversion

code to read temperature out of DS1620 initialize the DS1620 chip's EEPROM at power-up

LOW RST HIGH CLK deactivate DS1620 initially high per specs PAUSE 2000 DSout = WConfig let everything stabilize write configuration GOSUB ShiftOut to DS1620 DSout = CPU + OneShot thermometer in 1-shot mode GOSUB ShiftOut to DS1620 deactivate DS1620 send 3 long blinks GOSUB BlinkLed to tell its on and working

continually loop between here and end

WhichOne = WhichOne + 1 & 1 IF WhichOne = 1 THEN Temper 'counts 1, 0, 1, 0, 1, ...

get humidity data when WhichOne = 0

HIGH RHon PAUSE 2000 PULSIN RHin, 0, V0 IF V0 < 10 THEN Humid HIGH RHget PAUSE 1000 PULSIN RHin, 0, V1

turn on humidity circuitry wait till stable get pulse width for V0 (applied) eliminate glitches

switch from applied to response

LOW RHget 'get pulse width for V1 (response)
LOW RHon 'shut down V1 output
'shut down humidity circuit
HumiData = 140 * V1 / V0 + 61 / 2 '% relative humidity
DataOut = HumiData + 128
GOTO Relays

interface, but is not needed for operation otherwise.

Pins 9 and 13 are used as outputs to the X10 interface. A high (+5 volt) signal on pin 9 is used to send an 'on' signal to the X10 transmitter. A high signal on pin 13 sends an 'off' signal to the transmitter. The lines are kept low when not really sending signals by resistors R4 and R6. Resistors R5 and R7 limit the current to the light-emitting diodes in optoisolators IC4 and IC5. The outputs of these two ICs are NPN transistors that either conduct (send 'on' or 'off' signals to the X10 transmitter) when the LEDs are conducting, or are open circuits when no current

100%

72

80

108

133

166

passes through the diodes. The X10 interfacing is explained in more detail in the second part of this article.

The Humidity Circuit

Refer to Figure 2 to understand how the humidity circuit works. It is built around a relative humidity sensor, RH1, an NH-03 from Figaro USA, Inc. It contains two humidity-sensitive elements made from a stable high polymer impregnated in porous ceramic, and two printed NTC thermistors. The elements are manufactured so that when an AC voltage of about 1 volt AC/approximately 1000 Hz is applied to the input (across pins

TABLE 4 LIEAT INDEV TABLE

1 and 3), an output AC voltage is presented (across pins 1 and 2) so that this output AC voltage is proportional to % relative humidity.

The linear, temperature-compensated output greatly reduces the problems that would be present for exponential-type outputs normally found with these types of sensors. However, there are two problems that present themselves: that of the AC input/output and the calibration of the AC signals.

AC voltage is required for input the humidity sensor. Any DC applied to the sensor will cause permanent damage to the sensor element and render it useless.

Therefore, a simple DC resistance circuit is out of the question. However, AC circuits are relatively difficult to regulate. A 10% deviation in the input signal would translate to an error of 10% or more. A self-calibration technique is used to get around these problems.

Two sections of a CMOS NAND gate (IC6-A and IC6-B) are used to create a 5-volt squarewave generator. Pin 6 is used to gate the oscillator; when it is high (+5 volt), the circuit oscillates, while when it is low (0 volt), there is no oscillation. This gate is controlled by the CPU pin 11 (signal labeled 'RHon.' The R9-C5 combination sets the rate of oscillation.

For the part values shown, it is approximately 1 KHz. Therefore, the output at pin 3 ('P-a' on Figure 2, pt 'a' on the PC board) is a 5-volt, 1-KHz gated squarewave. C6 is used to translate this from a [+5V to 0V] signal to a [+2.5V to -2.5V] (true AC) signal. It is reduced to a 1-volt signal [+0.5V to -0.5V] by the divider made up of resistors R11 and R12. This 1-V 1-KHz AC signal can then be applied to the humidity sensor.

IC7 (a CMOS quad bilateral switch) and gate IC6-C (used as an inverter) form a switch that isolates the humidity sensor when the circuit is not really measuring humidity. They also are used to switch either the input or the output to the measuring circuitry that follows it. When 'RHon' is high (+5V), the 1-V 1-KHz AC signal is applied to the input to the sensor, and an output is sent to

feel.					Air Tem	perature	e, deg. F.				
	70	75	80	85	90	95	100	105	110	115	120
Relativ					Heat In	dex: App	arent Te	mperatu	re		
0% 10% 20% 30% 40% 50% 60% 70% 80% 90%	64 65 66 67 68 69 70 70 71 71	69 70 72 73 74 75 76 77 78 79	73 75 77 78 79 81 82 85 86 88	78 80 82 84 86 88 90 93 97	83 85 87 90 93 96 100 106 113 122	87 90 93 96 101 107 114 124 136 150	91 95 99 104 110 120 132 144 157	95 100 105 113 123 135 149	99 105 112 123 137 150	103 111 120 135 151	107 116 130 148

```
get temperature data when WhichOne = 1
                                                                                                      GOSUB BlinkLed
Pulses = Pulses * 100
Temper:
                                                                                                                                    blink that many hundreds
                                        code to start a temp. conversion to DS1620
          DSout = StartC
GOSUB ShiftOut
                                                                                                                                     either 0, 100, or 200
                                                                                                      J = LedData - Pulses
Pulses = J / 10
                                                                                                                                     tens and units
          LOW RST
                                         deactivate DS1620
                                                                                                                                     tens only
          PAUSE 2000
                                         wait for conversion to end
                                                                                                      GOSUB BlinkLed
                                                                                                                                    blink that many tens
                                                                                                                          units only blink that many ones
                                         and additional second
                                                                                                      Pulses = J // 10
GOSUB BlinkLed
                                        code to get the temperature to DS1620
          DSout = RTemp
          GOSUB ShiftOut
                                                                                                        -loop consumes 5 minutes, mostly in low-power mode
            read data from DS1620 chip
                                                                                            Loop5min:
                                                                                                                                              about 5 minutes per loop
low power for 2.3 seconds
          INPUT DQn
                                         make pin an input
                                                                                                      FOR CountSec = 1 TO 130
          FOR I = 1 TO 9
                                         for 9 bits
                                                                                                                SLEEP 1
                   DSin = DSin / 2
LOW CLK
                                                                                                      NEXT CountSec
                                        'shift right 1 bit
                                         falling clock triggers DS1620 get the data bit
                                                                                                      GOTO Loop
                                                                                                                                              redo everything
                    Bitln = DQp
                    HIGH CLK
                                         preset clock high
          NEXT I
                                                                                                         send data to DS1620 chip
                                                                                            ShiftOut:
          LOW RST
                                                 deactivate DS1820
                                                                                                      HIGH RST
OUTPUT DQn
FOR I = 1 TO 8
                                                                                                                                               activate DS1620
         IF SignBit = 0 THEN Skip
DSDat = DSDat I $FE00
                                                 this means neg. deg. C make 16-bit 2's compl.
                                                                                                                                               make pin an output
                                                                                                                                               for 8 bits
Skip:
                                                                                                                LOW CLK
                                                                                                                                               preset clock low
                                                                                                                DQp = BitOut
HIGH CLK
          TempData = DSDat * 9 + 325 / 10 'convert to deg. F
                                                                                                                                               data bit to DS1620
                                                                                                                                               rising clock triggers DS1620 shift right for next bit
          DataOut = TempData
                                                                                                                DSout = DSout / 2
                                                                                                      NEXT I
            -send data to relays
Relays:
                                                                                                      RETURN
                                                 ' for 8 bits
                    ABit = DataOut & 1
                                                 'lowest bit
                                                                                                         -blink the led a certain number of times
                   IF ABit = 1 THEN HiBit
HIGH RelayOff
GOTO RelayDelay
                                                                                            BlinkLed:
                                                                                                      HIGH Led
LowBit
                                                  pulse for off state relay
                                                                                                                                               turn on Led
                                                                                                                                               at least a short blink
                                                                                                      IF Pulses = 0 THEN DoneBlink
FOR I = 1 to Pulses
HiBit:
                                                                                                                                               for zero count, skip loop
                    HIGH RelayOn
                                                  pulse for on state relay
                                                                                                                                               do how many times
RelayDelay:
                                                                                                                HIGH Led
                                                                                                                                               turn on Led
                    PAUSE 500
                                                  0.5 second on time turn off
                                                                                                                PAUSE 500
                                                                                                                                               wait 0.5 second
turn off Led
                    LOW RelayOff
                                                                                                                LOW Led
                                                                                                                PAUSE 500
                    LOW RelayOn
                                                                                                                                               wait 0.5 second
                                                  both relays
                    PAUSE 1500
                                                  1.5 second off time
                                                                                                      NEXT I
                    DataOut = DataOut / 2
                                                                                            DoneBlink
                                                 'shift to next bit
          NEXT I
                                                                                                      LOW Led
                                                                                                                                              'turn off Led
                                                                                                      PAUSE 1000
                                                                                                                                               wait a second
                                                                                                      RETURN
            -display temperature by blinking led
Display:
         Pulses = LedData / 100 'hundreds
```

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the rest of the circuit. However, signal 'RHget' (from the CPU pin 10) is used to create a SPDT switch so that the output via pin 10 of IC7 is either the input to the sensor (when 'RHget' is high, the AC signal is passed from pin 2 to pin 1 to pin 4 to pin 3 to pin 11 and then to pin 10) to measure the 'control' signal, or the output of the sensor (when 'RHget' is low, the AC signal is passed through pin 2 through the sensor from its pin 3 to pin 2, to IC7 pin 8 to pin 9 to pin 11 and then to pin 10) to measure the 'test' signal.

The result of all of the above: when 'RHon' is high and 'RHget' is low, the output 'P-c' is the control signal (the input to the sensor), which, at that point, is the 1-V AC signal attenuated slightly by passing through three sections of IC7. When 'RHon' is high and 'RHget' is also high, the output 'P-c' is the test signal (the output from the sensor), which is an AC signal, typically less than 1-V AC and directly proportional to % RH; this signal is also attenuated slightly by passing through three sections of IC7. The CPU then measures two signals: the control signal and the test signal.

Software inside the CPU's program divides the result from the test by the result from the control. This effectively cancels out any effects of voltage loss through IC7, deviations from 1 KHz, deviations from 1-VAC, deviations in the trianglewaves or amps (see below), etc. It completely eliminates the need for any calibration whatsoever.

The rest of the circuit is used to create a signal that the CPU can measure that is in some way directly proportional to the level of AC voltage at 'P-c.' In this case, it is a pulse width which the CPU measures. The signal at 'P-c' is an AC 1-KHz squarewave that varies from approx. 1-V (for 'control' or for 100% RH 'test') to nearly 0-V (for about 30% RH 'test'). The amplifier IC8-A and resistors R14, 15, 16, 17, and D1 rectify the AC signal and amplify it to more measurable levels. D2, C7, and R19 filter it so that the signal at 'P-e' is a DC signal that is approximately 2.5V maximum, about 0.5V minimum,

IC8-C and IC8-D and associated components (R20, 21, 22, 23, and 24, and C8) form a precision trianglewave generator, with a frequency of about 125 Hz. It also is gated (turned on) by a high level of 'RHon.' The output of the trianglewave is dropped a fraction of a volt through D3, so that the high tip of the triangle is at about 2.9V, while the low tip is about 0.4V, at 'P-f.' A squarewave at the same frequency of the triangle is output via pin 10 of IC8-D ('P-g'); the squarewave is high whenever the triangle is increasing (going from 0.4V to 2.9V), while it is low when the triangle is decreasing (going from 2.9V to 0.4V).

Another squarewave is created by IC8-B, used as a comparator. Here this squarewave at 'P-h' is high when-

PARTS LIST FOR **HUMIDITY-TEMPERATURE TRANSMITTER**

IC1 - 78L05 5-volt 100-mA voltage regulator integrated circuit, TO-92 package IC2 - PIC16C58A-04, Microchip 8-bit RISC microcontroller integrated circuit programmed with THX10 program (see below)
IC3 - DS1620, Dallas digital thermometer, integrated circuit, Jameco #114382
IC4, IC5 - 4N27 (NTE/ECG #3040) optoisolator: diode and NPN phototransistor integrated circuit, Jameco #144340 or Digit Key #4N270T ND.

integrated circuit, Jameco #144240 or Digi-Key #4N27QT-ND IC6 - CD4011 quad 2-input NAND gate CMOS integrated circuit IC7 - CD4016 quad bilateral switch CMOS integrated circuit

IC8 - LM3900N or CA3401N quad current-mirror op-amp integrated circuit BR1 - W02G full wave bridge rectifier, 4 lead molded 200-PRV 1-Amp, Jameco #103018 or Digi-Key W02G-ND D1, D2, D3 - 1N4148 or 1N914 silicon switching diode 75-PRV 10-mA

LED1 - Light emitting diode, red

(All resistors are 1/4 watt, 5% units unless noted otherwise) R1, R2, R4, R6, R11, R13, R15, R16, R27 - 10,000-ohm

R3 - 1000-ohm R5, R7, R8 - 470-ohm R9 - 47,000-ohm

R10, R17, R18, R20, R23, R25, R26 - 1.0-megohm R12A, R12B - 5100-ohm (see text) R14 - 200,000-ohm

R19, R22 - 100,000-ohm R21 - 510,000-ohm

R24 - 120,000-ohm

CAPACITORS
C1 - 100-uF, 25-WVDC, electrolytic
C2 - 22-uF, 25-WVDC, electrolytic
C3, C4 - 0.1-uF, ceramic disk
C5 - 0.01-uF, 10% mylar
C6 - 10-uF, 25-WVDC, electrolytic
C7 - 1.0-uF, 25-WVDC, electrolytic
C8 - 0.0047-uF, 10% mylar

ADDITIONAL PARTS AND MATERIALS
J1 - 0.100" right angle male header 10 conductor (2X5), and matching IDC sock-

et connector (such as Jameco S-10) RES1 - 4-MHz ceramic resonator, Digi-Key PX400-ND or equivalent

RH1 - NH-03 temperature-compensated linearized-AC humidity sensor, available from Figaro USA, www.figarosensor.com (see below)
T1 - low profile transformer 115-V 60-Hz primary, 12-V @ 50-mA secondary, SPK0051200-10001 or equivalent, available from Advanced Components

Industries, www.advancedcomponents.com (see below)

Mini-controller - X10 Powerhouse Transmitter MC460 (Tech America #980-0213, Home Automation Systems www.smarthome.com #4030), or Home Controls Inc. www.homecontrols.com #XT460X) or similar products by Stanley (Home Automation Systems #4031) or RadioShack #61-2677c (see text)

PC Interface - X10 Activehome CM11A (Home Automation Systems www.smarthome.com #1140), also available as part of X10 home automation kit at RadioShack stores, Home Controls Inc. www.homecontrols.com #XTCK11A, etc. (see text) etc. (see text)

IC sockets, PC board (see below), suitable enclosure, wire, hardware, PC and

Note: The following items are available from M. Keryan, 207 Baucom Park Dr., Greer, SC 29650: Preprogrammed IC2 and 3-1/2" diskette with X10 monitoring software, circuit board layout, etc., \$15.00; Etched and drilled double-sided PC board, \$20.00; RH1 humidity sensor, \$14.00; T1 transformer \$10.00. Quantity discounts of 20% for 3 or more of same items. Please include \$5.00 shipping and handling per order (\$10.00 for international orders), check or money order only in US funds. SC residents add 5% sales tax. Source code for PIC controller and for PC monitoring available.

Michael J. Keryan — 207 Baucom Park Drive — Greer, SC 29650 (864) 244-4175 — mkeryan@pobox.com

ever the voltage of the trianglewave is less than the DC level at 'P-e.' The two squarewaves are gated by IC6-D NAND gate to form a pulse, that is at OV only when the trianglewave is increasing and is at a lower voltage than the DC voltage at 'P-e.' The width of this negative pulse is therefore directly proportional to the DC voltage at 'P-e' and thus also proportional to the AC voltage at 'P-c.

The humidity circuitry appears quite complex, as is its explanation. However, it uses three extremely inexpensive ICs and a handful of resistors, capacitors, and diodes. It is designed so that the results are virtually independent of any minor deviations in parts values, voltages, or frequencies. The results are almost totally defined by the precision and accuracy of the humidity sensor itself, and the cost of the circuitry of Figure 2 is also almost totally defined by the cost of the sensor.

Parts and Construction

Except for the oscillator of the PIC CPU, no very high frequencies are involved, and voltages and currents are low. Therefore, any type of circuit construction (breadboarding, wire wrapping, etc.) will work fine. However, to keep the circuit small and to avoid wiring errors, a printed circuit is recommended. Foil patterns for the top and bottom of a doublesided board are included if you are adept at etching your own boards. For the rest of you, PC boards can be purchased from the author (see the parts list).

A preprogrammed PIC CPU containing the THX10 program can be purchased, as well as the other hardto-get parts (see the parts list). The humidity sensor is available from the author and through Figaro; there is no substitute for this item. Other transformers can be used to deliver 12 volts to the circuit, but the part shown in the parts list is ideal for making a compact system - it is only 0.6 inch tall, allowing a very thin case to be used. You should have no trouble finding any of the other parts; sources for some of them are shown in the parts list.

The op-amp (IC8) should not be substituted. It uses current-mirror techniques, so other types of opamps will not work at all in the circuit. It is also about the least expensive op-amp you can find. For the resistors, you should stick to using 1/4 watt to ensure they will physically fit. The same goes for the capacitors; higher voltage caps will work fine, just make sure they will fit on the board. For J1, a 2x5 connector was used because a 10-pin female connector is easier to find than a fivepin connector. If you wish, use a fivepin connector installed in either of the rows on the PC board.

For R12, two 5100-ohm resistors are used in parallel to give a 2550ohm equivalent. This is close enough to the desired 2500-ohm that would give an exact 1-volt p-p AC signal. If you can find one, use a single 2500ohm 1% resistor installed in either the R12A or R12B position on the PC board. The only capacitors that are critical at all are C5 and C8. Make sure you use 10% mylar or better here to minimize timing drifts.

A red LED is specified in the parts list, but actually any color will do. You may want to splurge and get a high-brightness LED for about a dollar, instead of a standard brightness 20-cent LED. The brighter ones are easier to see from across the room.

There are no jumpers to worry about. Use IC sockets for all the ICs except the regulator, IC1. When soldering in IC1, the LED, and the diodes, take care to not overheat the leads; you may want to use a hemostat-type heatsink clamped to the leads. If you build your system like the author, you will want to stand the LED off the PCB so that it will fit into a hole drilled in the top side of the case.

Using the placement diagram, solder in all the resistors and diodes (watch the diode orientation - the banded ends all point the same way, toward the left). Similarly, for the items that are partially round but have one flat side (IC1, BR1, LED1) the flat ends all go toward the top of the board. RES1 can be oriented either way. RH1 must be oriented so that the front (the side with the two little 'M's) faces the closest edge of the PC board.

After all the parts are soldered in, inspect your work to make sure there are no solder bridges and that everything is clean and shiny (no cold solder joints). Then plug in all the ICs, making sure all pin 1s (the end with the dimple or notch) face towards the top of the board. Take the normal precautions to avoid static electricity discharges when handling the

Testing and Calibration

To test the board after construction, connect either a 12-volt (AC or DC) supply or a 9-volt battery to pins 1 and 2 of J1, with no connections to pins 3, 4, and 5 of J1. After a few seconds, you should see the LED blink three times. This indicates that the CPU and program inside it are working. After about 10 more seconds, you should see the LED blink out the temperature, in degrees F. After about five to six minutes, you'll see the LED come on for about two seconds, then after about 10 more seconds, it will blink out the humidity, in %. Try breathing directly on the humidity sensor just before it takes a reading, and notice the change in humidity.



The temperature is only half of the story.

You may be wondering how a single LED can be used to blink out this information to you in a meaningful way. It blinks in one-second intervals - 1/2 second on, 1/2 second off. One blink means 1, two blinks means 2, ... nine blinks means 9.

Between the hundreds and tens digits and between the tens and units digits, there is a longer gap, or pause. For a zero, there is a very short blink, one that is noticeably shorter than the others. For example consider a sequence like this: a very short blink - a pause - 7 blinks - a pause - 3 blinks; this is 0-7-3, or 73. The humidity is preceded by about a two-second long blink to differentiate it from temperature.

What about calibration? There isn't any. The Dallas thermometer chip (IC3) is truly digital; it sends binary data to the CPU. The humidity circuit (see section: 'The Humidity Circuit') uses a self-calibration technique. Any inaccuracies that occur are due to either the sensors themselves, or are due to their placement and the possibility that they might not be ventilated adequately.

The only thing that remains to be tested is the interface to the X10 transmitter. We'll do that when we describe how to connect the sensor board to the transmitter.

For Next Time

This concludes Part 1 of this twopart article. To this point, we have constructed a PC board that contains sensors for temperature and humidity, and a PIC CPU that processes the data and sends the data to an interface. In its current state, it is a selfcontained instrument that can communicate its findings via a LED.

Next time, we will explain how to interface this instrument to an inexpensive X10 mini-controller that transmits the data on our house power line. So, between now and then, build the sensor board and have fun watching the LED count. Later on, get the remaining parts: the mini-controller and the serial PC interface that will be used to receive the data on up to eight of the transmitters. Also make sure you have a free serial port on your PC. NV

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AR - WEST MEMPHIS - Hamfest, Eugene Woods Civic Center, 212 W. Polk. 9am-4pm. VE Exams. Talk-in: 147.150+, 444.775+. Dixie AR Group, Kellye Farris KB5RCE, 870-732-8724. E-Mail: kb5rce@media-two.com E-Mail: dixiefest@media-two.com

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SC - NORTH CHARLESTON - Hamfest. Stall High School. 8:30am-4pm.VE Exams. Charleston ARS, Jenny Myers WA4NGV, 843-747-2324. E-Mail: brycemyers@aol.com E-Mail: wa4usn@amsat.org

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FL - MIAMI - Tropical Hamboree. Fair Expo Center, S.W. 112th Ave. & Coral Way. VE Exams. Center, 5.W. Talk-in: Claim Way. Ve Exams Talk-in: 146.925, 146.76, 444.525. Dade Radio Club of Marmi, Evelyn Gauzens. 305-642-4139, E-Mail: edg@elink.net. 305-226-5346, E-Mail: wd4sfg@bellsouth.net. Web: www.hamboree.org

FEBRUARY 7

OH - LORAIN - Hamfest. Northern Ohio ARS, Mike Willemin W8EU, 440-324-4574 PA - LATROBE - Hamfest American Legion, 1811 Ligonier St. 8am-Ipm. Talk-in: 145.150 (-600). Chestnut Ridge ARC, William Demosky K3AFS, 724-539-1552

FEBRUARY 12-13-14

FL - ORLANDO - Hamfest, Northern FL Section Conv., Tim Starr AE4NJ, 407-850-9258. E-Mail: AE4NJ@aol.com Web: http://www.oarc.org/hamcat.html

FEBRUARY 13

CA - FONTANA - Inland Empire ARC Amateur Radio & Electronics Swapmeet. A B Miller High School, Bill 909-822-4138 eves

MA - MARLBOROUGH - Hamfest, Marlborough Middle School, Rt. 85. 10am-2pm. Algonquin ARC, Ann Weldon KA1PON, 508-481-4988 MI - NEGAUNEE - Swap & Shop, Township Hall. Talk-in: 147.27. Hiawatha ARA, Bob Serfas N8PKN, 906-226-9782. John Veight N8RSE, 906-228-9417

NY - WESTFIELD - Hamfest. Westfield Exempt NY - WESTFIELD - Hamfest. Westfield Exempt Volunteer Fireman's Assn., 75 Bourne St. 8am-3pm. Talk-in: 145.350 (-). Chautauqua County RAs, Eric Kroon N2PCQ, 716-595-3220. E-Mail: ekroon@netsync.net PA - OBERLIN - Hamfest. Oberlin Fire Co., Fire Hall. VE Exams. Talk-in: 146.76. HRAC 717-939-4825. E-Mail: n3njb@juno.com

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CO - BRIGHTON - Hamfest. Aurora Repeater Assn., Wayne Heinen NOPOH, 303-699-6335. F-Mail: nrclog@aol.com

IL - ROCK ISLAND - Hamfest. QCCA Expo Center, 2621 4th Ave. Talk-in: W0BXR 146.28/.88 and 146.04/.64. Davenport ARC, Kent Williams K9UQI, 309-796-0718, 4-9pm only. E-Mail: k9uqi@arcsupport.com E-Mail: k9uqi@netex press.net Web: http://www.arcsupport.com/drac OH - MANSFIELD - Mid*Winter Hamfest & Computer Show. Richland County Fairgrounds. Talk-in: call W8WE on 146.34/94. InterCity ARC, Inc., Pat Ackerman N8YOB, 419-589-7133 after 2pm EST.

FEBRUARY 20

AR - RUSSELLVILLE - Hamfest. AR River Valley AR Foundation, Margaret Alexander KCSMCS, 501-968-7270. E-Mail: ealexand@rswnet.com CA - SANTEE - ARC of El Cajon Ham, Computer & Electronic Swapmeet. Santee Drive-in. 619-561-0052

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All listing information should be sent to

Nuts & Volts Magazine **Events Calendar**

430 Princeland Court Corona, CA 91719 Phone 909-371-8497 Fax 909-371-3052

E-mail events@nutsvolts.com

Post 10209, Spring Hill Dr. between US 41 & Mariner Blvd. Talk-in: 146.715, Hernando County ARA, Ralph Wilson AF4FC, 352-754-9653. Jim Angello KE4SZP, 352-688-5214.

E-Mail: jangello@fiber-net.com Web: www.fiber-net.com/pub/hcara/index.htm NY - HORSEHEADS - Hamfest Elmira College Murray Athletic Center Domes, Rt. 14. 8am-3pm. VE Exams, Talk-in: 147,360+, ARAST, Gary Selxella N2OKU, 607-739-0134. E-Mail: arast@arast.org Web: http://www.arast.org OR - RICKREALL - Hamfest. Polk County Fairgrounds, 520 S. Pacific Hwy, W. Talk-in: 146.86-. Salem Repeater Assn. and Oregon Coast Emergency Repeater, Evan Burroughs N7IFJ, 503-585-5924 before 8pm.

E-Mail: n7ifj@teleport.com Web: http://sra.goldcom.com/sraflyer.htm TX - SMITHVILLE - Hamfest. Bastrop County ARC, Lynn Fisk K5LYN, 512-360-4809. E-Mail: kc5kfv@onr.com Web: http://www.qsl.net/kb5yae

FEBRUARY 21

CANADA - BRITISH COLUMBIA - NEW WEST-MINSTER - Hamfest, Burnaby ARC, Harry VE7HNC, 604-530-3962

MI - FARMINGTON HILLS - Swap 'n Shop, William M. Costick Activities Center, 28600 Eleven Mile Rd. 8am-3pm. Talk-in: 145.350-repeater and 146.52 simplex. Livonia ARCs, 734-261-5486. E-Mail: swap@larc.ml.org www.larc.mi.org

NC - ELKIN - Hamfest, Briarpatch δ Foothills ARCs, Jimmy Holbrook KB4GKI, 336-957-3820. E-Mail: kb4gki@aol.com Web: http://members.aol.com/kb4ghi/kb4gki.html

NY - FREEPORT - Hamfest. Armory, 63 Babylon Tripk. 8:30am-1pm. Talk-in: 146.850 (136.5 PL). LIMARC, 516-520-9311. E-Mail: hamfest@limar c.org Web: http://www.limarc.org

FEBRUARY 27

GA - DALTON - Hamfest. Dalton ARC, James an K4FLG, 706-278-0630 evenings only KY - CAVE CITY - Hamfest. Mammoth Cave ARC, 502-651-2363. E-Mail: lbrumett@glasgow ky.com Web: http://www.scrtc.blue.net/mcarc ND - BISMARCK/MANDAN - Hamfest. Central Dakota ARC, Dennis Murphy KOGRM, 701-258-6747. Web: http://www.qsl.net/cdarc VT - MILTON - Hamfest and Convention. Milton High School, Rt. 7. 8am-3pm. Talk-in: 145.15-.

RAs of Northern VT, Mitch Stern W1SJ, 802-879-6589. E-Mail: w1sj@vbimail.champlain.edu Web: http://www.ranv.together.com

FEBRUARY 27-28

OH - CINCINNATI - Convention. Cincinnati Gardens, Exhibition Center. Great Lakes Div. Conv., William Tittle KA8LAY, 513-661-1861. E-Mail: gldivconvention@juno.com

FEBRUARY 28

NY - CHEEKTOWAGA - Hamfest, Lancaster ARC, Luke Calianno N2GDU, 716-634-4667. E-Mail: Icalianno@freewwweb.com Web: http://hamgate1.sunyerie.edu/-larc/greaterbu ffälowinterhamf

NY - MELVILLE - Hamfest. Radio Central ARC, JoAnn Colletti N2IME, 516-399-1877. E-Mail: wo2n@li.net

OH - CIRCLEVILLE - Hamfest, Teays ARC, Roy Ulko KG8EK, 740-477-8310. E-Mail: royulk@scioto.net

OH - CUYAHOGA FALLS - Hamfest. Emidio & Sons Party Center, 48 E. Bath Rd, 8am-2pm. Cuyahoga Falls ARC, Carl Hervol N8JLQ, 330-497-7047. E-Mail: carlh@pop.raex.com Web: http://www.cfarc.org/hamfest.htm

COMPUTER SHOWS

AGI Shows, 317-299-8827. E-Mail: info@agishows.com http://www.agishows.com

Blue Star Productions 612-788-1901 http://www.supercomputersale.com

Computers And You, 734-283-1754. www.a1-supercomputersales.com

Computer Central Shows 847-412-1900 & 1-888-296-6066. E-Mail: compcent@megsinet.net www.computercentralshows.com

Five Star Productions 810-890-0988 E-Mail: jeff@fivestar www.fivestarshows.com

Georgia Mountain Productions 706-838-4827. E-Mail: gamtnpro@blrg.tds.net georgiamountain.com

PA - CASTLE SHANNON - Hamfest. VFD Memorial Hall, Library Rd. (Rt. 88), 8am-3pm, Talk-in: 146.955- N3RNX repeater, N3SH ARC, Steve Lane W3SRL, 412-341-1043, E-Mail: slane@adelphia.net

Web: http://www.hky.com/~sanfordb/index.htm VA - ANNANDALE - Hamfest. N. VA Community College, 8333 Little River Tpke. (Rt. 236). VE Exams. Talk-in: 146.91 (-) & 146.685 (-). Vien Wireless Society, Mike Tola K3MT, 703-757-5021. E-Mail: k3mt@erols.com Web: http://www.erols.com/k3mt/vws

WV - FAYETTEVILLE - Hamfest, Plateau ARA, Juddie David Burgess KCBCON. E-Mail: kcBcon@ usa.net Web: http://www.geocities.com/Cape Canaveral/Launchpad/4842

MARCH 1999

MARCH 5

MO - ST. LOGIS - Hamfest. Amateur Radio Auction, Bill Schmidt WA0JCO, 314-544-1515

MARCH 5-6

MS - PASCAGOULA - Hamfest. Jackson County Fairgrounds, Civic Center. Fri: 5pm-9pm, Sat: 8am-3pm. VE Exams. Talk-in: W5WA 145.110. Jackson County ARC, Charles F. Kimmerly, 228-826-5811

NE - NORFOLK - State Convention. Fred Wiebelhaus NOVLX, 402-379-1929. E-Mail: dfwlebel@sufia.net Web: http://members.aol.com/davidn0xbn/evarc.html

MARCH 6

CA - SANTEE - ARC of El Cajon Ham, Computer & Electronic Swapmeet. Santee Drive-in. 619-561-0052

NJ - PARSIPPANY - Hamfest. PAL Building, Smith Field, Rt. 46 & Baldwin Rd. VE Exams. Splitrock ARA, Mark Turner KB2VKO, 973-347-3195 or 1-888-511-7272. E-Mail: mlturner@bell atlantic.net Web: http://ham.hsix.com/sara

TN - KNOXVILLE - Hamfest. Kerbela Temple 315 Mimosa Ave. 8am-4pm. Talk-in: 144.83/145.43 or 146.52 simplex. Kerbela ARS, Paul Baird K3PB, 423-986-9562

Gibraltar Trade Center, Inc. 734-287-2000. Taylor, Ml. Gibraitar Trade Center, Inc. 810-465-6440. Mt. Clemens, Ml.

MarketPro, Inc., 201-825-2229 http://www.marketpro.com

MarketPro, Inc., 301-984-0880. E-Mail: md@marketpro.com http://marketpro.com

Narisaam Computer Show 770-663-0983. E-Mail: narisaam@aol.com Web: http://www.shownsale.com

Northern Computer Shows 978-744-8440 E-Mail: inquiries@ncshows.com Web: ncshows.com

Peter Trapp Computer Shows, 603-272-5008. Web: www.petertrapp.com

FL - NEW PORT RICHEY - Hamfest, Fred K. Marchman Technical Educational Center: Sat: 8am-5pm, Sun: 8am-3pm. Talk-in: 146.670 or 145.330. Gulf Coast ARC, Rick Brown KF4GXS, 813-842-2127, E-Mail: richar@gte.net

MARCH 7

FL - ZEPHYRHILLS - Hamfest. Zephyrhills ARC, Ernie Vanselow KD4VRV, 813-783-8389. E-Mail: kd4vrv@ate.net

MA - WESTFIELD - Hamfest. Westfield South Middle School. MTARA, Jim Allen N1RUT, 413-568-1175 days, 413-536-5182 eves. E-Mail: Jim.Allen@the-spa.com Web: http://www.mtara.org

Web: http://www.mtara.org
NY - LINDENHURST - Hamfest. Great South Bay
ARC & Suffolk County RC, 516-422-9594.
E-Mail: ka2d@li.net Web: http://www.gsbarc.org
WI - WAUKESHA - Swapfest. Waukesha County Expo Center. 8am-2pm. VE Exams. Talk-in: 146.82 PL 127.3. SEWFARS, John Breecher

MARCH 13

N9NWN, 414-835-7035

AZ - SCOTTSDALE - Hamfest. Scottsdale ARC, Roger Cahoon KB7ZWI, 602-948-3548

CA - FONTANA - Inland Empire ARC Amateur Radio & Electronics Swapmeet. A B Miller High School. Bill 909-822-4138 eves CA - LINDA - Hamfest. Yuba Sutter ARC, Clara KC6JPP, 530-742-2674. Ron W6KJ, 530-674-8533

FL - EAST ENGLEWOOD - Hamfest. Tringali Community Center, SR 776. Talk-in: 146.700. Englewood ARS, J.R. House K9HUY, 941-475-3005. George KA4JKY, 941-697-3445,

E-Mail: gshreve@ewol.com Web: http://www.finet.com/-crosby/ears/index.html FL - SEBRING - Hamfest. Highlands County ARC, Phyllis Dibble KD4CQG, 941-465-8176. E-Mail: dibble@strato.net

Web: http://www.strato.net/~hamradio KY - CAVE CITY - Hamfest. Mammoth Cave ARC, Larry Brumett KN4IV, 502-651-2363. E-Mail: lbrumett@glasgow-ky.com Web: http://www.scrtc.blue.net/mcarc

MO - KANSAS CITY - Hamfest. Ararat AR Shrine Club, Steve Dowdy WJ0I, 816-941-3392. E-Mail: sdowdy@qni.com

ND - WEST FARGO - Hamfest. Fairgrounds. 8am-3pm, VE Exams. Talk-in: 146.76-. Red River Radio Amateurs, Mark Kerkvliet KG0FR, 701-282-4716. E-Mail: mbkerk@worldnet.att.net

Web: http://www.rrra.org
NJ - WEST ORANGE - Hamfest, High School, 600 Pleasant Valley Way. 8:30am-1pm. Talk-in: 146.415 +1.0 85.4T, 224.480 -1.6 no tone, 447.875 -5.0 156.7T, 146.520 simplex. IRAC, Jim Howe N2TDI, 973-402-6066. E-Mail: n2tdi@juno.com

WA - PUYALLUP - Hamfest. Mike & Key ARC,

Michael Dinkelman N7WA, 253-631-3756 or 425-867-4797. E-Mail: mwdink@eskimo.com

NC - CHARLOTTE - Hamfest & Computerfair. Charlotte Merchandise Mart, 2500 E. Independ ence Blvd. Mecklenburg ARS, Tim Slay WO4G, 704-382-3234 (W) or 704-948-6283 (H). E-Mail: wo4g@w4bfb.org

Web: http://www.w4bfb.org/hamfest.html
LA - RAYNE - Hamfest. Acadiana ARA, Nolen Griffith K5ARH, 318-989-9039. E-Mail: k5dpg@aisp.net

Web: http://www.acadian.net/w5ddl/

IL - STERLING - Hamfest. High School Fieldhouse, 1608 4th Ave. Talk-in: 146.25/146.85 W9MEP. Sterling-Rock Falls ARS, Lloyd Sherman KB9APW, 815-336-2434

E-Mail: Isherman@essexl.com IN - INDIANAPOLIS - Hamfest. State Fairgrounds. Morgan County Repeater Assn., Dennis Bauernfiend WB9ZNZ, 317-996-3782. E-Mail: dennis.bauernfiend@dfas.mil Web: http://www.eb1.com/mcra OH - CONNEAUT - Hamfest, Human Resources Center, 327 Mill St. Conneaut ARC, Jack Marttila KA8TUU, 440-593-3353

FL - FT. WALTON BEACH - Hamfest. Playground ARC, Clyde Gowdy KE4FLC, 850-244-0624. E-Mail: parcfest@aol.com

ME - LEWISTON - ME State Convention Androscoggin ARC, Ivan Lazure N1OXA, 207-784-

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OK - TULSA - OK State Convention. Maxwell Conv. Center, 700 S. Houston Ave. Talk-in: 145.11 6 443.85. Green Country Hamfest Assn., Merlin Griffin WB5OSM, 918-622-2277. E-Mail: info@GreenCountryHamfest.org Web: http://www.GreenCountryHamfest.org

AR - JONESBORO - Hamfest. Jonesboro ARC, Mike Conley KC5ISI, 870-931-9957. Evelyn Castleberry N5DSY, 870-932-1660. E-Mail: isnodgra@insolwwb.net

CA - SANTEE - ARC of El Cajon Ham, Computer & Electronic Swapmeet. Santee Drive-in

FL - STUART - Hamfest. Martin County ARA, PL - STUART - Hamfest, Martin County ARA, David Millard KE4AMW, 561-288-7100 MI - MARSHALL - Hamfest. Southern Michigan ARS & Marshall HS Photo Electronics Club, Wes Chaney N8BDM, 616-979-3433. E-Mail: n8bdm@voyager.net

TX - MIDLAND - Hamfest Midland ARC Reverly Harwood KC5BNT, 915-686-1841. E-Mail: shamrock@apex2000.net Web: http://www.lxnet/edge/mldswap.htm

CT - SOUTHINGTON - Hamfest. Southington ARA, Chet Bacon KA1ILH, 860-628-9346. E-Mail: hcbacon@connix.com Web: http://www.connix.com/~hcbacon/sara.html NC - KINSTON - Down East Hamfest, Lenoir County Fairgrounds, Hwy. 11 S. 8am-3pm. Doug Burt W4OFO, 252-524-5724 NJ - TRENTON - Hamfest. Tall Cedars of Lebanon picnic grove, Sawmill Rd. Talk-in: 146.67-. Delaware Valley Radio Assn., Darryl Foyuth N2JVP, 609-882-2240 E-Mail: n2jvp@amsat.org Web: www.slac.com/w2zq OH - MAUMEE - Hamfest. Lucas County Recreation Center, 2901 Key St. 8am-2pm. Talk-in: 147.27+ or 442.85+. Toledo Mobile Radio Assn., Paul Hanslik N8XDB, 419-243-3836. Web: http://www.tmrahamradio.org WV - CHARLESTON - Hamfest. Charleston Area Hamfest & Computer Show, Jimmie Hewlett WD8MKS, 304-768-1143

Rollinson KB1CNW, 860-928-2456. E-Mail: paulrollinson@worldnet.att.net
CT - WATERFORD - Auction, Waterford Senior

Center, Rt. 85. Talk-in: 146.730-. RAS of Norwich, Tony Griggs AA1JN, 860-859-0162. Mark Venable N1RSK, 860-572-9380, E-Mail: mvenable@99 main.com Web: www.ims.uconn.edu/-rason
IN - MICHIGAN CITY - Hamfest. High School,
8466 W. Pahs Rd. 8am-1pm. Michigan City ARC,
Inc., Ron Stahovlak N9TPC, 219-325-9089
NY - NEWARK - Hamfest. Drumlins ARC, E-Mail:

TX - WEATHERFORD - Hamfest, ARC of Parker County, Elizabeth Hunkele N5ONE, 817-594-1700. E-Mail: eliz@mesh.net

MD - TIMONIUM - Maryland State Convention. Sharon Dobson N3QQC, 410-HAM-FEST (Box 3772), 1-800-HAM-FEST (Box 3772). E-Mail: n3qqc@amsat.org Web: http://www.gbhc.org

CA - SANTA ANA - Swapmeet. ACP parking lot. Mary Russo 714-558-8813 FL - LEESBURG - Hamfest. Lake ARA, Paul Branch K3NON, 352-343-8729. John Wentz W8HFK, E-Mail: w8hfk@aol.com NH - HENNIKER - Hamfest. Contoocook Valley

RC, Jock Irvine N1JI, 603-428-3476 ext. 256 OH - MADISON - Hamfest. Lake County ARA, Roxanne, 440-256-0320

APRIL 1999

OK - MOORELAND - Hamfest, Tri-State AR Group, Duane Henderson KC5NID, 580-994-2223. E-Mail: kc5nld@pldi.net

CA - SANTEE - ARC of El Cajon Ham, Computer & Electronic Swapmeet. Santee Drive-In. 619-561-0052

GA - ATLANTA - Southeastern VHF Conference. Southeastern VHF Society, Dick Hanson K5AND, 770-844-7002, E-Mail: k5and@prestique.net Web: http://www.svhfs.org.svhfs

CA - FRESNO - Int'l DX Convention, Gordon Girton W6NW. E-Mail: gordon@svpal.org

Continued on page 59

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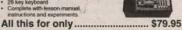
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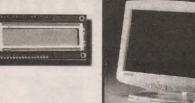
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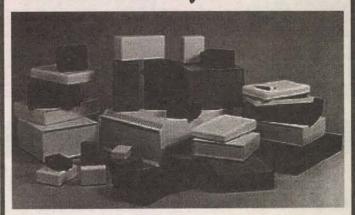
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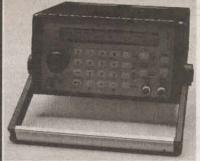
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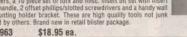
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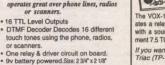
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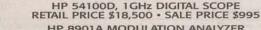
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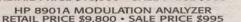
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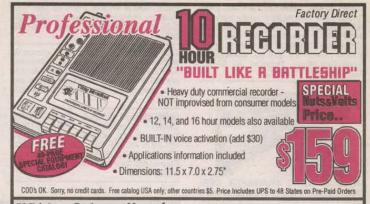












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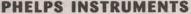
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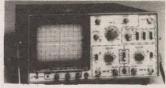
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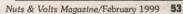


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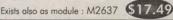


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NC - MORGANTON - Hamfest & Computer Fair.
Burke County Fairgrounds, Hwy. 181N (Exit 100
Eastbound, Exit 105 Westbound I-40). 8am-5pm.
Talk-in: 147.15 (K4VLY repeater). Catawba Valley, Tom Tayler, 704-433-6205.

E-Mail: kc4qpr@vistatech.net WA - SPOKANE - Hamfest, Lilac City ARC. Warren Kelsey KJ7BB, 509-534-8443

NC - RALEIGH - RARSFest. State Fairgrounds, Jim Graham Bldg. 8am-4pm. Raleigh ARS, Wilbur Goss WD4RDT, 919-266-9883. E-Mail: k4hfi

WI - MADISON - Hamfest, Madison Area Repeater Assn., Paul Toussaint N9VWH, 608-245-8890. E-Mail: n9vwh@hotmail.com

AL - ALBERTVILLE - Hamfest. Marshall County ARC, Buddy Smith KC4URL, 256-593-2516. E-Mail: kc4url@airnet.net E-Mail: kc4url@airnet.net CA - SANTEE - ARC of El Cajon Ham, Computer

& Electronic Swapmeet. Santee Drive-in 619-561-0052

ID - IDAHO FALLS - Hamfest. Eastern Idaho CIHF Society, Jay Greenburg WA4VRV, 208-524-1388. E-Mail: wa4vrv@srv.net

Web: http://www.srv.net/~wa4vrv/hamfest.htm KY - MURRAY - Hamfest. Murray State University ARC, Pat Compton KF4FMZ, 502-762-6433. E-Mail: patrick.compton@murraystate.edu Web: http://mursukv.edu/clubs/msuarc/hamfest.htm MN - BLAINE - Hamfest. Robbinsdale ARC, Jerry Dorf NOFWG, or Harriet Johanson 612-537-1722 E-Mail: jerryd@skypoint.com

MO - JOPLIN - Hamfest. Joplin ARC, Ray Brown KBOSTN, 417-781-4967. E-Mail: raybrown@ipa.net

Web: http://www.joplin-arc.org
OK - LAWTON - Hamfest. Lawton Ft. Sill ARC Bob Morford KA5YED, 580-355-6120 or 580-353-8074

CT - HARTFORD - 1999 Trinity College Fire-Fighting Home Robot Contest. Trinity College campus. Jake Mendelssohn, 190 Mohegan Dr., West Hartford, CT 06117. F-Mail: JMENDFL141@AOL.COM

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MA - CAMBRIDGE - Flea Market. Kendall Square area. MIT. Nick Alternbernd KA1MQX, 617-253-3776. Web: http://web.mit.edu/w1mx/www/ swapfest.html

PA - MONROEVILLE - Hamfest. Two Rivers ARC, Michael Kowalcheck, Jr. KV3L, 412-751-9657

AR - LITTLE ROCK - Hamfest, Jim Blackmon K5VZ, 870-246-7833 H, 870-246-6734 W. E-Mail: Irhamfest@usa.net Web: http://www.aristotle.net/-ares/hamfest/

APRIL 24 AR - BENTONVILLE - Hamfest. Benton County Radio Operators, Betty Weiberg NOXWQ, 417-435-

IA - DES MOINES - Hamfest. Des Moines RAA, Duane Bower WB0UCY, 515-287-6542 NJ - HARMONY - Hamfest. Warren County Farmers Fairgrounds, Rt. 519 N. 8am-2pm. VE Exams. Talk-in: 147.375+ 146.730-. Cherryville RA II, Inc., Randy Vance N2MQZ, 908-788-4080 or 908-454-4370. E-Mail: n2mqz@aol.com

Web: mailto://w2cra@gsl.net NM - ALBUQUERQUE - Hamfest. Albuquerque ARC & AR Caravan Club, Chuck Opdyke KC5GA, 505-858-0306. E-Mail: n5oqj@worldnet.att.net

VA - CHESAPEAKE - Hamfest. Chesapeake AR Service, Jim Cannon KF4RQQ, 757-382-0193. Web: http://www.gsl.net/cars

WA - VANCOUVER - Hamfest, Clark Co. ARC, Luther Brisky KC7KVL, 360-896-8909 or 360-254-5082. E-Mail: lwayne@e-z.net Web: http://www.w7aia.org

FL - GAINESVILLE - Hamfest. Gainesville ARS H. Walter Johnston W4TKE. E-Mail: w4tke@juno. com E-Mail: w4tke@gator.net IL - ARTHUR - Hamfest. Moultrie ARK, Ralph

ncha WC9V, 217-873-5287 or 217-543-2178. E-Mail: rzancha@one-eleven.net Web:

http://home.stlnet.com/~jhudsonl/hamfest.html IL - GALVA - Hamfest, Bill Anderson WB9TEW, 309-932-3023. E-Mail: bill@inw.net

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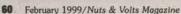
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STAMP by Lon Glazner

APPLICATIONS

Putting the Spotlight on BASIC Stamp Projects, Hints, and Tips

Storing Data With The RAMPack B

Overview

A problem commonly faced by Stamp users is how to store data that can sometimes come in overwhelming quantities. We're not talking just a few bytes here and a few bytes there. We're talking about a few hundred bytes — or more — that need to be stored for later use. If you ever wanted to store a text file, and parse the data out to some serial device, or have a string of serial data stored automatically for you, then the RAMPack B may fit the bill.

More importantly, we'll be using this month's RAMPack B (RPB) overview as a stepping stone. Next month, we'll use the serial data storage capacity of the RPB to store graphic bit-map (*.BMP) data files. These files will be downloaded directly from your PC into the RPB. Next month's article will also use the Scott Edwards Electronics, Inc., G12032 Mini Serial Liquid Crystal Display (G12032 LCD). With the RPB and the G12032 LCD, developing graphic displays becomes a relatively simple task. Some limited animation with the graphic display is also possible using these two devices in tandem.

In this article, we will start off covering some of the basic functions of the RPB, briefly discuss data conversion, and finish up with how to use the First-In-First-Out(FIFO) buffer mode to store serial data automatically. But first, an overview of electronic memory "types."

Data Memory Discussion

There are quite a few ways to store data in today's electronic devices. There are typically four areas of concern that need to be addressed when selecting a memory device. These areas are speed, volatility of memory, input/output (I/O) pins required to access the memory, and how often the memory can be written to.

For example, with serial EEPROM (Electrically Erasable PROM), such as Microchip's 24LCxx series, you gain the dual

benefits of a low count pin to access the memory and non-volatile memory (stored data is retained power With removed). EEPROM, you can usually access memory with two or three I/O pins depending on the type of memory you use. Parallax provides application notes for interfacing a BASIC Stamp to EEP-ROM. In fact, the BASIC Stamp has EEPROM on board that can be

accessed through the PBASIC READ and WRITE commands. EEPROM is usually an excellent vehicle for the storage of data in electronic designs. It is low-cost, easy-to-use, and has memory that is retained even after power is lost.

There are only three downsides to EEPROM.

There are only three downsides to EEPROM. First, EEPROM is usually only guaranteed for one million erase/write cycles. This may seem like a lot, but if you were to update a memory location every three seconds, the EEPROM could fail after only 35 days of use. Secondly, interfacing to EEPROM is not always the easiest thing for beginners to accomplish. Finally, compared to

other memory types, access time for EEPROM is considered slow. For the experienced Stamp user, the second shortcoming is of little consequence, and the third isn't entirely relevant because of the operating speed of BASIC Stamps.

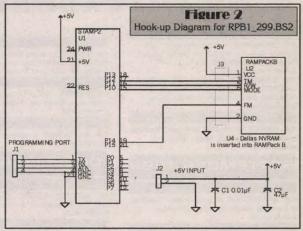
SRAM (Static RAM), on the other hand, has no limitation on how many read/write cycles it can be used for, but requires a large number of I/O pins to address memory locations. In fact, with no additional logic buffers, more than 22 I/O pins could be required. The additional problem of volatile memory (data is lost when power is removed) usually precludes SRAM from being an attractive memory storage device for Stamp-based designs. SRAM, and RAM in general, has one additional advantage of fast

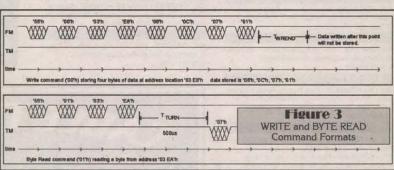
access time that makes it attractive to designers using much faster processors than the BASIC Stamp.

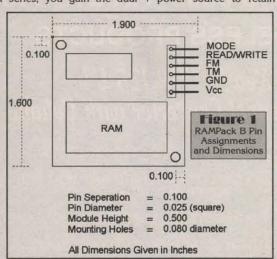
There are additional types of RAM including Dallas Semiconductor NVRAM (non-volatile RAM). NVRAM provides a back-in

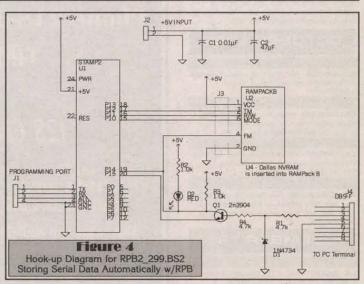
vides a back-up lithium power source to retain data in RAM when power is removed from the system. This is an example of an after-market addition to RAM that eliminates one of RAM's inherent shortcomings.

The RPB is another such attempt to delete the shortcomings of RAM-based memory. The RPB is kind of like "smart RAM." With the RPB, access to SRAM can be accomplished with a single I/O pin. The communication format used by the RPB is the very common 8N1(eight data bits, no parity, one stop bit) serial communication.

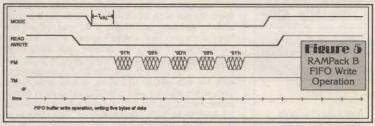








STAMP APPLICATIONS



This is the same format as is used in many devices such as serial printers, PCs, GPS receivers, and the BASIC Stamp. In the RPB, SRAM comes socketed in the module. This SRAM can be removed and replaced with NVRAM. The RPB normally comes with 8Kx8 byte SRAM. 8Kx8 byte SRAM has room to store 8,192 bytes of data. The user can replace the 8Kx8 byte SRAM with 32Kx8 byte SRAM and extend the storage capability of the RPB to 32,768 bytes of data.

I used a Dallas Semiconductor DS1230Y-150 32Kx8 byte NVRAM in the RPB used in this design. I tend to keep one of these lying around for test purposes. There is no reason that the 8Kx8 byte SRAM that the RPB is sold with can't be used for any of the functions described in this

Using the RAMPack B WRITE and **BYTE READ Commands**

To start with, we'll be taking a look at just the WRITE and BYTE READ commands of the RPB. All commands sent to the RPB must be prefaced with a \$55, or '55'hex. This is a binary '01010101', and is used by the RPB to calculate the baud rate that the Master unit is using to send data. In this design, the Master unit is a BASIC Stamp 2. For more information on the RPB data formats, I would recommend downloading the latest data sheet from "www.solutionscubed.com."

Code Listing 1 -RPB1 299.BS2

shows one example of writing and reading data from the RPB using just the WRITE and BYTE READ commands. The WRITE command discussed here should not be confused with the PBASIC WRITE command, which accesses EEP-ROM on-board the BASIC Stamp. All Solutions Cubed Mini-Mods - of which the RPB is one can communicate using the PBASIC SEROUT and SERIN commands.

In RPB1_299.BS2, part of the ASCII character set is written to the RPB with the WRITE command. These ASCII values are then read back to the BASIC Stamp 2 (BS2) using the BYTE READ command. Figure 2 can be used as a hook-up, or wiring diagram, if you want to try this yourself. This connection scheme uses two I/O pins to communicate with the RPB. You could connect the TM and FM pin of the RPB together and run this program using one I/O pin on the BS2. Multiple baud rates are used in this code example to display how the communication baud rate to and from the RPB can be changed on the fly.

The RPB WRITE command follows a simple format. Figure 3 displays the serial format in hexadecimal values. The decimal equivalents work for these values as well. The data string for a WRITE command always starts with the sync byte ('55'hex), then the command byte

('00'hex), followed by the high address byte, and low address byte, for the address location that the WRITE is to begin at. For example, to start writing data at address location 1000 ('03E8'hex), you would send '03'hex as the high address byte, and 'E8'hex as the low address byte. After this data is received by the RPB, it will store any subsequent bytes of data sequentially

SOURCES

For more information on the BASIC Stamp, contact:

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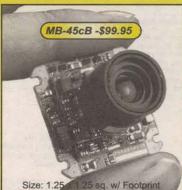
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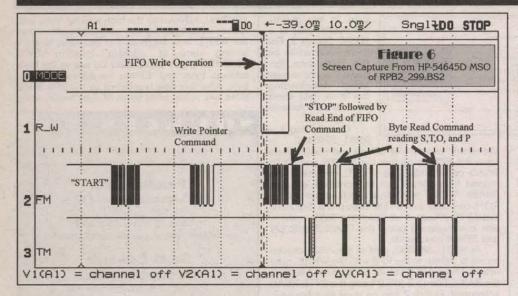
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STAMP APPLICATIONS



in RAM. The RPB will exit the WRITE subroutine if there is no data received after a period of time. The time it takes for this to occur is based on the baud rate that data is being received at. For 9600 baud, the time the FM line must remain high for a WRITE to end is roughly 2ms.

For the BYTE READ command, the RPB expects the sync byte ('55'hex), then the command byte ('01'hex), and finally the high and low address bytes for the memory location that you would like to read. The RPB will send the data byte requested on the TM line in 500us. Figure 3 displays this function with data displayed in hexadecimal format.

Storing Serial Data Automatically With The RAMPack B

While the RPB WRITE and BYTE READ commands are useful, they don't solve a very common problem Stamp users run into. It's difficult to store large amounts of serial data for later use by the Stamp. Using the circuit in Figure 4 and the RPB's FIFO mode, you can easily interface to the RPB to store serial data from a PC terminal program.

Some explanation of the circuit in Figure 4 is required. The transistor Q1 - along with D1, R1, and R4 - acts to invert and limit data signals from the PC serial port to the BS2 and RPB. This could be considered a "poor-man's" RS-232 converter. Data received at the RPB's FM pin from the PC will be at roughly TTL levels. R2 and D2 just provide a visual indication when data is being transmitted. The red LED, D2, will flash when data is present at the FM pin.

One of the trickier aspects to using the RPB FIFO mode in this configuration lies in the need to send commands to the RPB. Because the Master unit (BS2) has to share the FM pin with the serial data source (PC in this case), the BS2 must have the ability to seize the serial data line. This is accomplished by connecting the P15 (FMEN in code) of the BS2 to the emitter of Q1. If P15 (FMEN) of the BS2 is an output high (5VDC), then Q1 is effectively removed from the circuit. In this configuration, P14 (FMBS2) can be used to send commands to the RPB.

Current can flow from the emitter of Q1 to the collector with this kind of switch. So it is possible to damage an I/O pin if R1 and R4 are not large enough. This would happen if Q1 were to be turned on while its emitter was held high (5VDC) and the BS2 was outputting a logic low (OVDC). The current that the BS2 is required to sink for the circuit in Figure 4 was only 6mA. This value agreed with a SPICE simulation of the same circuit. In the lab, I reduced the values of R1 and R4 to 1.0K ohm resistors. This increased the current that the BS2 had to sink to about 30mA. If you use this circuit, I would recommend sticking with the values in Figure 4. You should also write your code to minimize the possibility of the BS2 writing to the RPB while your serial data source is sending data.

It is also necessary to give the serial data source (PC) access to the RPB. When the BS2 outputs a logic low (OVDC) at P15 (FMEN), it provides a ground path for the emitter of Q1. This effectively places Q1 in the circuit. When P15 (FMEN) is low, then P14 (FMBS2) should be configured as an input pin. P11 (R_W) and P10 (MODE) are also used to place the RPB in FIFO mode. In this application, the FIFO write operation is used to automatically store data sequentially in RAM with the RPB. Figure 5 shows the proper pin configurations for the RPB MODE and READ/WRITE pins for a FIFO write operation. Tval is the time from executing a FIFO write operation until serial data will be accepted. The

maximum time to expect here is 20us. Code Listing 2 — RPB2_299.BS2 stores data from a text terminal into the RAM residing on the RAMPack B. This routine waits for the ASCII characters "START" to be received by the BS2 before executing a FIFO write operation. Any text typed into the data terminal after the "START" characters are received will be stored sequentially in RAM. When the ASCII characters "STOP" are received, the BS2 will read the data stored in the RPB and display it via the Debug command. The RPB baud rate is set to 9600 baud just after the "START" is received. Up to 8,192 characters could be stored in RAM using this routine and the SRAM that an RPB is sold

I should note a sticky point in this design. The "START" that is received by the BS2 is also

Code Listing 2. RPB2_299.BS2 Storing Serial Data Automatically with the RPB

"RPB2_299.BS2 - Storing Serial Data Automatically with the RPB: This program waits for the characters "START" to be received. Once received the RPB has its internal baud rate reset to 9600 by the WRITE "POINTER command. This command also has the effect of pointing any subsequent FIFO write operations to address location "0000/hex. Data is then loaded into the RPB while it, is in FIFO write mode until the "BS2 receives the characters "STOP". The READ END OF FIFO command is used to find the last address pointed to by the FIFO write operation. This value is always the same as the number of bytes stored during the FIFO write operation. The last byte of data written during a FIFO write operation will be at one less than the value returned by the READ END OF FIFO command.

Stores address in RAM to write or read from

Stores address in FAM to write or read from Address is broken into bytes for sending to the RPB 'Address is broken into bytes for sending to the RPB 'Used to hold data to be sent or received 'Stores Read End of FIFO pointer 'Pointer broken into bytes for receiving from the RPB 'Pointer broken into bytes for receiving from the RPB

Address Addr_lo Addr_hl DataByte VAR End_Addr_VAR End_Addr_loVAR End_Addr_hiVAR		Word Address.lowbyte Address.highbyte Ir.lowbyte Ir.highbyte
'Pin Assignments		
FMEN FMBS2 TMBS2 R_W MODE	CON CON CON CON CON	15 14 12 11 10
'Communication Cons	tants	

Enables/disables data from serial data source From Master pin: sends data/commands to the RPB
To Master pin: receives data from the RPB
Read/Write pin: selects type of FIFO operation
Mode pin: enables/disables FIFO mode Sync B_Read W_Pointer CON EOF_PointerCON 'Sync byte 'Byte Read command CON \$01 Write Pointer command Read End of FIFO command

'Initialization of registers

'Program Variables

FMEN 'Disable data from serial data source 'Disable FIFO mode MODE R_W 500 'Default to FIFO read 'Allow RPB time to power up High Pause

9600 baud

CR,CR,"Initialized",CR debug

MainProgram: "Wait for "START" from serial data source, display message when received

Low Serin FMBS2,Baud,[wait("START")]
"START Received",CR debug High

'Enable data from serial data source 'Disable data from serial data source

At this point the RPB has reset itself due to the "START" data and has returned to a default baud rate of 2400. The Write Pointer command is used to reset the address that the FIFO write operation will start at, and reset the RPB baud rate to 9600 for further data. 'Pointer will be reset to '0000'hex

Address = 0 FMBS2,Baud,[Sync,W_Pointer,Addr_hi,Addr_lo] - Make FMBS2 an input pin Serout Input debug "Resetting FIFO Pointer",CR
"Entering FIFO Buffer Mode",CR debug Pause

'Enable FIFO write operation and wait for "STOP" to be received

Low **FMFN** R_W MODE Low Low Serin High FMBS2,Baud,[wait("STOP")] MODE

Enable data from serial source Enable FIFO buffer 'Disable FIFO buffer after "STOP"

Default to FIFO read

High High Debug 'Disable data from serial source "STOP received", CR, CR The Read End of FIFO command is used to determine how many bytes of data were stored during the

TFIFO write operation. This value is used to set up a For...Next loop to read back all of the data and display it using the Debug command.

Serout FMS2_Baud_Sync_EOF_Pointer
Serin TMBS2_Baud_Sync_EOF_Pointer
Number of bytes in message = ",Dec End_Addr_CR
Debug "Data received after START is...",CR
For Address = 0 in End_Addr_CR For

Next

Data received and Addr-1 'Read data from '00 Serout FMBS2,Baud,[Sync,B_Read,Addr_hi,Addr_lo] Serin TMBS2,Baud,[DataByte] 'Read data from '0000'hex to (End_Addr - 1)

Debug DataByte Initialize

'Display data read 'Start over

Baud

STAMP APPLICATION

received by the RPB on its FM pin. Since these characters do not meet the typical command structure that the RPB expects (sync byte, then command byte, etc.), the RPB will execute a system reset. This reset returns the RPB to a default condition which has the baud rate set to 2400. Sending any valid command from the BS2 to the RPB at 9600 baud prior to executing a FIFO write operation resets the internal baud rate of the RPB to 9600 baud.

In RPB2_299.BS2, this is done by resetting the RPB's internal address pointer with the WRITE POINT-ER command ('05'hex). This command resets the internal address pointer to '0000'hex, as well as setting the

RPB baud rate to 9600.

The hassle of dealing with the effects that the "START" characters have on the RPB can be easily removed. The BS2 could simply execute a FIFO write operation, and then wait for the "STOP" characters. In this manner, all received data would be loaded into the RPB. Since this design interfaces to a human typist, through the PC, adding additional Debug routines and commands can be accommodated. The Debug commands used in this routine might cause unnecessary delays and can be removed in designs where timing is critical.

In instances where data is received as one long string - such as from GPS receivers - it is best to exe cute a FIFO write operation immediately and wait until a particular end-of-string message is received. In this design, the "STOP" constitutes the end-of-string message

Figure 6 displays a screen capture from an HP-54645D MSO (Mixed Signal Oscilloscope). This image is of a slightly-modified version of RPB2_299.BS2. From it, you can see how the data flows from the serial data source to the RPB, and then from the RPB to the BS2. I should note that my serial data source was a PC utilizing a common terminal program found on most IBMstyle computers available today. The communication parameters that I used were 8N1 serial data, 9600 baud, no-handshaking, and local-echo "on."

In Closing

Most of the difficulty in interfacing the RAMPack B's FIFO mode to the BS2 concern the pin sharing requirements for TM and FM pins. These difficulties can usually be overcome with a minimum of additional electronic parts. Often times, the BASIC Stamp is expected to operate as kind of a "traffic director" for serial data. In these instances, the RAMPack B can be effectively used to buffer serial data.

Next month, we'll take a look at pin sharing with the TM pin, as well as the FM pin. Sharing both pins allows the BASIC Stamp and RPB to act as traffic director and data buffer in a myriad of configurations. One such configuration will be covered in the March installment. Next month, we'll trap serial data from a PC, and then send the data to the Scott Edwards Electronics G12032 LCD. The same circuitry we used in Figure 4 will be added to, to accommodate the sharing of the TM pin, and to convert from non-inverted serial data to inverted serial data. The end result will be a device that records bit-maps from your PC and can then display these bit-maps to a graphic LCD. NV

on Glazner is a partner and engineer at Solutions Cubed. Solutions Cubed is an innovative group of design engineers who spe-

cialize in embedded control design. They also produce a line of BASIC Stamp compatible products called Miniature Engineering Modules.

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Code Listing 1. RPB1_299.BS2 ASCII Loop Program

'RPB1_299.BS2 - ASCII Loop Program: this Basic Stamp2 program writes part of the ASCII character set to the RAMPack B at 4800 baud. It then reads the data back in reverse order at 2400 baud. This data is 'displayed using the Debug command. Finally, the data is read back at 9600 baud in the order in which it was stored, this data is also displayed via the Debug command.

'Program Variables

Address	VAR	Word	"Stores address in RAM to write or read from
Addr_lo	VAR	Address.lowbyte	'Address is broken into bytes for sending to the RPB
Addr hi	VAR	Address.highbyte	'Address is broken into bytes for sending to the RPB
Baud	VAR	Word	'A word variable is used to store the data rate
DataByte	VAR	Byte	'Used to hold data to be sent or received
A	VAR	Byte	'ForNext variable

'Program Constants

FMBS2 TMBS2 B_Write B_Read	CON CON CON	14 12 \$00 \$01	'From Master pin: sends data/commands to the RPB 'To Master pin: receives data from the RPB 'Write command for the RPB 'Byte read command for the RPB

Initialization of registers

'Allow some time for RPB to power up
'Default address is 0
'Start data at ASCII "I"

MainProgram: Write data to RPB at 4800 baud

Baud	= 188	vyrite data at 4800 baud
For	A = 1 to 58	"Send ASCII "I" through "Z"
	Serout FMBS2, Baud, [\$55, B_1	Write,Addr_hi,Addr_lo,DataByte]
	Pause 20	'Allow time for WRITE to end
	DataByte = DataByte +1	'Point to next ASCII character
	Address = Address +1	'Point to next address
Next		

'Read data from RPB at 2400 baud, reads data in reverse order of how data was written to RAM

'Read data at 2400 baud A = 1 to 58 For 'Read starting at last byte written

"Read str FMBS2,Baud,[\$55,B_Read,Addr_hi,Addr_lo] TMBS2,Baud,[DataByte] Serout

'Display byte received Debug DataByte.

'Read data from RPB at 9600 baud, reads data in the same order as data was written to RAM Baud 'Read data at 9600 baud Debug CR,CR 'Place a blank line between data sets

Serout

Address = Address + 1

FMBS2,Baud,[DataByte]
TMBS2,Baud,[DataByte]
DataByte, ""

'Read data start at first byte written FMBS2, Baud, [\$55, B_Read, Addr_hi, Addr_lo]

'End of program

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AMATEUR ROBOTICS

107 33(0)(0) 3

his month, I'm going to start a project a bit different from past Breadbot projects. Over the last

columns,

shown three different ver-

The BS-2 SIMMStick project was

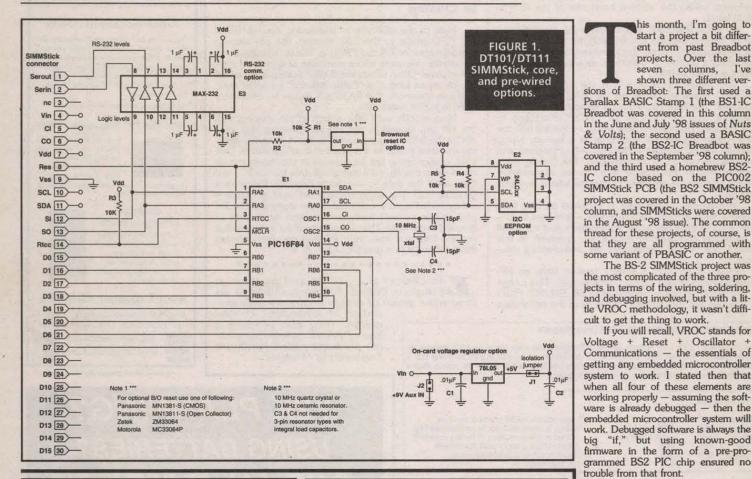
If you will recall, VROC stands for

but using known-good

I've

seven

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Over the Falls In this project, however, I won't be starting with the known-good firmware of PBASIC, so beyond getting the VROC details nailed down, there's the issue of bringing up an embedded system with untested software. When you have to debug hard-

ware and software at the same time, the potential complexity isn't doubled, it's squared; software bugs can masguerade as hardware bugs and vice versa, and if you venture out in these waters unprepared, you have paddled out into a swift stream indeed. That thunder you hear up ahead is white water, and you find yourself going over the falls with PIC assembly language as

To make the plunge survivable and even enjoyable - we need to start with the simplest hardware and software combination possible, the bare minimum needed to tell that both hardware and software are functioning

as designed.

With PCs, the usual first program you write is the good old "Hello World" program which prints (big surprise) "Hello, World!" to an appropriate text display such as an LCD screen or a laser printer. Breadbot doesn't have any text device to print to - not yet, anyway - so we'll need some other output device. Among embedded control programmers, the output device of choice for the microcon-troller equivalent of "Hello World" is the LED. If you can get a microcontroller to blink an LED on demand, you'll survive going over the falls.

It may sound trivial, merely blinking an LED, but the first time you program any new microcontroller - especially one in a homebrew system you'll discover how incredibly difficult it can be to get all the I/O, status, and configuration registers properly programmed just to make that LED blink. In effect, you are using the microcontroller as a tool to help build and debug itself. And a blinking LED gives you one very important thing: success. If you can make that LED blink, it means you've got the hardware working half the battle.

The Hardware

The hardware, in this case, is a PIC16F84 built on a DonTronics DT101 or DT111 PCB (Figure 1). I'm not going to present the detailed assembly instructions for the DT101 as I did for the PIC002 I used in the SIMMStick project. DonTronics board has a clear component placement silkscreen (unlike the PICO02), and you can ftp summary instructions for building DonTronics DT101 from the Wirz Electronics at dtp://wirz.com/ 3rdParty/DT101/dt101.pdf.

For your initial tests, you will need nine components, those marked by asterisks in the parts list.

First solder in J8, the 30-pin right angle header connector. In addition — although they aren't required — I do recommend soldering in high-quality, machined-pin IC sockets for all the ICs you install. These sockets are more expensive than the regular ones, but they are much more rugged and reliable. For the minimal system, though, all you need is the 18-pin socket for the microcontroller.

If you are using the DonTronics DT001 development board to program your SIMMSticks directly in-circuit, you can dispense with the socket for the MCU, and just solder it in (see my Dec '98 column for more on the DT001). If you are using another programmer, such as the Parallax PIC programmer, you'll need a socket on the SIMMStick so you can plug and unplug the MCU each time you program it.

Even though the PIC16F84 uses flash erasable program memory, and thus can be permanently soldered into the circuit, I don't recommend doing this if this is your first microcontroller project. Few things are more frustrating than frying a brand new MCU, but having to then unsolder and replace it before work can continue - and possibly damage the PCB in the process is one of them.

After you've familiarized yourself with the characteristics of PICs and SIMMSticks, then it might be a good idea to solder the MCU to the board. It will be a more reliable connection when subjected to the vibration of a moving robot, and it will also be cheaper. If you choose to install the

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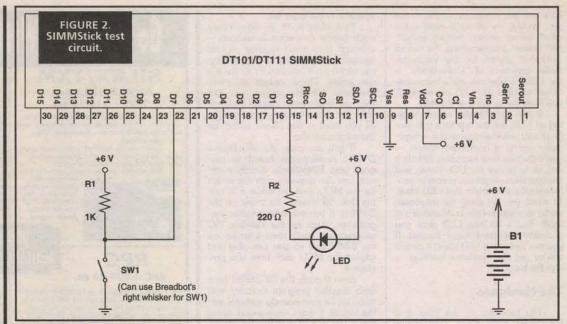
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RS-232 communications option, you should at least use a socket for the MAX-232 because it's pretty easy to accidentally zap it when you're working out serial cable problems.

Power Supply

You can power this circuit either directly at Vdd (pin 7 of the SS-Bus) from Breadbot's six-volt battery pack, or at Vin (pin 4 of the SS-Bus) from a nine-volt battery. For the latter, you'll need to install the on-card voltage regulator option.

To install this option, you'll need C1, C2, J1, and VR1. The +5V regulator VR1 isn't labeled on the DT101 silkscreen (not enough room), but it goes between C7 and J1 with the flat of the TO-92 package facing J1. If you are installing this option, after you solder in VR1, I recommend that you cut the trace on the solder side of the board that shorts the pads of J1 together, solder in the J1 header, and place a shorting jumper between its

The reason for this is that the DT001 programmer automatically switches SS-Bus pin 7 between its own +5V Vdd and +13V Vpp supplies during programming, so if you have VR1 installed on the DT101, its output must be temporarily isolated from the programmer during programming. Otherwise, VR1's +5V will fight against Vpp's +13V, and the result may be curls of blue smoke from one or both voltage regulators.

At the very least, the programmer won't be able to burn the program into the PIC. A sign that the SIMMStick's Vdd supply isn't isolated from the DT001 programmer's Vdd is that the DT001's Vdd indicator LED will be lit when you plug the SIMMStick in the programming slot and switch the Run/Load switch to the "Load" posi-tion; when you switch to "Run," the Vdd LED will go out. I'll talk more about using the DT001 later.

If you are using a separate PIC chip programmer, then install the J1 isolation jumper option if you want, though it's only really necessary in this case if it's possible you will ever apply voltages to both Vin (SS-Bus pin 4) and Vdd (SS-Bus pin 7) simultaneously. As with the BASIC Stamps, use one or the other, but not both.

Next, solder in C1 and C2. With the SIMMStick oriented component side up and the SS-Bus connector fac-

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_CONFIG _CP_OFF & _WDT_OFF & _HS_OSC & _PWRTE_ON

PAGE

org 0

STATUS, RPO bsf

TRISB & 0x07F, 0; Set RB0 to Output bcf bcf

STATUS, RPO

btfsc

PORTB,7

; Turn LED ON

; Wait for switch press

wait OFF

PORTB,7

; Wait for switch release : Turn LED OFF

wait ON

goto wait_ON

bcf PORTB,0

goto wait_OFF

PORTB,0 bsf

goto wait ON

end

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Questions & Answers

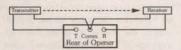
TECHEOD

This is a READER TO READER Column. All questions AND answers will be provided by *Nuts & Volts readers* and are intended to promote the exchange of ideas and provide assistance for solving problems of a technical nature. All questions submitted are subject to editing and will be published on a space available basis if deemed suitable to the publisher. All answers are submitted by readers and *NO GUARANTEES WHATSOEVER* are made by the publisher. The implementation of any answer printed in this column may require varying degrees of technical experience and should only be attempted by qualified individuals. Always use common sense and good judgement!

QUESTIONS

I would like to hook-up a circuit that is similar to the beam-braking safety part of my garage door opener. It is a Chamberlain unit.

I want to use this system in conjunction with a burgler alarm system. There is no schematic with the opener. Refer to the following schematic for wiring information.



Can someone supply a simple circuit that I can try? What kind of sender unit and optical detector is required?

2991

Roger W. Hamel Cedarville, MI

In most projects that use crystals, they never specify series or parallel. What is the difference between series and parallel crystals? Are they interchangeable?

For example, a 20 pF capacitance of the parallel crystal, is this internal or external and is this a set value or minimum or maximum?

The capacitance in most projects vary from 10 to 30 pF, is this for series or parallel and how do you calculate the value?

2992

Marvin Saj Ontario, Canada

Is there a simple circuit modification to add to a triac light control to provide "soft-on" function to increase bulb life? Is it known what the bulb makers believe is possible here? I wonder if the relatively new axial disposed filaments are more prone to failure from mechanical shock?

2993

John Connell San Francisco, CA

Are ZN416 [preferred] or ZN414 available somewhere? These are simple AM radio receiver ICs. I would like to purchase some, but haven't been able to locate any of either type. 2994

David Rowe Sacramento, CA

I would like to have the pinout for an Analog Device AD2038 temperature meter. It was described in the Send all material to Nuts & Volts Magazine, 430 Princeland Court, Corona, CA 91719, OR fax to (909) 371-3052, OR E-Mail to forum@nutsvolts.com

1987 short-form selection guide.

Through experimentation, I have resolved many of the interconnect requirements, but not all. A pinout would be helpful.

2995

Kenneth Keck via Internet

I am looking for a circuit that I can use to calculate the time between two vehicles in motion.

Vehicle 1 will have the circuit installed, and needs to calculate how far behind (in seconds) vehicle 2 is following.

2996

Mike Ciotti via Internet

I have a gasoline 120V AC 8KW generator that I use at job sites. The thing just rip-roars whether I have a power tool plugged into it or not.

Can anyone direct me to a circuit that can do load sensing to see if a load is on-line, which would then run a servo motor, or solenoid to open the throttle on the engine, and when the load is removed to idle it back down?

It does have a 12V battery to provide sensing voltage.

John Jones II via Internet

Is there an antenna for shortwave radio? Where can I find it or them?

2998

Nelson Ortega Tampa, FL

I have a project underway that uses two separate inexpensive Elenco sine/squarewave generators.

On these, the frequency output is controlled by a simple potentiometer. I need to be able to control these pots using a computer/Visual Basic 6. Does anyone know how I can accomplish this? I wish to use a mouse, where pressing the left mouse button assumes control of generator 1, allowing mouse movement to control frequency. Pressing the right button would adjust genera-

Also, once frequency 1 is set, I would like things set up so that pressing the right button would start up the second generator at the same frequency as generator 1. I am sure all this could be done in software, perhaps directly controlling a Sound Blaster card, but currently I am trying to control those pots via RS-232. Tom Moore

via Internet

I am looking for a circuit that will interface with the data port of a number of automobile on-board comput-

My immediate need is for a 96 Jeep Cherokee. Once I get to talk to the computer, I would need to figure out what I'm seeing. Possibly using a BASIC Stamp and or a laptop to help decode the information?

Trying to troubleshoot a newer vehicle now is much harder than it was back before the days of the onboard computers.

29910

Joe Reed Charlotte, NC

I am looking for a device that would protect equipment from voltage sags during brownouts and from power going on and off quickly as often happens during blackouts.

This device would pass power from the AC mains to the load device(s) as long as the AC supply remains inside an acceptable range of voltages (from 100 to 130 VAC). But, if voltages drops for goes too high], then it disconnects the devices from the mains (both sides, hot and neutral) and keeps them disconnected until the voltages on the mains have returned to normal values and have stayed there continuously for at least 100 seconds.

The device must be able to support inductive and non-inductive loads of up to 15 amps. The device could be completely prepared for consumers (like a power strip is) or could be a component that requires the addition of power plugs and sockets

29911

Nelson Bolyard via Internet

I have a DBS receiver that is capable of controlling a VCR via an IR emitter.

Due to my shelf arrangement and room conditions, the DBS receiver does not reliably control the VCR.

I would like to build a simple 'repeater' circuit in which an IR sensor placed in front of the emitter of the DBS receiver would transmit, via

ANSWER INFO

· Include the question number that appears directly below the question you are responding to.
• Payment of \$25.00 will be sent if

your answer is printed.
• In most cases, only one answer per question will be printed.

Your name, city, state, and E-Mail address, [if submitted by E-Mail], will be printed in the magazine, unless you notify us otherwise with your

submission.

Due to space limitations, we can not reprint the original questions with the answer. The question number and the issue it appeared in are printed above the answer.

• Unanswered questions from a past

issue may still be responded to.

Comments regarding answers printed in this column may be printed in the Reader Feedback section if space allows.

QUESTION INFO

TO BE CONSIDERED FOR PUBLICATION

All questions should relate to one or more of the following:

1) Circuit Design 3) Problem Solving

2) Electronic Theory 4) Other Similar Topics

INFORMATION/RESTRICTIONS

 No questions will be accepted that offer equipment for sale or equipment wanted to buy.

 Selected questions will be printed one time on a space available basis.

Questions may be subject to editing.

HELPFUL HINTS

 Be brief but include all pertinent information. If no one knows what you're asking, you won't get any response (and we probably won't print it either).

Write legibly (or type). If we can't read

it, we'll throw it away.

Include your Name, Address and Phone Number. Only your name will be published with the question, but we may need to contact you.

a short cable, to an IR emitter placed in front of the VCRs IR receiver.

I am sure there are some inexpensive IR modules available from distributors that might do the job easily, but I am not very familiar with them.

29912

Lee Roth Columbus, OH

I am looking for a device for a telephone line that has the Caller Line ID (CLID) feature.

One side of this device would hook to the telco line, the other side

ECH FORUM

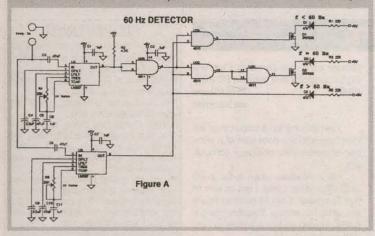
ANSWER TO #1996 - JAN. 1999

What you are describing is a frequency detector. It should be fairly simple to construct using a couple of LM567 tone decoders.

Referring to Figure A, U4 is set up to detect an input frequency of 60 Hz and with a little logic, turn on D2. When the input frequency is less than 60 Hz, D1 is on and D2 is off. When the input frequency is greater than 60 Hz. U5 turns on D3 and disables operation of D1 and D2 through the nand gates U2A and U2C.

To set up U4, monitor the center frequency of the decoder on pin 6 with a scope or frequency counter and adjust R4 for an output of 60 Hz. Likewise, to set up U5, monitor the center frequency of the decoder on pin 6, adjust R6 for an output of 62 Hz. See Figure A for circuit details.

Kevin Goodwin Oceanside, CA



would be connected to the phone(s).

The device would prevent the phones from ringing unless and until CLID information containing a number was supplied by the telco. The device would not ring the phone for incoming calls that have no CLID information, nor for calls whose CLID info indicates P (private) or O (Out of area), or any other non-numeric info for the phone number.

The phones that connect to this device must still be able to get dial tone and/or answer calls merely by lifting the receiver, and the telco line features that require flashing the hook (e.g., call waiting, three-way calling) must continue to work with those phones.

29913 Nelson Bolyard via Internet

ANSWERS

ANSWERS TO #19917 - JAN. 1999

You can solve this problem by getting a device known as the

"ymouse" manufactured by P. I. Engineering, 2296 Williamston Rd., Williamston, MI at 1-800-628-3185 or 517-655-5523.

This adapter will handle either two mice or one mouse and a touchpad device, or one mouse and a trackball, and connects to the computer's serial DB9 port.

They also manufacture adapters for PS2, keyboards, and laptops.

The website can be found at http://www.ymouse.com

Arthur Hazboun Harbor City, CA

ANSWERS TO #19917 - JAN. 1999

You may want to consider purchasing a Y-splitter which would allow two pointing devices to be used simultaneously by your PC.

A mail order business called Cyberguys sells these Y-splitters for both serial and PS/2 pointing devices. They are advertised to work with standard mice, trackballs, and other pointing devices such as touchpads. The catalog number is 104-0520, and they are priced at \$45.95 each. Check them out on the web at www.cybererguys.com or by voice at 1-800-892-1010.

> John McMichael Laramie, WY

ANSWER TO #1998 - JAN. 1999

It sounds to me like a case of AGC overload with resultant crosschannel modulation. That's a fancy way of saying those two channels are way too strong for your TV set, and your high-gain antenna is not helping one bit.

If the antenna has a pre-amplifier in it, that will just make things worse.

Here's a simple test: instead of your big antenna, connect a halo loop or maybe just a couple of paper clips to the antenna terminals of your TV set. The picture may look weaker, but the bars should go away.

Once you have determined that too much signal level is the problem, then you can address how to reduce the signal on those two channels while still receiving other stations in the area.

Tuning stubs used as notch filters would be one approach. Turning off the pre-amplifier [if there is one] might do the trick, or pointing the antenna in some other direction, such as 90 or 180 degrees offcourse.

> Harry Boling Garland, TX

ANSWERS TO #1999 - JAN. 1999

You want a set of cascaded timers. This should be easy using 555 ICs. Connect pin 2 [trigger, active low) on each timer via resistor to +V and a capacitor to pin 3 (output) on the preceding timer. The trailing edge of the output pulse will spike the trigger low starting the next

To start the timers properly, you should probably set up a momentary switch to all the resets (pin 4, active low), and a momentary switch to pin 2 of the start timer.

> Peter Hanely via Internet

ANSWERS TO #1999 - JAN. 1999

CEBEK recently released a three-timer circuit designed to simulate the operation of a traffic light. Time settings are adjustable from 4 to 50 seconds for the "Red" and "Green" outputs. The "Yellow" output is automatically set to 1/4 of the time setting.

This circuit operates at 12V DC and can switch up to 2A. This will easily control relays to operate the light at 120 VAC.

Best of all, the price of this board level unit is under \$20.00 available from MCM Electronics, 1-800-543-4330. Order number is 28-6215.

> Alex McIlwain Lakeland, FL

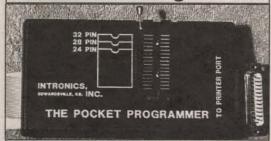
ANSWERS TO #1999 - JAN. 1999

Rather than using discrete components to generate timing signals for the traffic light, have you considered using a PIC microcontroller from Microchip Electronics?

A PIC 12C508, for example, has six I/O pins and sells for under \$2.00 in single quantities. It also has its own clock which runs at 4 MHz and should be accurate enough for your application.

If you don't mind setting the delay values in software, you should literally need no external components to get the timing signals, since three of the six I/O pins could be pro-

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TECH FORUM

ANSWERS TO #19915 -JAN. 19915

You can make a dual channel oscilloscope act like a Huntron Tracker (characteristic curve tracer] by using an external sinewave generator and a resistor. The signal generator (or scope) must have a floating common.

Channel-A of the scope measures the voltage across the component under test, Channel-B measures the current.

Set the scope time scale to X vs. Y (or A vs. B). Apply a 5Vpk [10Vpp] 1KHz sinewave to the component under test in series with a 1,000 ohm resistor. Connect the scope's CHA-COM and CHB-COM to the junction of the component under test and the resistor

Connect CH-A to the junction of the signal generator output and the component under test, connect CH-B to the junction of the signal generator and the resistor.

Be aware that some tiny diodes have very low Imax. The above circuit will put up to 5mA though your component. Lower the signal voltage or increase the resistance appropriately.

Use a relay or toggle switch to place other components into this circuit automatically for comparison of "good" vs "bad" components.

Anthony Tekatch Ontario, Canada

ANSWERS TO #19915 -JAN. 1999

We have a .pdf file on our web site that shows a curve tracer that may be added to most oscilloscopes like the one requested by Farley. reader. Joe http://www.wenzel.com /pdffiles/curve.pdf (A copy is reprinted here, to the right.)

The simple version may be all that you need, but the multi-voltage design has enough voltage and power to look at the behavior of power devices and enough sensitivity to non-destructively characterize delicate components. Just make sure the switch settings are right.

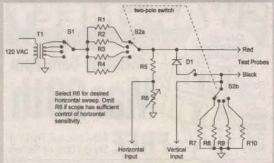
I also like the built-in diode for single-polarity testing when highreverse voltage can cause damage.

Charles Wenzel Austin, TX

grammed to provide the timing signals for the lights.

If you are new to programming PICs, check out the Microchip web site at www.microchip.com and invest some time in learning. If you do a lot of work with electronic circuit design, the time you are able to save on projects like this should more than make up for the time you invest in

V/I Curve Tracer



The V/I Curve Tracer is an indispensable tool for troubleshooting circuits and testing components. The circuit traces the current versus voltage curve for the component under test on an ordinary oscilloscope. The peak-to-peak test voltage is adjusted by selecting different taps on a power transformer and the test current is limited by a selected series resistor. The voltage and current ranges are not critical and a single voltage version built with no switches will prove quite useful. The "deluxe" version shown in the schematic provides four test voltages with current ranges from a few hundred microamps to a few hundred milliamps. An optional diode is included in the output to limit the voltage swing to a single polarity to prevent reverse breakdown when checking delicate devices

T1: Unless you plan to test high-power devices, T1 may be a small power transformer with a few different secondary voltages. The prototype depicted in the schematic has four secondary taps but a center-tapped 24VAC transformer will give two useful test voltages of about 17 and 33 volts peak. Avoid voltages much above 24VAC to reduce risk of shock.

S1: A single-pole switch with enough positions to accommodate the desired number of test voltages.

S2: A two-pole switch with enough positions to accommodate the desired number of test current ranges. Note that the switch selects resistor pairs: R1 & R7, R2 & R8, R3 & R9, R4 & R10.

R1 - R4: These resistors limit the test current. R1 could be a 100 ohm, 10 watt resistor for a high power range capable of testing incandescent lamps (and quickly zapping semiconductors!). R1 works with the current sensing resistor R7. The current sensing resistors should be

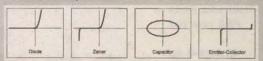
about 1000 times smaller than the series resistors so R7 should be 0.1 ohms if R1 is 100 ohms. The power dissipated in the current sensing resistors will be small so any

style may be used. Try R2 = 1000 ohms, R3 = 10,000, and R4 = 100,000 ohms.

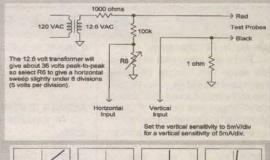
Following the 1/1000 guideline gives R8 = 1 ohm, R9 = 10 ohms, R10 = 100 ohms. Note that these current sense values give four ranges from 100mA to 100uA with about 10 mV per vertical division for the oscilloscope. If the oscilloscope does not have a vertical sensitivity of 10 mV per division, the current sense resistors [R7 - R10] may be increased.

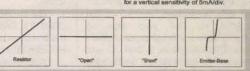
D1: A silicon diode capable of handling the highest test current and voltage. A 1N4002 should work well for most applications. When the diode is in the circuit, it will limit the negative swing to under -1 volt

Here is a simple version with a single voltage range of about 18 volts peak and a current limit of about 18



milliamps peak. The transformer is an ordinary "filament" transformer or similar with a single secondary. This onerange tracer is quite useful for quick checking of zeners, transistor junctions, LEDs, and most other semiconduc-





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TECH FORU

learning the PIC technology.

There are many web sites available which give sample PIC code, explain how to build your own PIC programmer, etc. Just use your favorite search engine and include "PIC" and "Microchip" in the search terms.

If you want to simply buy a device for this application, check out the "Lights to Go" web site at http://www.trafficlights.com/e5ad. htm. This describes a \$44.00 unit they sell for controlling a traffic light.

It should be sufficient to control the light if you plan on using it indoors.

Mark Winters Orem, UT

ANSWER TO #1993 - JAN. 1999

All modems should have that

Go to START - SETTINGS -CONTROL PANEL - MODEM, When the box pops up, choose the DIALING PROPERTIES button.

Approximately 2/3 down the

newly displayed window is a check box for "Call Waiting" make sure it is not checked. If it is not, go to START PROGRAMS - ACCESSORIES DIAL-UP NETWORKING. Highlight the "Entry Name" or "Connection Name" you connect to.

Now choose FILE - PROPER-

In the windows that pops up, verify that the "Telephone Number" box does not have a *70 (or whatever your phone company uses to disable call waiting) in the box, if it does, delete ONLY the *70 click ok and close the other windows. That should fix your problem.

If this does not fix it, you should check that you do not have your calls automatically forwarded when the number is busy.

Gregg Berkholtz Portland, OR

ANSWER TO #1992 - JAN. 1999

You are probably suffering from two separate problems, but both of them are related to the current the motors draw.

First, your power supply probably cannot provide enough current when the motors are first turned on. Although the motors may say they are 5 amperes, the current the motors draw when they are first turned on could be much higher. If it is high enough, then the supply voltage may dip low enough that the microcontroller gets upset. The motor supplies and the logic supplies should be separate, you don't want the dip on the motor supply to affect the microcontroller.

If you must use one supply, then connect the motor to the supply directly, but use a series diode to connect the positive supply to the microcontroller. If the motor supply dips, then the diode will reverse bias and prevent the motor from pulling down the microcontroller supply.

The microcontroller power supply (not the motor) should have some large capacitors so it can coast through the dip in the motor supply. Use a scope to look at the power sup-

Second, you probably have a wicked ground loop. You must arrange your ground wires so none of the motor current flows through any of the microcontroller ground connections. The microcontroller ground connections include the grounds used for the power devices that turn the motors on and off.

You may need transformer or optoelectronic coupling. The generalized notion is called single point grounding.

Here's what happens: Say the motor current does flow through the microcontroller ground. Say the resistance of the ground connection is 0.1 ohms. If the motor startup current is 20 amperes, then the voltage drop across the ground connection is 2 volts - more than enough to change a logic state from false to

You may also want to add some capacitors, diodes, and resistors across the motor, but these components are usually added to reduce the stress on the power switching components or to reduce RFI.

Gerald Roylance Mountain View, CA

ANSWER TO #1991 - JAN. 1999

There are several PLL ICs that can be used for a 100-1000 MHz synthesizer.



TECH FORUM

Motorola's MC145200 will work to 2 GHz. National has an LMX2315. and Harris has an HFA3524. Even better for this application would be a fractional-N chipset, but I don't have any data handy. All these chips are programmed serially, so the interface to a computer is simple.

Unfortunately, the problem in building such a synthesizer is not the IC, but the oscillator. It is tough to build an oscillator that covers one octave, but you want to cover about 3.5 octaves.

The simplest way around the oscillator range problem is a heterodyne design. Use a VCO that covers 5.1 to 6.0 GHz, mix it with a 5.0 GHz local oscillator, and use the 0.1-1.0 GHz result as the synthesizer output. The frequencies are a little scary, and the performance won't be great.

An alternative is to build a 250-500 MHz VCO to cover the middle octave. Other octaves are derived from this signal. Switch in a doubler if you need the top octave, or use one or two dividers to get the lower octaves. You will need six or seven half-octave filters to clean up the output signal.

There are a lot of switches, so we are not talking about something simple. The performance should be better than the heterodyne design.

Building a one-octave VCO is difficult, and building a good one is an art. The good ones are bandswitched and vary the oscillator bias conditions in different bands. They also use pretuning and compensate for changes in PLL loop gain.

For low-noise oscillators, the VCO tuning sensitivity is often less than 500 KHz/volt and the VCO will have 32 tuning bands.

Good (but expensive) texts are: Manassewitsch, Frequency Synthesizers: Theory and Design, and Rohde, Microwave and Wireless Synthesizers.

> Gerald Roylance Mountain View, CA

ANSWER TO #129818 - DEC. 1998

I recall that one of the hobby electronics magazines did a construction project a while back on building a GPIB interface, perhaps Electronics Now, or Popular Electronics.

However, Computerboards, Inc. in Massachusetts sells a GPIB interface for \$249.00 new. Their phone number is 508-946-5100.

You can probably get the spec for the GPIB interface from the National Instruments or Hewlett-Packard web site

> Joe Heck Wrentham, MA

ANSWER TO #129817 - DEC. 1998

It is very simple to construct a linear, 10X amplifier, for this application. It is also very inexpensive (total cost is about 45¢).

Build the non-inverting amplifier exactly as drawn in the book, The Art of Electronics, by P. Horowitz and W.

For instance, one could use a LM 358 op-amp, a 1 Kohm resistor, a 3.3 Kohm resistor, a 5.6 Kohm resistor, and a 7-32 volts DC power supply (or just an ordinary 9-volt battery).

1. Connect the positive terminal of the power supply to pin #8 of the LM 358.

2. Connect the negative terminal of the power supply to pin #4 of the LM 358.

3. Connect the end of the 5.6 Kohm resistor to pin #1.

4. Connect one end of the 3.3 Kohm resistor to the free end of the 5.6 Kohm resistor. (5.6K + 3.3K = 9K. This is R2 on the drawing.)

5. Connect one end of the 1 Kohm resistor to the free end of the 3.3 Kohm resistor. [This is R1 on the drawing.)

6. Connect the free end of the 1 Kohm resistor to the negative terminal of the power supply.

7. Connect the junction of the 3.3 Kohm and the 1 Kohm resistor (that made in step #5) to pin #2 of the LM 358.

8. Be sure to connect the negative terminal of the power supply to the ground of the sensor (s).

Continued on page 81





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- RCA Connectors for CD Player or Cassette to Amp/Receiver.
- 100% foil shield for reduced interference and superior
- Molded connector with gold plated contacts improves the quality of the connection.
- Color coded for easy connection of left and right channel.



Part#	1.ength	Price
VC-7009	3'	\$2.00 ea.
- VC-7010	6'	\$3.00 ea.
VC-7011	12'	\$4.00 ea.

"F" Video Cable

- Push-on connector for easy installation.
- Connects VCR/Cable Box to TV
- Highest quality 75 ohm video cable for a superior picture. Molded connector with gold plated contacts improves the quality of

the connection.



Part#	Length	Price
VC-7000.	3'	\$2.00 ea
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"S" Video Cable

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	Part#	Length	Price
1	VC-7007	6'	\$3.00 ea.
ğ	VC-7008	12'	\$5.00 ea.

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 - Color coded for easy installation. Molded connection with gold plated contacts improves the quality of the connection.

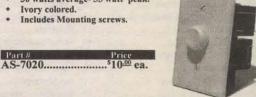


Part#	Length	Price
VC-7012	3'	\$4.00 ea.
VC-7013	6'	\$6.00 ea.
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ADVERTISER'S INDEX Abacom Technologies68 Davilyn Corp. .. KDE Electronics Corp.48 Le

ABC Electronics29	Decade Engineering86	La
ACP Super Store72	DeMar Electronics87	Len
Advanced Educational Systems68	Digital Products Co86	Line
Alfa Electronics59	Earth Computer Technologies44	LLF
All Electronics Corporation60	Edlie Electronics, Inc46	Lyn
Allison Technology Corporation81, 86	E.H. Yost & Co54	M2
Alltech Electronics18	ELECTRO MAVIN8	Ma
Alltronics23	Electro Tool, Inc53	MC
American Technologies Network Corp35	Electronic Design Specialists, Inc22	Me
AM Research, Inc35	Electronic Goldmine49	Me
Andromeda Research21	Electronic Rainbow Ind., Inc51	M.F
Antique Radio Classified87	Electronix Corp39	mic
AST Global Electronics32	Electronix Express72	Mic
Aventrade86	EMAC, Inc53	Mo
Base287	EPS87	Mr.
Basic Electrical Supply	Equipment Management Technology61	MS
& Warehousing Corporation20	ExpressPCB34	Net
Baylin Publications19	Fair Radio Sales11	Nor
Bilocon Corp87	Foss Warehouse Distributors86	Oce
Bisme Computers Outlet59	Gateway56	Opt
Black Feather Electronics26	General Device Instruments86	Pac
Brick Wall Div., Price Wheeler Corp13	Glentech, Inc86	Par
Brigar Electronics67	Graymark44	PAF
C & S Sales, Inc40	Halted Specialties Co3	PC
C and H Sales Company45	H.T. Orr Computer Supplies61	Phe
Chaffin Electronics78	Hyatt Electronic Surplus87	Pio
Chenesko Products, Inc71	IndustroLogic16	Pol
Communications Surplus87	Information Unlimited45	Pra
Consumertronics28	Inkjet Southwest58	Pul
Corporate Systems Center2, 95	Intronics, Inc70	R8
Cruising Equipment65	Jade Products, Inc86	Rai
Cunard Associates53	James' Electronic Services, Ltd84	Res

.50 J-Works, Inc.

Paz Electronics Int'l.	.71
mos International Co., Inc	.67
near Systems	.15
H Technology Publishing	.38
nxmotion, Inc.	.21
2L Electronics	.59
atco, Inc.	.87
CM Electronics	9
eredith Instruments	.19
etric Equipment Sales, Inc	.48
F.M. Communications	.24
croEngineering Labs	.65
cromint	.66
otron Electronics	.39
NiCd	.54
SC Electronics	.87
etcom	.85
orthwest Cable & Connector Co	.25
cean State Electronics	.42
otoelectronics	.94
cific Test Equipment Corp	.43
rallax, Inc Back Co	
RAMAX, INC.	.83
CW, Inc	.70
nelps Instruments	.52
oneer Hill Software	.81
laris Industries	.63
airie Digital, Inc.	.87
ılsar, Inc	.25
& S Surplus	.54
amsey Electronics, Inc	.57
esources Un-Ltd.	.14

Roger's Systems Specialist73
Sam's Electronics54
Scott Edwards Electronics8
Seabird Technical87
Shreve Systems86
SIMCO47
Skycraft Parts & Surplus, Inc72
Square 1 Electronics34
Surplus Traders86
Synergetics79
Tech 200026
Techniks, Inc86
Technological Arts86
Telulex, Inc
The RF Connection15
Timeless Products61
Timeline, Inc47
Ultra Link87
Unicorn Electronics22
USI Corp
Utopia Tools29
V&V Mach. & Equipment, Inc86, 87
Velleman55
VersaTech Electronics
Vesta Technology, Inc87
Viking International52
Visitect, Inc82
Weeder Technologies20
Western Test Systems30-31
Wholesale Cable78

77.86

Danbar Sales Company ..

		Corporate Systems Center2
AMATEUR RADIO & T	V	Earth Computer Technologies
	-	ELECTRO MAVIN
Altronics	68	Halted Specialties Co
Alltronics	87	La Paz Electronics Int'l
Jade Products, Inc	56	Northwest Cable & Connector Co
Lemos International Co., Inc.		Roger's Systems Specialist
Ocean State Electronics	42	Shreve Systems
Ramsey Electronics, Inc	15	Ultra Link Worldwyde
The Fit Controction III.		Worldwyde77
BATTERIES/CHARGER	25	Software
		AM Research, Inc.
Aventrade Cruising Equipment		Bisme Computers Outlet
Cunard Associates		Electronix Corp. Pioneer Hill Software
E.H. Yost & Co	54	Ultra Link
Jade Products, Inc		Missassas IIIO December
		Microcontrollers / I/O Boards Abacom Technologies
BUSINESS	- 10	Advanced Educational Systems
OPPORTUNITIES	- 18	AM Research, Inc. Bisme Computer Outlet
THE RESIDENCE OF THE PARTY OF T		EMAC, Inc.
Chenesko Products, Inc	71	IndustroLogic
BUYING		La Paz Electronics Int'l
	10 III	Motron Electronics
ELECTRONIC SURPLU	5	Parallax, IncBack Co
ABC Electronics	29	PARAMAX, INC.
Alltech Electronics	18	Prairie Digital, Inc.
Black Feather Electronics		Scott Edwards Electronics
C and H Sales Company Earth Computer Technologies	45	Square 1 Electronics
EPS	87	Technological Arts
Equipment Management Technology		Vesta Technology, Inc.
Metric Equipment Sales, Inc.		
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		Chenesko Products, Inc
CABLE TV		Inkjet Southwest
CADELIV		Contract the second
Basic Electrical Supply &		DESIGN/ENGINEERING
Warehousing Corporation Foss Warehouse Distributors	20	
James' Electronic Services, Ltd		SERVICES
KDE Electronics Corp	48	ExpressPCB
PCW, Inc	54	Pulsar, Inc
Tech 2000	26	V&V Mach. & Equipment, Inc86
Timeless Products		Daniel Company of the Company
Wholesale Cable	78	EDUCATION
CD/CCANNEDC		Advanced Educational Systems
CB/SCANNERS		Electronix Corp.
USI Corp.	66	EMAC, Inc.
The same of the sa		EVENTOLONIO
CCD CAMERAS/VIDEO		EVENTS/SHOWS
American Technologies Network Corp.	-	ACP Super Store
Black Feather Electronics	26	
Decade Engineering	86	KITS
MSC Electronics		
Ramsey Electronics, Inc.	57	Altronics
Resources Un-Ltd.	14	C & S Sales, Inc.
Seabird Technical		Earth Computer Technologies
Timeline, Inc		Edlie Electronics, Inc.
		Electronic Goldmine
COMPONENTS		EMAC, Inc
COMPONENTS		Gateway
Communications Surplus		Hyatt Electronic Surplus
Electronic Goldmine	49	Inkjet Southwest
Electronix Express		Jade Products, Inc.
Hyatt Electronic Surplus	87	Ocean State Electronics
La Paz Electronics Int'l	71	Ramsey Electronics, Inc.
Linear Systems Ocean State Electronics		USI Corp.
Pulsar, Inc.	25	Velleman
Skycraft Parts & Surplus, Inc	72	Weeder Technologies
Unicorn Electronics		LACEBO
		LASERS
COMPUTER	1	Information Unlimited
COMPOTER		Meredith Instruments
Hardware		Resources Un-Ltd
ACP Super Store	72	
Allison Technology Corp81	, 86	MISC./SURPLUS
Alltech Electronics	18	
AM Research, Inc.		All Electronics Corporation
Bisme Computers Outlet	59	Black Feather Electronics
Brick Wall Div., Price Wheeler Corp	13	Brigar Electronics
Chaffin Electronics		C and H Sales Company
		No. of the last of

2, 95	
8	
86	
3	
9	
73	
86	
7, 86	Mrs.
35	
39	
87	
68	
35	
53	
16	
66	
over 83	ALCOHOLD BY
87	
8	
	Communications Surplus Consumertronics
29	DeMar Electronics
	Electronic Goldmine Electronic Rainbow Ind., Inc.
71	EPS Equipment Management Tech
61	Fair Radio Sales
	Gateway Halted Specialties Co Hyatt Electronic Surplus
G	Linear Systems
	Resources Un-Ltd
34	Skycraft Parts & Surplus, Inc.
6, 87	Surplus Traders Timeline, Inc.
	Unicorn Electronics Viking International
	Visitect, Inc
39	
53	PROGRAMME
	Andromeda Research
70	General Device Instruments . Intronics, Inc.
The Real Property lies	M2L ElectronicsmicroEngineering Labs
	iniciocing incerning cases
23	PUBLICATIO
86	
46	Antique Radio Classified Consumertronics
49	LLH Technology Publishing
53	Netcom
87	Syncigotics
58	ROBOTICS
86	
8	Abacom Technologies Lemos International Co., Inc.
66	Lynxmotion, IncPARAMAX, INC
20	
	SATELLITE
45	Baylin Publications
19	
22	SECURITY

..18

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Consumertronics		SOLAR EQUIP
DeMar Electronics	87	SULAR EQUIP
Electronic Goldmine Electronic Rainbow Ind., Inc	51	Cruising Equipment
EPS	87	
Fair Radio Sales	11	STEPPER MO
Gateway	56	
Hyatt Electronic Surplus	87	Altronics
Linear Systems	15	TAININA, INCq
Shreve Systems	86	TELEPHO
Skycraft Parts & Surplus, Inc	72	12221110
Surplus Traders	86	Bilocon Corp Digital Products, Inc
Unicorn Electronics	22	M.F.M. Communications
Viking International		Telulex, Inc
Weeder Technologies	20	
2222244452		TEST EQUIP
PROGRAMMERS		
Andromeda Research	21	ABC Electronics
General Device Instruments	86	Allison Technology Corp AST Global Electronics
Intronics, Inc. M2L Electronics		C & S Sales, Inc
microEngineering Labs		Cruising Equipment
DUDLIGUE	100	Danbar Sales Company
PUBLICATIONS		Davilyn Corp
Antique Radio Classified	97	Electronic Design Specialist Equipment Management Te
Antique Radio Classified	28	Electro Tool, Inc.
LLH Technology Publishing Netcom		Glentech, Inc.
Square 1 Electronics		J-Works, Inc

SATELLITE

..67 ..21

.86 s, Inc. chnology .61 .53 .86 .70 .77 ...9 Metric Equipment Sales, Inc.

MENT

TORS

IENT

.87 .86 .24 .49

Optoelectronics	94
Pacific Test Equipment Corp	43
Phelps Instruments	52
Pioneer Hill Software	81
R & S Surplus	54
Seabird Technical	87
Telulex, Inc. Western Test Systems	49
vvesterii rest systems	50-51
THE RESERVE OF THE PERSON NAMED IN	-
TOOLS	
TOOLS	
C & S Sales, Inc. Electro Tool, Inc. Graymark The RF Connection Utopia Tools	53
WIRE/CABLE & CONNECTORS	
Northwest Cable & Connector Co Roger's Systems Specialist The RF Connection	73

agnifiers come in many sizes, shapes, and prices. To put a numerical value on the property we call magnification, you need to go back to 1800's England when they defined the near point. The near point is the closest distance from the eyes most

adults can comfortably focus and is defined as 10 inches (250mm).

This is the basis for determining the property we call magnification of near subjects. If you look at one line 10mm long from 10 inches, and it covers a particular angle, and compare it to another line 5mm long with a magnifier, and it covers the

same angle, you have a 2X magnifier.

Under the same viewing conditions, a 0.1mm line covering the same angle would mean you are using a 100X magnifier. Not all manufacturers use this definition of magnification and use the term power instead. Power is not that rigorously defined and often refers to the increase in area. In this case, the magnification factor is the square root of the power. A 9X power lens would have a magnification factor of about 3X.

When you focus your eyes from infinity to 10 inches, it's similar to introducing a four diopter lens into the view. My old eyes don't come close to the 10-inch focus of the average adult, so I have

Figure



a different size image on the retina. Individual differences and preferences support the thousands of different magnifiers in the marketplace.

Simple Lens Magnifiers

Simple lens magnifiers use one lens group between the eye and the subject under observation. These simple magnifiers may be a single lens, several lenses cemented together and, in rare cases, air-spaced lenses. They may yield magnifications from a little over IX to over 300X. In the current commercial market, you can find magnifiers that provide slightly over 1X to about 25X. Higher magnifications are now provided by the more easily used compound magnifiers.

Compound magnifiers differ from the simple magnifiers in that they use a second set of lenses to magnify the image of the primary group. Representatives of compound magnifiers are microscopes, binoculars, and telescopes. There are image magnifiers that use infrared, ultraviolet, Xray, and electrons, but we will only cover the visi-

ble frequencies.

A popular form of simple magnifiers in Figure I is an oversized 5X and a focusing 8X model. When you look through these magnifiers, you will find that for practical purposes, the visual linear magnification is about half the stated value. If you put the magnifier on a piece of quadrille paper, you can easily see the degree of magnification. You can increase the magnification by lifting it from the surface of the subject and increasing the distance to your eye, however, a little bit goes a long way as the image is quickly distorted beyond use. The ones shown cost about \$5.00 to \$10.00.

Some magnifiers include a measuring reticle (a glass scale) at the focal plane for accurate measurements of length, angle, or thread pitch. More highly corrected optics can increase the price up

252 IX to 1000X

by John C. Little

to \$250.00 for special applications such as photo retouching. Most of the simple magnifiers on the market today use clear bodies so you can view either opaque or transparent subjects.

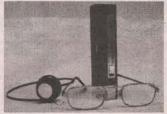
Another simple magnifier is the eyeloupe shown with a spring retainer in Figure 2. It is difficult to find eyeloupes with a spring retainer now, but plain loupes from 2X to 5X are available at less than \$10.00.

Bi-ocular Magnifiers

Your local drugstore carries a very economical bi-ocular magnifier called reading glasses. The strongest sold is usually 3.25 diopter that give a little less than a 2X stereo view and are priced at \$8.00 to \$15.00. (The diopter is one meter divided by the focal length of the lens.) The "half glasses" allow quick orientation of your subject by looking over the top. Some people may be uncomfortable trying to converge the sight lines and maintain a stereo view so close to the face.

A solution is the head-mounted magnifiers, some with flip-up lenses that are available in 2X to 8X. These are designed with wedge shaped lenses to ease the strain of the converging sight lines. They are priced in the \$20.00 to \$50.00 range.

Shown in the background of Figure 2 is an inexpensive compound microscope that is found in magnifications from 20X to 100X. The higher mag-



nifications do not seem to have a consistent, good image quality so they should be carefully examined before purchasing. This type of microscope usually includes a "flashlight" to illuminate an opaque subject. They are particularly useful in the field for simple tasks. They are priced from \$5.00 to \$20.00. Some models can be focused below the plane of the foot. With these, you can examine a few of the problems on PC boards.

Compound Magnifiers

When you look into a compound microscope, you see the image at the end of a dark tube. How far away the image appears is determined by the eyepiece. How much of the subject you can see is determined, in part, by the focal length of the objective and the diameter of the field stop in the eyepiece. The field stop is a disk located at a focal plane within the eyepiece. It gives a sharply-defined limit to the image and also limits the image projected up the tube to the optically-corrected area.

As the focal length of the objective gets smaller, you get higher magnification and a smaller field of view. The common plan achromats (color-corrected objectives), when used with IOXWF eyepieces, have these approximate field diameters: 40X 4.5mm, 100X 1.75mm, 400X 0.45mm, 1000X 0.18mm. When you look at a printed circuit board and need a larger field of view or a greater depth of field, you must increase the focal length of the objective(s). Changing from a 10X eyepiece to a 5X will only make the image look farther away while the area covered by the image stays about

The approximate magnification of the compound microscope is determined by multiplying the magnification factor marked on the objective by the factor on the eyepiece. This is only an approximate value due to manufacturing variations and the settings of the eyepiece diopter adjustment. For accurate measurements, you will need the optics calibrated using a stage micrometer and a reference reticle mounted in the eyepiece.

Stereo Microscopes

Stereo microscopes are two compound microscopes mounted so that the sight lines converge at about a seven-degree angle. A typical fixed magnification stereo microscope is illustrated in Figure 3. This arrangement provides an apparent depth perception similar to that of the near point. These microscopes are designed primarily for those applications where there is a need to manipulate the subject. Image erecting prisms or mirrors are introduced into the optical train without which a direct stereo image could not be obtained.

Applications for stereo microscopes include: electronic surface mount placement and attachment, repair of fine mechanisms, quality control, and a long list of other applications. A single magnification model will cost from \$125.00 to over \$300.00. Two or more fixed magnifications will cost \$250.00 to \$1,000.00. Remember that at magnifications above 10X,

hand/eye coordination and tremor will bring more frustration than satisfaction for many placement tasks. It is the same problem you would have controlling handheld binoculars.

Locating solder faults and other QC work is more easily done at higher magnifications. Most of the current manufacturers provide good optics except for some of those sold in toy and hobby stores. The primary difference among different models and manufacturers is the quality of the illumination system and

the quality of the mechanical work.The graph (Figure 4)

illustrates the diameter of the field of view with different values of

magnification. It should only be used as a rough guide because of the variations from manufacturer to manufacturer. You would not be able to see a whole 16-pin DIP or the top of a TO-8 can at 30X.

In my experience, perhaps one-half to one percent of users have difficulty attaining or maintaining a fused stereo image from a stereo microscope. This is usually an example of the strong habit of combining the eyes focus and the convergence of the sight line. This is a learned response and can be overcome with practice. It often helps to focus the instrument on a subject, lift your head, and focus on a distant object, close your eyes, and place your head over the eyepieces and opening the eyes. The stereo view pops into view in most cases. Those who need to wear corrective glasses for astigmatism should look for designs providing high eyepoint eyepieces. The near or farsighted can usually use a microscope without glasses.

Zoom Stereo Microscopes

Stereo zoom microscopes are the industry standard for electronic assembly. As assembly people become more experienced, they like to work at increasing magnifications and the zoom optics provide a continuously variable magnification and depth of field. Most cur-

rent stereo zooms provide visual magnification from 7X to at least 30X. With auxiliary lenses and eyepieces, the range can be

expanded from 3.5X to over 200X. The cost of new instruments run from \$650.00 to over \$4,000.00.

Stereo zoom heads (pods) are sold installed in many designs of stands (Figure 5) and lighting systems, as well as a trinocular photo tube design for camera or video use. If your PC boards are less than 7.5 inches in the narrow dimension, then nearly all stand designs will allow you to work on the whole board. Larger dimensional subjects may require boom stands or other solutions.

Other Compound Microscopes

The average student and research grade compound microscope (under \$2,000.00) has a

maximum visual resolution of about 900X when using air to glass or oil immersion objectives in visible light. This is a result of

non of diffraction. For the technologist, the real guestion is not the degree of magnification but how much information is retained in the image. With a microscope set at 1000X visual magnification, you can take a photograph and print the image on a billboard at say

10,000X. There would not be

any more information than at

physical

limitation

of the

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Figure

900X, in fact there would be a lot less. Magnification alone will rarely be the main factor in microscopy.

There are no universal compound microscopes (those useful for every type of subject), although some in the \$50,000.00 range may come close. The purchaser must decide what information they are seeking, what lighting is needed, and the effort and type of sample preparation they are willing to perform to acquire a useful image.

There are hundreds of useful books on microscopes and dozens of excellent ones to help in the selection of the proper microscope for your application. You should be aware, however, that the selection of a specific microscope brand is like selecting a brand of automobile. If you ask an experienced professional for a recommendation, most will quote the brand they are using although the basic microscope has changed little in the last 75 years. All well-designed microscopes should last a lifetime with a reasonable amount of care while a good warranty will cover that rare one that slips through the quality control checks.

One, Two, or Three Eyes?

You would think that a binocular microscope would be inherently better than a monocular model; they certainly cost more. For short term use, it is hard to say. You need to balance the

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Figure

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image degradation of at least four air to glass surfaces in a binocular head against the discomfort of using a single eye. If you do not plan intense viewing sessions lasting longer than an hour at a time, a monocular model should work very well.

Do you need a third eye (a trinocular head)? It is difficult but not impossible to obtain excellent photomicrographs or videomicrographs with binocular heads. Because of the angle of the eyetube, it is difficult but you can configure a copy stand for photography. You need to figure about \$200.00 more for a trinocular head over the binocular. A good copy stand will cost a little less. Some trinocular heads blank out the two viewing eyepieces when in the photo mode while others allow a small

50 X

40 X

30 X

25 X

20 X

15 X

10 X

5 X

Figure

40

compared to a research model. However, student grade microscopes may provide all the image quality you need for non-critical use. The achromatic objectives used in this class of instrument provide a good image in the central 60% of the image field. Outside that area the image is not in focus in the same plane as the central area and color fringes increase.

Of course, if your subject is not flat it may not make much difference. Most of these

tives. They may or may not have both coarse and fine focus control. With 10X eyepieces and 40X objectives (400X), limit so adding a 100X objective to the instrument is not very

> pinch, you can view an opaque subject up to about 100X with a strong sidelight. Shown in Figure 6 is

upgraded. Student grade microscopes cost from about \$125.00 to \$500.00.

Figure instruments come with 4X, 10X, and 40X objecthe coarse focus mechanism has reached its practical. These instruments are designed with only transparent subjects in mind, however, in a Figure 6 one of the few student microscopes designed to be portion of the light to be projected to the eyes to track moving sub-

Advanced Grade Microscopes

Research grade microscopes are available in an enormous range of designs. Because laboratories and industries can afford instruments designed for specific uses, manufacturers modify their designs to fit specific applications. There are tissue culture microscopes with extended clearance objectives to focus through the bottom of a petri dish, metallurgical microscopes with reflective illumination for opaque subjects, and polarizing microscopes for counting asbestos fibers. The list goes on and on.

Wherever and from whoever you decide to purchase an advanced microscope, make sure they know your imaging problem and will help you solve it.

The cost of a quality fullsized biological microscope is about \$700.00. Such an instrument would have 4X, 10X, 40XSL, and 100XSL oil

objectives, a binocular head with 10XWF eyepieces, a mechanical stage, an Abbe' condenser, and a variable intensity light source. In Figure 7, is an unusual current product in that it has a vertical

illuminator built into the trinocular head for viewing opaque subjects as well as transparent ones. Someone somewhere has a magnifier to solve your imaging problem in the range of IX

Books and Other Sources

To decide the specifications for your new microscope purchase the book Exploring with the Microscope by W. Nachtigall/Sterling Publishing Co., ISBN #0-8069-0867-x; a winner at \$14.95. This book has over 100 color micrographs.

To familiarize you with the nomenclature and simple sample preparation, I recommend you invest in a Dover book titled The Microscope and How to Use It by Dr. G. Stehli, ISBN #0-486-22575-5; economically priced at \$4.95 (1996).

One of my favorites is the 1958 book Practical Use of the Microscope by G.H. Needham. The current price is \$99.00. This

book has just been reprinted and is available through McCrone Accessories at www.mccrone.com.

The Microscope Society of America has a website (www.msamicroscopy.com) with information on local microscope chapters, and an extensive bibliography is also available.

Get on the web and search with the words "light microscopy;" it will be a long list. NV

I can be reached at ilittle@netwizard.net for comments or brickbats. You can also write me at:

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Tell us the



An

RESOURCE BIN

number eighty five

Another look at some favorite websites.

ur usual reminder here that the Resource Bin is now a two-way column. You can get tech help, consultant referrals, and offthe-wall networking on nearly any electronic, tinaja questing, personal publishing, money machine, or computer topic by calling me at (520) 428-4073 weekdays 8-5 Mountain Standard Time.

Be certain to frequently check out my new Guru's Lair web site you'll find at (where else?) www.tinaja.com. This is the place you'll go for instant tech answers. Among the many files in our library, you will find complete reprint sets for all of the Resource Bin and other columns. Plus a brand new Research InfoPack Service.

You will get the best results if you have both Netscape Communicator and AcrobatReader 3.0 installed.

Where to go for what?

Quite a bit has happened since we last surveyed great places to visit on the web. So I thought it was way past time for an update. Needless to say, the web is where everything technical or electronic now seems to be coming down. You simply cannot afford to miss out. You can easily sample the web at your local school or library if you are not yet online.

We saw how to get yourself on the web in RESBN78.PDF. And secrets of web-based research in RESBN71.PDF.

You'll need a newer computer that supports Netscape or another modern browser. Perhaps a Pentium running Windows 98. Or a Linux box. While you can use Web TV (I feel this is an outright joke) or any national service such as AOL, I strongly believe a local ISP or Internet Service Provider is often your best way to go. Typical charges are around \$19.00 per month or less. This usually includes a CD-ROM or similar startup software.

You can pick up that latest Netscape Browser free at www.netscape.com. One useful local ISP is www.zekes.com.

Tip: Do look into the new wireless services being offered by a few ISPs. These can end up 400K fast, leave you connected all the time, and tie up no phone lines or have any telco or cable fees. But the transceivers are costly and you'll need line-of-sight.

If you are brand new to the web, you go to a site by booting Netscape and then entering a url address into the Location box.

NEXT MONTH: Don explores the denizens in the pseudoscience morass.

When you find sites you like, you save them by clicking on the Bookmark button. Much more on web use, from bare startups to fancy advanced home page design are at www.tinaja.com /weblib01.html.

You will find untold zillions of web sites active today. How do you locate the better ones? My choices here are simply based on the sites that I use most often. Instant "hot buttons" for linking most of these are now found at www.tinaja.com. Here are several of my current favorites ...

www.questlink.com

This is the place to go for electronic data sheets and all application notes. They are industry wide, and represent pretty near anybody and everybody. They also let you instant order small quantities of many harder-to-get ICs and semiconductors.

As with my own site and just about any other source of decent tech info on the web, you will need an Acrobat Reader to let you view their ap notes and data sheets. You get this free from www.adobe.com. For Acrobat utterly and totally blows HTML away on all counts. More info about this superb PostScript extension can be found at www.tinaja.com/acrob01.html and at my www.tinaja.com/post01 .html.

Additional electrical engineering links and link farms can be found at www.tinaja.com /eewb01.html. Since the link farms do such an incredibly good job here, I personally provide ee links only to the farms and the actual sites I have a repeating need for.

www.hotbot.com

This one is my favorite web search engine. You'll go here to find what is where on the web. Just type in some keywords, and dozens to hundreds of results get listed. Put the keywords in quotes when searching for a name or other exact match. You can also make use of their "links to this url" search as a great ego trip to find out just who is linking your own site.

There are hundreds of other engines. www.altavista.digital.com is quite popular, although I use it only for emergency backup. There's also

an "inference engine" that trys to gather together larger concepts for you up at www.infind.com. When this works, it performs very well. When it misses, it does so badly. An example of a meta search engine master site which links hundreds of others is www.kresch.com. They also offer all sorts of webmaster tools, free search engine submissions, and bunches more.

Books

My very favorite online bookstore is www.lindsaybks.com. Who specialize in republishing the "lost technology" titles on everything from old machine shop practice to his early radio books. The quickest way to reach them is to click through on one of their banners found on my website. More banners info on www.tinaja.com/advt01.html.

That 800-pound gorilla, of course, is Amazon Books. Who have now become the place to go to get any book on any topic. Reach them by way of www.tina ja.com/amlink01.html. I have also placed a few carefully selected book recommendations on dozens of topics here.

By the way, your use of this exact www.tinaja.com/amlink01 .html link to Amazon supports both your Resource Bin and the Ask the Guru web pages at zero additional cost to you.

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trade journals. Find these at www.mediafinder.com.

Online and E-Mail publisher linkings often do get provided in their listings. But sadly, Oxbridge does not give you complete snailmail addresses as a free service. Instead, you may have to use the backwards phone finders found at in-123.infospace.com or at www.anywho.com to pin these

Additional phone number sources and other useful web utilities appear at www.tinaja.com .webwb01.html.

RESOURCE BIN

SOME RECOMMENDED WEBSITES

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www.drms.com

This is your main site to go to for military surplus sales. As we've seen, there's all sorts of incredible surplus bargains these days. It is now super easy to bid on the web and pay by VISA. We saw lots of details on the access secrets a few months back in RESBN81.PDF and RESBN82.PDF.

Examples of the gettable goodles are at www.tinaja.com/barg01.html.

For convenience, I've split this site access up into these four hot buttons at www.tinaja.com ...

DRMS1 — DOD stuff for sale
DRMS2 — Preliminary results
DRMS3 — Final sales results
DRMS4 — Master search engine

What I'll personally do is grab the info off the web. Then I print it and stash it in a time ordered box. First the descriptions, then their offerings, and finally a search on items of any special interest. The latter to find their condition and acquisition cost. I will also try to actually inspect their lots when and where feasible. Or have them inspected for me. I'll then worry about and revise the bids for a week before submitting them.

The general object of the game is to buy for a penny on the dollar, sell for a dime, and then try to make a nine percent profit. But lately, I have been bidding far lower. When you win too often, you're paying way too much.

The feds are experimenting with private surplus sales. An outfit called *Levy-Latham* is now handling some of the federal surplus auction offerings.

Be sure to check out their website at www.levylatham.com.

Maps and Aerial Photos

I have long been a topo map freak. Besides having handled my share of underground cave mapping. There's a wide variety of map-related websites that are good and getting better.

Start off with www6. MapsOnUs.com. These folks sell "roadmap" style maps and trip planning routes. I've found them to be exceptionally useful.

I recently got off on the wrong 4WD track near the Galiuro Wilderness. I was utterly amazed to find this trail online, and was quickly able to "fly" on over to the Powers Hill trail I was really looking for. On the other hand, Maps On Us seems to refuse to let you go over Mule Creek pass or through the "tunnel" in Lordsburg.

A useful second alternate here is *MapQuest* at *www.mapquest.com*. Who I have found almost as good.

The actual USGS topo maps are still at their "stumbling first steps" stage. Although I'd expect a superb quality free site shortly. That seamlessly lets you print and map to high res.

Meanwhile, there is a new USGS map site up as Map One and found at www.horizons.com/suremaps. This one seems more interested in selling stuff than presenting it online. They seem to have missed the essential fact that web success depends on giving a lot away to sell a little.

Somewhat poorly scanned versions of the USGS maps themselves (sadly with those infuriating borders intact) are sold by www.bsinet.com/map1 and a few others. Prices are around \$16.00 for 64 quads and a viewer.

Yet another "almost but not

quite there" is the outrageously fascinating Terra Server image base that's up at www.terraserv er.microsoft.com. This one offers free "flyby" topographic and satellite maps. Down to one meter per pixel resolution, even. There are over four terabytes of data here!

But even with the latest additions, the coverage remains limited. It does take a lot of practice to interpret aerial photos. Especially if they are in black and white and lack a stereo viewing. Things sure get confusingly fuzzy and blobby at maximum resolution. But I would expect hires stereo color maps online within a year or two at most.

Runway maps and other pilot info for airports is at www.airnav.com.

These are especially handy if a pilot is going to visit you. But they seem to have left Thatcher International off their list. Probably because there's a few old refrigerators and other minor debris where the runway used to be.

Finally, I have found the USGS real time stream gauge site to be quite interesting. White water folks consider this data essential, while I've found it handy to spot out which remote 4WD crossings are and are not passible. It is also fun watching floods move down through the Gila Valley.

Try out wwwdaztcn.wr.usgs .gov or some similar page for your state. Be sure to check these out.

Patents

Patents tend to be highly overrated. Since not one patent in two hundred ever shows a net positive cash flow, a patent repository is mostly of, for, and by losers. Studying patents can (and almost always does) end up as a mind-rotting waste of time.

Nonetheless, there is an intriguing site up at patent.wom plex.ibm.com. This one has summaries and full images of most patents back to 1971, along with collections of other IP info.

More on the perils and pitfalls on patents and patenting are found at my www.tinaja.com/patnt01.html. Along with my tested and proven real-world alternatives.

Bee's Favorites

Bee is an unindicted Guru's Lair co-conspiractor. Her tastes in web sites are wildly different from mine. At any rate, here are some of the sites that Bee uses the most ...

For investments, stock quotes from quote.yahoo.com and the actual trades at www.etrade.com. This one does take a membership and investment. For free medline access, www.healthy.net.

For movies, us.imdb.com.
For timely customer package real time tracking, www.ups.com.

For postal rates www.usps.com. Or their zip code directory over at www.usps.gov

Plus, of course, Dilbert who is over at www.unitedmedia.com/comics/dilbert. Virtual flowers at www.virtualflorist.com. And don't forget the essential hacker nutrients at www.mohotta.com.

Bee is also very much into string bending, so two sites of major interest are a weaving guild at www.weavespindye.org plus the weaving links at www.ghgcorp.com/stilgar/shuttlelinks. Additional craft links of all flavors are found at www.craftsfairon-line.com.

There is also the new www.ebay.com auction site. But this one can end up a giant time and dollar sink.

Lots of additional annotated links (similar and otherwise) can be found at www.tinaja.com/beewb01.html.

Plus a Few More of Mine ...

Such as that periodical table of the elements chem info you should find at www2.shef.ac.uk/~chem/web-elements. Or the extensive job opportunities at www.datamation.com/PlugIn/jobs/, obs.html or at www.monster.com. Or blue book car values at www.kbb.com. Or car sales at www.classifieds2000.com.

Or the good old Thomas Registry at www.thomasregister .com. That web url registration site up at www.internic.net. Or their Whois site finder service up at www.internic.net/cgi-bin/whois. Or finders people at www.whowhere.com. At www .drebes.com. At www.bigfoot.com. Or at www.infospace.com.

More of my favorites are found at www.tinaja.com/dtekwb01.html or at my www.tinaja .com/dntkwb01.html.

For More Info

Annotated links to many hundreds of other useful web sites are found on various pages of my www.tinaja.com. I also have a service where I can do fee-based research for you. Web centered or otherwise. Many times I can find better and more useful answers a lot quicker than you might by yourself. See www.tinaja.com /info01.html.

We also have a unique consultant's network of individuals which I can personally recommend for just about any technically related task. You will find their links and capabilities up at www.tinaja.com/consul01.html.

There's also my US no-fee helpline service as noted below.

This Month's Contest

As our contest for this month, just tell me about your favorite web site and why you like it.

There'll be a dozen or more of my new Incredible Secret Money Machine III books going to the better entries. Plus an all expense paid tinaja quest for two (FOB Thatcher, AZ) going to the very best of all.

Send your written and snailmailed entries on this contest directly to me here at Synergetics. Let's hear from you. NV

Microcomputer pioneer and guru Don Lancaster is the author of 35 books and countless tech articles. Don maintains his no-charge US tech helpline found at (520) 428-4073, besides offering all of his own books reprints, and con-sulting services. Don also offers a free catalog full of his unique products and resource secrets. The best calling times are 8-5 on weekdays, Mountain Standard Time.

Don is the webmaster of his Guru's Lair found at http://www.tinaja.com. Full reprints and preprints of all Don's columns and ongoing tech support appear here. You can reach Don at Synergetics, Box 809, Thatcher, AZ 85552. Or send any messages to don@tinaja.com.

TECH FORUM

CONTINUED FROM PAGE 73

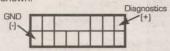
Now, when you connect your sensor's signal to pin #3 of the LM 358, a signal 10X as large will appear at

> Thomas Ng San Jose, CA

ANSWER TO #129816 - DEC. 1998

You can use an analog voltmeter to retrieve the trouble codes from the on-board computer. The diagnostic connector and voltmeter hook-up varies with the model and

On the Galant, Starion, Van, Montero V6 [1987 and 1988] and all models 1989 and on, the diagnostic connector is in or under the glove compartment. To retrieve trouble codes, connect the meter as



On 1983 to 1986 models, the diagnostic connector is located under the battery tray or the right side firewall near the computer.

On the Mirage Turbo [1987/1988], connect the meter to a good ground and the single connector on the firewall near the set timing connector.

Turn the ignition on and watch the voltmeter, count the number of sweeps. The meter will sweep every 2 seconds in a 10 second period. The codes can be determined as fol-

00000 = 0

10000 = 1

01000 = 2

11000 = 3 etc.

This is based on the binary numbering system.

You should consider buying a scanner instead of trying to build one. The two companies most likely to have a scanner to fit your needs are: OTC Tools, 655 Eisenhower Dr., Owatonna, MN 55060. Or Snap On Tools, Inc., Kenosha, WI 53141-1410, Phone number is 414-656-

> Dennis Gifford Henagar, AL

ANSWER TO #129810 - DEC. 1998

The FUJITSU M2312K disk drive is (according to the FUJITSU CE manual) an 84MB SMD disk drive. Transfer rate is 1.229 MB/sec. It requires +5, +24, and -12 volts

Digital Equipment Corp., Prime Computer, Data General, and many other manufacturers used them either as OEM drives, or third-party companies made controllers to use them with the previous computer manufacturers.

I have two of them hooked to a DEC 11/73 computer, and they make quite a bit of noise and heat.

Joe Heck Wrentham, MA

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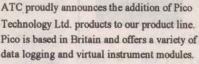






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- Acoustic Research

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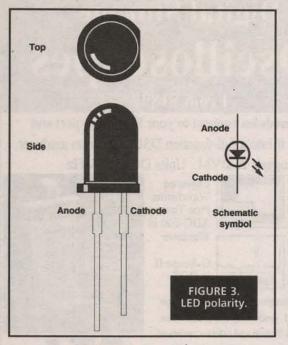


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ing you so the SIMMStick's notch is to the lower left, C1 goes in the upper left corner of the board just above C5; C2 goes to the right of J1.

When you've completed the power supply section of the DT101, apply 9V to SS-Bus pin 4 and ground to pin 9. First, test the voltage at the output of the voltage regulator, then at pin 14 of E1, and finally at pin 7 of the SS-Bus; you should read a nice, clean +5V at all three points.

If any of these tests fail, go back and check your solder joints and check continuity of the board against the schematic. In particular, make sure you have continuity between E1 pin 5 and SS-Bus pin 9 (the ground connections) and then between E1 pin 14 and Vdd (the +5V supply). Verify power and ground connecground connec-tions for all the options you install. A good way to do

this is to use a highlighter and a photocopy of the schematic; highlight each connection as you probe them out on the board until you either find a problem or you run out of circuit board traces.

0000

0000 1683 0001 1006

0002 1283

0003 1B86 0004 2803

0005 1006

0006 1F86 0007 2806

0008 1406

0009 2803

LOC OBJECT CODE VALUE

00002

00036

Reset Circuitry

The minimum reset circuitry consists of two 10K ohm resistors R1 and R2; in the absence of other reset circuitry, they function as a 20K pull up

Constantly polls input bit for switch closure, indicates result with LED 00004 00005 00006 LIST P=16F84, F=INHX8M, R=DEC errorlevel 0,-305
INCLUDE "\pic\mpasm\P16F84.inc" 00007 00008 00001 00002 00136 ; P16F84.INC Standard Header File, Version 2.00 Microchip Technology, Inc. 00009 00010; Configuration Registers 00011 2007 3FF2 00012 CONFIG _CP_OFF & _WDT_OFF & _HS_OSC & _PWRTE_ON 00013

00015 00016 org 0 00017 00018 00019 STATUS, RP0 TRISB & 0x07F, 0 STATUS, RP0 hsf bcf 00020 bcf 00021 00022 wait 00023 btfsc PORTB,7 goto wait_ON 00025 00026 bcf PORTB,0 00027 00028 wait_OFF 00029 00030 00031 btfss PORTB,7 goto wait_OFF 00032 bsf PORTB,0 00033 goto wait_ON 00035

LINE SOURCE TEXT

00001 title "test1 - Poll a Bit"

; Set RB0 to Output

; Wait for switch press

; Turn LED ON

Wait for switch release

Turn LED OFF

on the MCLR\ or Res, SS-Bus pin 8. In addition to these two resistors, you can install a reset IC. Note 1 in Figure 1 gives a list of optional brownout voltage detector reset ICs that will work for this board. While strictly not required - my DT101 worked fine without one - I find these reset chips to be quite valuable in that they increase reliability and predictability of the reset action, and I plan to install them in all future boards.

When a reset chip is installed, R2

serves to limit current at the OUT pin of the reset IC, especially for CMOS versions with an active pull up, such as the Panasonic MN1381-S; for open collector versions, R1 functions as the pull up resistor.

While you are soldering in the above reset pull up and current limiting resistors, you might as well solder in R3, too. It pulls the MCU's RTCC input high so the pin doesn't float, leading to possible spurious counts at the RTCC input.

To test these components, mea-

sure the resistance between SS-Bus pins 7 and 8 (between Vdd and Res) without power applied to the board; it should read about 20K ohms. If you have installed one of the brownout reset ICs, measure the voltage at SS-Bus pin 8 while gradually increasing a variable DC input at SS-Bus pin 4 (Vin) from 0V to 9V. The Res line should stay low until Vin reaches somewhere above 4.5V, at which point it will jump up to about the same level as Vdd. If you temporarily tie the Res line low, pin 4 of E1 should also drop low, regardless of the voltage at Vin.

Oscillator Section

The oscillator section is just two 15pF capacitors, C4 and C5, and a 10-MHz crystal. If you choose to use a three-lead ceramic resonator with built-in load capacitors, you don't need C4 and C5. In any case, make sure that the load caps (built-in or external) are between 15pF and 33pF to ensure reliable oscillator start-up.

Finish up the SIMMStick hardware by plugging in a programmed PIC16F84, and you're all set.

What? You don't have a pre-pro-grammed F84? Check out the December '98 "Amateur Robotics Notebook" for PIC programmer resources. As I said then, I use two dif-

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ferent parallel port programmers the DonTronics DT001 and the Parallax PIC16Cxx-PGM; I use these with Igor, the 386 DOS machine I keep chained up in my basement.

The DT001 can be configured to program individual chips, to program SIMMStick boards in-circuit, or to function as a SIMMStick motherboard, with lots of expansion connectors and an RS-232 communications port. It comes as a bare PC board directly from DonTronics in Australia or from any of the numerous SIMMStick distributors worldwide. It costs about \$75.00 US to build if you install all the many options DonTronics has provided.

The Parallax PIC16Cxx-PGM costs a bit more than the DT001, but it comes already built and can handle a wider range of PIC chips, including the older 12-bit core family, which uses a different programming method than Microchip's newer PICs. It's available in a "Hobbyist Pack" for \$109.00 US from Digi-Key.

If you use the Parallax programmer, you'll be using Parallax's own programming software, which is well described in the manual that you can download from their website. If you've never built a microcontroller system before, you may want to

go this route just so you have one less

piece of hardware to debug.

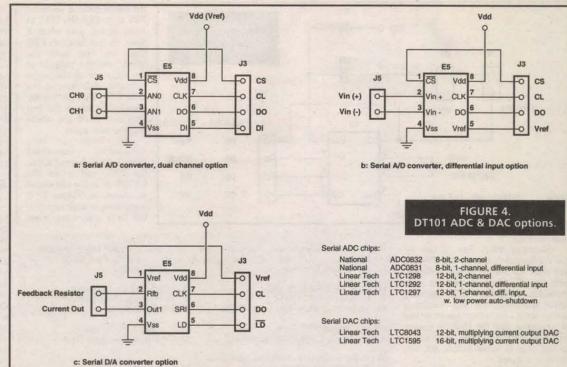
To use the DT001 as a programmer, you will need to download an appropriate version of Nigel Goodwin's PIC84PGM software. You can find all his versions for DOS and Windows at: http://www.lpilsley.demon.co.uk/programs.htm. You can also find the software at DonTronics at http://www.dontronics.com/download.html. The latest version of the DOS software is at http://www.dontronics.com/zip/pieprog2.zip.

The DOS screen capture shows the various menu options for the PIC84PGM software. Use "M" to toggle between the PIC16C84 and the PIC16F84 (you want the latter), "H" to load your hex file, and "P" to program the chip. Easy. Unless your parallel port doesn't want to talk with PIC84PGM.

This happened to me. For some reason, Igor's parallel printer port wasn't recognized by PIC84PGM. Installing a cheap \$13.00 parallel port card in Igor solved the problem. Be sure to read all of Goodwin's documentation, too, because he has a couple command line switches that invoke debugging modes of PIC84PGM to help troubleshoot parallel port problems. "/D" turns on a debugging mode that shows program initialization details, in particular the PICPROG. CFG setting. Another handy debugging mode is the "/T" test mode option which helps sort out problems with the connection between the parallel port and the programmer.

Igor, Bring in the Hex!

None of the above will do you any good if you don't have a .HEX or .OBJ file to load into the program buffer. TESTI.ASM is a simple test program to exercise the DT101 hardware, and TEST1.LST shows this same file after it's been assembled by MPASM. I've



been using both the Parallax assembler and Microchip's MPASM for my PIC development work, but here I'll just talk about MPASM.

MPASM is available for free download from the Microchip website ("asm22000.zip" is the file you want). It comes with all the INCLUDE files for every PIC Microchip makes; this means you don't have to retype all of the register names and equates; for working with the PIC16F84 chip, you just include the P16F84.inc file in your source file (see line 8 of TEST1.LST).

While you're visiting the Microchip site, you might also want to download MPSIM, a software PIC simulator. This program has a horrible user interface (more about that next time), but it is free and it runs under DOS so computers like my Igor can handle it. For those of you running Windows (the majority, I suppose), you

might want to try MPLAB, instead. It does everything that MPASM and MPSIM do (and quite a lot more), it's also free, and the MPLAB simulator interface is far superior to MPSIM. The point is, you need to get yourself set up with one or another of these packages.

This is Only a Test ...

The simplest blinky light program uses great gobs of time delay loops to make the LED change state slow enough that the human eye can perceive the blink. Another, only slightly more complicated system, is a program that causes the LED to turn on and off in response to an external input, say, a switch. The software is actually simpler to write for this one, and the extra hardware is just a switch and a pull up resistor, so that's what I've used (Figure 2). The code for this

is easy (see TEST1.ASM).

If you've never worked with assembly language before, TESTI.ASM may seem quite daunting. It's really quite simple, though. I'll use the TESTI.LST file to show, line-by-line, what's going on.

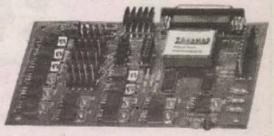
Lines 1 through 5 are just title and comments, all of which the assembler ignores when producing code; they're just there to help you, the programmer, keep track of what you're doing. Line 6 tells the assembler that we want to use the PIC16F84 chip, that we want the output file (the ".HEX" file) to be in the form of an eight-bit Intel Hex format (nevermind, trust me), and that we want to use decimal numbers as the default. Line 7 sets up which types of error messages will be displayed during assembly. Line 8, as I said above, includes the standard equates and goofy register names that Microchip

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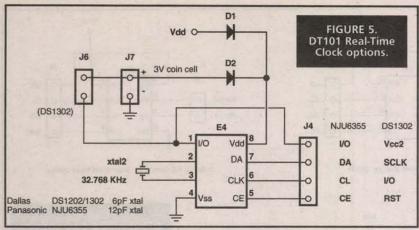
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the above code; it waits for PB7 to go high (for SW1 to open again), and when it does, on line 32 it sets PB0 high, so that both the anode and the cathode of the LED are at the same potential, thus turning the LED OFF. Line 34 merely goes to the top of the first loop and starts the whole process over again.

So, when you have successfully assembled TEST1.ASM, burned it into the PIC, and wired the DT101 up in the test circuit as shown in Figure 2, if everything is working right, the LED will shine when

install a MAX-232 for serial communications with your PC or other SIMMSticks, you can add on a I2C serial EEPROM for expanded data storage (Figure 1), and you can even add an ADC or a DAC (Figure 4) for analog I/O capabilities, and a real-time clock and calendar (Figure 5) so your robot will know what time it is and (maybe) what all the fuss is about Y2K. Feel free to experiment with any or all of these but, for the next few installments, I'll be concentrating on what you can do with the core circuit to make some really cool robots.

GrowBot?

Speaking of cool robots, I'd hoped to give a hands-on review of Parallax's new Growbot kit this month, but I haven't been able to get ahold of one yet. The basic configuration of GrowBot will be familiar to anyone who has followed the Breadbot series (i.e., bow-tie bumper up front, same wheel size, two servo motor drive, four AA-cell holder slung underneath, with a BS2-IC for the brain), but it's a slick, expandable design that uses a printed circuit board for the body of the robot instead of a solderless breadboard. Also, they've considerably simplified the caster arrangement, using what appears to be a plastic ball to act as a rollerskid (rolls forward or backward, skids sideways).

They've also got a serial programming port and a couple expansion ports for "AppModules" which stack on headers in the middle of the robot. One AppModule is apparently a solderless breadboard, another is a board suitable for wirewrap or point-to-point breadboarding. The Parallax website also has hints of AppModules such as "ISD Mobile Recording Studio," "LED Display Terminal," and "Infrared Proximity Sensor." I can't wait to get my hands on some of these. As soon as I do, I'll let you know all about them. I'm not sure what the price will be by the time you read this, but it should be \$150.00 to \$180.00 US range.

Winding Down

I still haven't got the Breadbot wheel encoders working yet. I've been promising them for months now, I know. Let me just say I haven't forgotten; accurate wheel encoders are essential for my future plans with Breadbot.

Finally, I've been doing some more inspirational reading from the Lindsay Publications catalog. This month's book of the month is actually seven books, namely the seven-volume Build Your Own Metal Working Shop from Scrap series by Dave Gingery. If you haven't heard of these books, then you really should take a look.

As always, if you have suggestions for improving Breadbot, if you've built a Breadbot, or if you have questions or comments about amateur robotics topics, you can reach me at:

> **Robert Nansel** 69 S. Fremont Ave. #2 Pittsburgh, PA 15202

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uses for PICs

Skipping down, line 12 sets up the configuration bits for the F84; in this case, the F84 is being configured with the CP Code Protect for code protection OFF, the WDTE watchdog timer disabled, the HS oscillator option set up for a high speed crystal , or resonator, and the PWRTE powerup timer enabled (to make sure power to the chip is stable before the PIC starts execution).

Line 16 sets the start of the program at address location zero. Line 18 switches to RAM Bank1 to access the TRISB register, line 19 clears bit0 of TRISB to set up Port B bit0 as an output, and line 20 switches the RAM bank back to BankO. Now the preliminaries are over, and the main program begins.

The Big Moment

Lines 22 through 24 constitute a simple two-instruction loop that waits for the switch SW1 to be pressed (see Figure 2). In line 23, "btfsc PORTB,7" does a bit test on Port B, bit 7 (PB7), and it executes the next instruction only if PB7 is set high; that is, it skips the next instruction only if PB7 is clear. As long as the SW1 remains open, PB7 will be pulled high through R1, the goto instruction will not be skipped, and the wait for SW1 to be PIC84PGM Programmer WDT: No PUT: Yes Prog Data Loaded:

.01a Copyright (C) 1997 Nigel Goodwin. Osc type: HS Printer Port: \$378 Hex Data Loaded: Version 2.01a CP: No

H: Load HEX file from disk.

Program target 16x8x. R: Read program & data from 16x8x.

Alt-W: Toggle WDT Fuse. Alt-C: Toggle Code Protection Fuse.

W: Write Program in buffer as HEX file. D: Disassemble program in buffer.

C : Clear Buffer.

A: About PIC84PGM Programmer

E : Erase Target 16x8x.

O: Load OBJ file from disk. V : Verify programmed 16x8x S : Display Buffers.

Alt-P: Toggle PUT Fuse, Alt-O: Toggle Osc Type Fuse.

M: Micro Type - 16F84

T: Card Type - SINGLE

Q: Quit programmer.

pressed will continue.

When SW1 is finally pressed, PB7 drops low and the "btfsc PORTB,7" instruction skips over the "goto wait_ON" instruction. What happens next is that "bcf PORTB,0" is executed, which clears Port B, bit 0 (PB0).

Recall from lines 18 through 20 that PBO was set up as an output; when PBO is cleared, that puts a voltage near ground on the cathode side of the LED, with 6V already present on the anode. This allows current to flow through the LED, thus lighting it up.
The code contained in lines 28

through 32 does just the opposite of

you close SW1 and go dark when you open SW1.

It's a pretty round-about way to light up an LED, I know, but it will give you a definite go/no-go assessment of your SIMMStick, and once you have confidence that the DT101 is working (VROC, remember?), then you can dive into more interesting software. But that will have to wait until next time.

DT101 Options

I've not even scratched the surface of the DT101, of course. You can



In Volume 1, you build his Charcoal Foundry with which you learn to make aluminum castings in green sand molds. Volume 2 - The Metal Lathe - details how you use those aluminum castings from the foundry to build a precision bench-top metal-cutting lathe with a 7" swing and 12" between centers. You then use the lathe and the foundry to build practically everything else required for a fully-equipped machine shop, including The Metal Shaper in Volume 3; The Drill Press in Volume 4; the Milling Machine in Volume 5; and Dividing Head & Deluxe Accessories in Volume 6. Volume 7 — Sheet Metal Brake - doesn't require the lathe or other tools of the earlier volumes, though it does require some welding and simple drilling.

Can you build a whole metalworking shop from scrap? Well, Dave Gingery has done it, and so have quite a few others. The only precision tool Dave used for building his first lathe was a blade-type feeler gauge, yet that same lathe holds to within 0.001" taper an eight-inch piece of stock, pretty impressive for a \$50.00 homemade lathe!

Many others have built Gingery machines, too, just by following his directions. I know, I've talked with some of them. Gingery isn't a professional machinist or a foundryman, and you don't need to be either to use his books to build your own machine shop. Gingery's a dedicated amateur who likes to build precision machines, be they lathes or steam engines, and I think robot builders can get a lot of insight from his books. The whole seven-volume set costs about \$60.00, but none of the individual books cost more than \$10.00 US, so you can check them out one at a time, if you want. By all means, though, at least get "The Charcoal Foundry," because that is the foundation from which the rest of the series builds.

That's it. Next month, I'll continue with the DT101 brain transplant, with a few surprises thrown in. NV

Item	Description	Vender	P/N
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C5 C6 C	15 pF 5% monolith ceramic cap 7,C8 1µF, 16V tantalum		P4839-ND P2105-ND
D1,D2	Schottky diodes (see Figure 5)	W - 10	11DQ03-ND
E1*	10 MHz PIC16F84 MCU		PIC16F84-10/P-ND
E2 E3	24LCXX I2C EEPROM RS-232 level converter		MAX232CPE-ND
E4	Real-Time Clock option (see Figure 5) = ·	WIANESEOF E-IND
E5	ADC/DAC option (see Figure 4)		
J1,J2,		NA ST	200017 00 00 110
J5-J7 J3.J4	2-pin single row straight pin header 4-pin single row straight pin header		929647-02-36-ND
00,04	J1-J7 above are cut from 36-pin pin h	eader	
J8*	30-pin single row, RA pin header		S1111-30-ND
R1*,R2*	,R3*,R4,R5 10K ohm Reset Voltage Detector, 4.5V, CMOS	12 Th	10KQBK-ND MN1381-S-ND
PCB*	DT101 or DT111 SIMMStick	Wirz Elex	
VR1	+5V positive regulator, 100 mA,		
MTAL 44	TO-92	Digi-Key	NJM78L05A-ND
XTAL1*	10 MHz crystal, HC49/US case 32.768 KHz (see Figure 5)		X422-ND
Misc:	02.700 Tale (000 1 iguit 0)		
	8-pin DIP IC sockets	Digi-Key	ED3308-ND
	16-pin * * *	-	ED3316-ND ED3318-ND
	18-pin " " " Shorting jumper (to isolate		ED3310-IVD
	+5V from Vdd		SPC02SYAN

^{*} Required components; see text & figures.

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165 XELTEK ROMMASTER II 99 EPROM 16 TO 1 MEG
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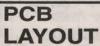
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ELCAD (Electronic Computer-Aided Design) is a simple, \$14.95 software program for the IBM PC with Windows 3.1 or 95. It allows you to do some fairly complex electronic calculations easily and quickly, and print out the results.

here are a number of ways that electronic circuits come into being. Some hobbyists and professionals have the "knack" and the experience to put together solidstate circuits with the proper transistors and integrated circuits, using the correct resistance, capacitance, and inductance values, with little apparent effort.

Some build a circuit using the

already designed to do the job, commonly created by designers using data sheets and books full of electronic formulae.

With the advent of the computer, circuit design has become more available to hobbyists and experimenters using some sophisticated software, most costing hundreds of dollars.

But what if you just need to do some occasional circuit design that doesn't justify the cost and time to learn to use the expensive

many commonly-used electronic calculations. Probably the best way to illustrate this is to describe how the program operates and the kind of calculations it performs. You can then decide for yourself how it might be helpful in your situation.

by Fred Blechman

FEATURES

ELCAD does 23 different types of calculations, as well as presenting the resistor color code in a graphical manner. The calculations include: Ohm's Law for DC and AC circuits; parallel resistors; RC time constants; power supply ripple filter capacitance; singlelayer coil windings; transformer

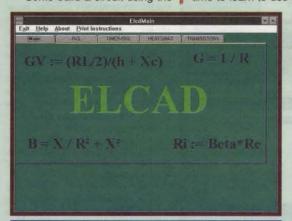


Figure 1. ELCAD Main Menu offers four category 'tabs" for calculations.

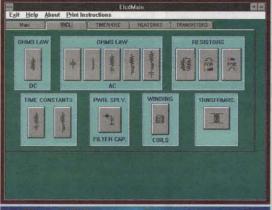


Figure 2. RCL screen offers seven types of calculations.

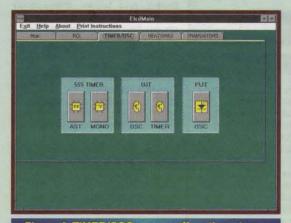


Figure 3. TIMER/OSC screen offers three types of calculations.



Figure 4. HEATSINKS screen offers three types of calculations.

"cut and try" approach, eventually getting to the proper component values

> Others follow schematics

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In all cases, context-sensitive HELP files are available for every screen, and the entire HELP file can be printed out. Navigation between screens is effortless.

Each calculation screen shows a schematic, and the appropriate boxes to enter data. The results are shown, and can be printed out for future reference.

To give you an idea of how the program works, we'll briefly cruise through many of the functions.

MAIN MENU (Figure 1)

No formal installation is required. Just run ELCAD.EXE from the supplied 3.5-inch diskette while in Windows, and the Main Menu screen pops up.

The menu bar at the top of the screen lets you "Exit," or get "Help" about this screen, or get details "About" ELCAD, or Instructions" (the entire Help file). ALT-H or F1 on any screen will also call up context-sensitive help.

Using the mouse is the easiest way to maneuver through this program. All mouse clicks are with the left mouse button.

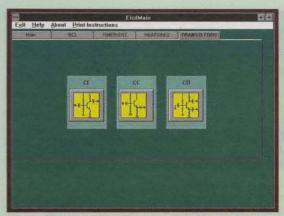


Figure 5. TRANSISTORS screen offers three types of calculations.

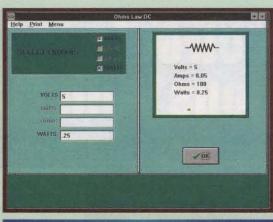


Figure 6. Ohm's Law DC Calculation.



Figure 7. Ohm's Law AC Calculations.

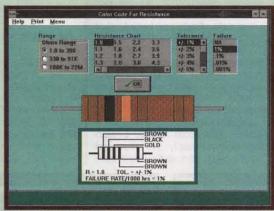


Figure 8. Resistance Color Code.

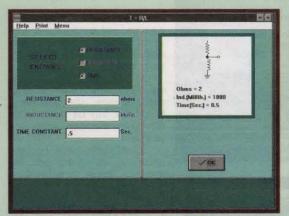


Figure 9. Time Constant Calculation.

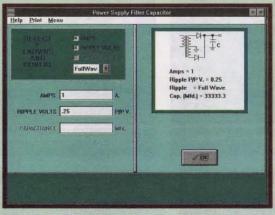


Figure 10. Filter Capacitor Calculation.

Five categories are shown as tabs near the top of the screen. Using the mouse or arrow keys, you select the category you wish to access. Figures 2, 3, 4, and 5 show each of the category screens.

RCL CALCULATIONS

Ohm's Law for DC Circuits

Figure 6 shows typically how most of the ELCAD screens work. You select those items for which you have data, and the rest are calculated. The results are then displayed and can be printed out.

On this screen VOLTS, AMPS,

OHMS, and WATTS are the variables. You simply check the boxes for the items for which you have data. When check box titles go gray, there are enough selections to compute for the grayed items.

For example, suppose you need a resistor to dissipate .25 watts at 5 volts. Put a check in the box by VOLTS and WATTS. The AMPS and OHMS check boxes become gray. The VOLTS and WATTS titles become black, ready for you to enter 5 and .25, respectively.

You use the tab or mouse to select the edit box, and enter the data. When you click on the OK

button, or press Enter, the Amps and Ohms calculations are displayed in the white box to the right. To print out the results, just click on PRINT. To return to the main menu, click on MENU.

Ohm's Law for AC Circuits

Five screens allow you to calculate: capacitive reactance; inductive reactance; resistor and capacitor in series; resistor and inductor in series; or resistor, inductor, and capacitor in series. The latter screen is shown in Figure 7.

As you can see, there are 11 different data entry boxes available

here, but you only need to use some. When you "Select Knowns" by checking boxes at the top left of the screen, the values that can be calculated turn gray.

For example, suppose you want to know what size capacitor and inductor to use at 1000 Hz to get a capacitive reactance of 1000 ohms and an inductive reactance of 500 ohms, and what size resistor is needed to get an impedance of 1000 ohms and what wattage resistor is needed at 100 volts. This is not a simple calculation, since there are so many variables. But it's easy in ELCAD.

You select the knowns: FRE-QUENCY, CAP.REACT, IND.REACT, IMPEDANCE, and VOLTS, and enter the data in those boxes. Click on "OK" and answers are instantly displayed in the white box to the upper right. The watts shown are for the resistor. Simple!

Resistors

Three screens are available for resistors. The first is for up to six resistors in parallel. The calculation for two is easy, but much more involved for six! The real "plus" here is that you can also calculate an unknown parallel resistance — together with up to five others — to make the combination equal to a desired value. This is real handy when trying to trim a circuit.

The other two screens in this section show resistor codes; one "decodes" known resistor color bands, the other shows the bands to look for when seeking a particular value of resistor. These screens go beyond just the three normal bands, and include tolerance and failure rate band colors.

Figure 8 shows the determination of color codes for a desired resistor value. In this case, 1 ohm with a 1% tolerance and 1% failure rate indicated the bands would be (left to right) brown, black, gold, brown, and brown. Interestingly enough, the actual colors are shown (within the color accuracy of your monitor settings).

Time Constants

Two screens are available. The first calculates the time constant for a resistor and capacitor in series, a fairly common (and simple) calculation. The time constant value is the time it takes for the capacitance to be charged to 63% of its full potential charge level.

The other screen allows the calculation of the time constant for a resistor and inductor in series, much less common. Here the time constant value is the time it takes for the induced current to reach 63% of its full value.

For the example shown in Figure 9, we entered a resistance of 2 ohms and a time constant of .5 seconds to determine that the

inductor would need to be 1000 millihenries. Of course, either of the three variables can be calculated from any two specified values.

Power Supply Filter Capacitor

On this single screen, you can determine the proper size filter capacitor for a desired ripple voltage with either a full-wave or half-wave power supply operating at a designated current. Or, knowing the capacitance used, you can calculate the ripple at a particular current.

As shown in Figure 10, you select two knowns and either full-wave or half-wave. We wanted to know the size filter capacitor to use to have .25 ripple volts with a full-wave supply delivering 1 ampere. We would need a hefty 33,333 microfarad capacitor!

Air Core Coil Inductance

The inductance of a singlelayer air-core coil depends on its length, radius, and turns per inch. The wire size determines the turns per inch if close wound. With this screen, as shown in Figure 11, you can either find the total number of turns or the inductance by entering the proper values. Notice that a WIRE GAUGE window pull-down allows you to select wire gauge, and shows turns per inch (TPI) for the selected gauge.

This is no trivial calculation. We wanted to calculate what it would take to make a 10 microhenry air core coil using 8-gauge wire wound on 1-inch radius for a length of .5 inches. The result shows this would take 11.8 turns of wire. Alternately, we could have calculated the inductance using the radius, length, and number of turns.

Transformers

Figure 12 shows the transformer calculations, where you select the data you have, and the program calculates the result. For example, say you have a common collector transistor audio output stage that gives you a 10-volt RMS output. You want to deliver a 0.5 watts of power to an 8-ohm speaker.

To deliver 0.5 watts to an 8-ohm speaker, you would need 2 volts RMS. (This is based on volts = square-root of the product of the watts and resistance. In this case, voltage is the square root of .5 watts times 8 ohms, or the square root of 4, which equals 2. Oddly, this calculation is NOT done by the program!)

Checking PRI.VOLTS, SEC.VOLTS, and SEC.IMPED, and entering 10, 2, and 8, respectively, in those boxes yields a result of 200 ohms for the primary impedance needed.

TIMER/OSCILLATORS

555 Timer

Two different configurations of

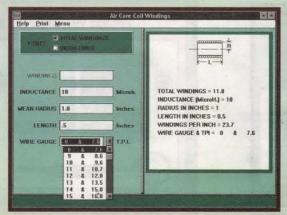


Figure 11. Air Core Coil Calculation.

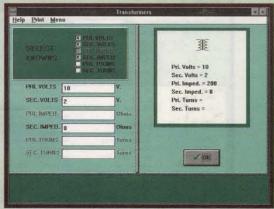


Figure 12 . Transformer Calculation.

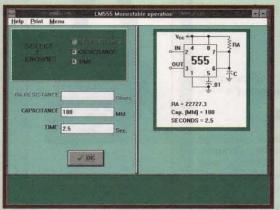


Figure 13. Monostable 555 Calculation.

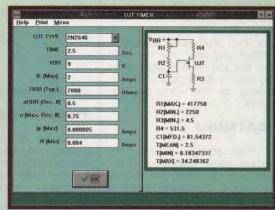


Figure 14. UJT Timer Calculation.

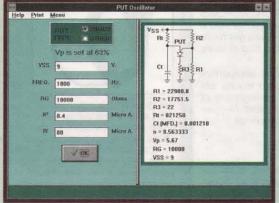


Figure 15. PUT Oscillator Calculation.

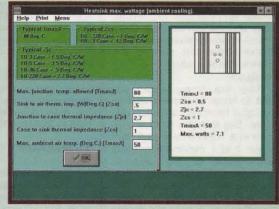


Figure 16. Heatsink Wattage Calculation.

555 timers are shown, astable (runs by itself — an oscillator) and monostable (stays in one condition until triggered, then resets when it times out).

Figure 13 shows the monostable 555 screen. You select two knowns in the selection box and then enter the data in the edit boxes that are selected. Click on "OK" to display the results. Here it can be seen that a 100 microfarad capacitance with a required time out of 2.5 seconds would require a resistor value of 22,727.3 ohms.

Note that this is calculated based on the presumed value of the typical electrolytic capacitor, which in actuality is highly variable from the marked value. In this case, it would make sense to use a 50K potentiometer in place of the resistor to set the time. The calculated value merely gives you an idea of the resistance needed.

Unijunction Transistor (UJT)

Two Unijunction Transistor screens are provided. One is an oscillator circuit, the other a timer. The timer circuit is shown in Figure 14.

The 2N2646 is shown as the default UJT type, but a pull-down allows you to select from nine oth-

ers, and enters the appropriate values for that UJT in the fill-in boxes.

If you want to use a UJT other than that shown, either select "NOT LISTED" and fill in your own UJT data, or select one that has data close to what you need and alter only the UJT data that you need to alter.

Fill in the TIME and VBB that you want, click on OK, and the circuit component values are calculated and displayed.

Programmable Unijunction Transistor (PUT) Oscillator

Figure 15 shows the PUT

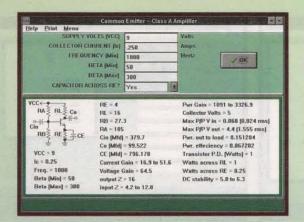


Figure 17. Common Emitter Calculation.

Oscillator screen. Only one PUT, a 2N6068, has pre-entered data. If you want to use some other PUT, either select "OTHER" and fill in your own PUT data, or select 2N6028 and alter only the PUT data that you need to alter. When you type in the VSS and FREQ, clicking on OK computes the results.

HEATSINKS

Three screens allow you to perform some complex calculations. You can determine various parameters concerning heatsink size, heatsink wattage, or heatsink temperature.

Figure 16 shows the screen for calculations involving the maximum wattage for an ambientcooled heatsink. For those not familiar with heatsink technology, many strange symbols are used. Typical values for some are shown at the upper left part of the screen. Temperatures are in Centigrade.

Use this screen when you want to know how many watts a particular heatsink can safely dissipate. Say that you have a transistor in a TO-220 case and want to use it in a maximum ambient temperature of 50 degrees Centigrade. You intend to use a heatsink that its source catalog has rated with a sink to air thermal impedance of .5 watts per degree Centigrade.

Using the information in the upper boxes, you would enter in the following data:

TmaxJ = 80Zsa = .5Zjc = 2.7Zcs = 1TmaxA = 50

Click on OK and the result shows maximum watts = 7.1

TRANSISTORS

Three transistor amplifier screens are available: common emitter, common collector, and common base. The common emitter amplifier screen is shown in Figure 17

The SUPPLY VOLTS must be greater than 1 volt. After entering in the COLLECTOR CURRENT, the minimum FREQUENCY, and the BETA range, you select if you want a CAPACITOR ACROSS RE, the emitter resistor, or not. If you use a capacitor, you get more stage gain, but at the cost of more distortion.

Click OK and the component values and parameter results are displayed. You can change any of the entered values and re-compute to fine-tune the circuit.

SUMMARY

While not intended to do the hundreds (thousands?) of possible types of electronic calculations, ELCAD very easily and elegantly performs the common calculations described. As a hobbyist or experimenter, you may find it handy. NV

Source

By the time you read this, ELCAD's author, programmer Brian Ellis (bellis@aol.com) intends to add even more calculations. The program, supplied on a 3.5-inch 1.44MB diskette for the IBM PC using Windows 3.1 or 95 (not available for the Macintosh), can be ordered for \$10.00 postpaid USA from:

> F.N.C. Corp. 350 Adam Dr. South Elgin, IL 60177 (847) 695-1210

MFI-922 VHF/UHF DUAL BAND ANTENNA TUNER



This compact dual band VHF/UHF antenna tuner from MFJ Enterprises, has a single meter that reads SWR and power. No adjustment is needed.

It covers VHF from 136 to 175 MHz, and UHF from 420 to 460 MHz. You can read power up to 150 watts in two ranges: 60 watts or 160 watts.



COMMUNICATION HEADPHONES

FJ's new communication headphones work well for amateur radio and shortwave radio listening in all modes — SSB, FM, AM, data, and CW. Each earphone has individual volume/bass controls.

A 40 mm driver unit reproduces enhanced communication sound, and there is near zero loss on signal transmission from the gold-plated plug and cord.

The lightweight earphones (eight ounces) come with nine feet of cord.

The MFJ-392 handles 450 mW and has a frequency response of 100-24,000 Hz. Impedance is 16 ohms at 1 KHz; sensitivity is 102 dB/mW. It works in mono or stereo mode and includes a free 1/4-inch phono adapter. Price is \$19.95.

VOX SPEAKER/MICROPHONE



FJ-2981 features an electronic Madjustable VOX control and is handy for use with any kind of handheld VHF, commercial, amateur, or marine radio. It also works for mobile hams and emergency operators on-the-go who need total handsfree operation.

In the VOX position, you just talk and the MFJ-298I automatically keys your HT. A "TRANSMIT" red LED lights up while your VOX is enabled.

This VOX mic picks up your voice, not background sound. Two condenser microphones are installed for feedback preven-

tion. Sensitivity is adjustable by rotating the trimmer switch which accommodates loud or soft voices. With MFJ's VOX speaker/microphone in the appropriate position (attached to your front pocket or lapel), the sensitive micro-

phate position (attached to your front pocket or lapel), the sensitive microphone picks up your normal speaking voice.

This mic works well for emergency operators such as fire, police, EMT, and active ham radio operators because it runs off of two "AA" batteries. Transmission is voice-activated in the "on" position. In the "off" position, you can use the MFJ VOX mic as a regular speaker/microphone. Transmission is activated only by pushing the PTT switch. The durable, hard plastic speaker mic fits in the palm of your hand.

A free external earnhouse is included. The earnhouse are be represented to

A free external earphone is included. The earphone can be connected to the earphone jack for total hands-free operation, or for monitoring the fre-

The VOX speaker/microphone is compatible with most Icom, Yaesu, Standard, RadioShack, Alinco, and ADI handheld transceivers with two prong plug-ins.

Price is \$39.95. For further specifications and other details on this or any of the other MFJ products listed here, contact:

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New Product News



BASICBOX

dvanced Graphic Systems announces the release of their newest product - a single board computer - the BasicBox.

The BasicBox is an all-inclusive system that comes with everything needed to get up and running in a short amount of time. Within minutes, the system is fully assembled, cabled into the PC, and powered on providing fully functional computing around its 8052 microprocessor with built-in BASIC-52 interpreter.

whose concept was adopted from lan Axelsons' Microcontrol-ler Idea Book, was designed with education in mind, but built to meet the demands of real-world control applications.

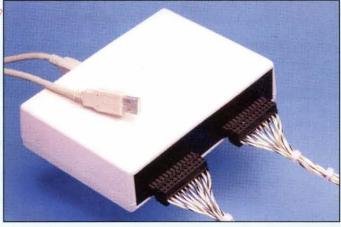
BasicBox The comes with an industrial-quality single board computer, an experi-menter's board which allows testing

debugging of Basic programs, power supply, all neccessary cables, Jan Axelsons' Microcontroller Idea Book, communications software, and lots of programming examples. It retails currently for \$249.00 in

single quantities.

For more information, contact:

ADVANCED GRAPHIC SYSTEMS 4055 GRASS VALLEY HWY., #103 DEPT. NV AUBURN, CA 95602 530-887-1619 FAX: 530-887-0107 WEB: http://www.ags-gv.com



JSB-210 USB RELAY MODULE

-Works, Inc. has begun shipping the

Model JSB-210 USB Relay Module. The Model JSB-210 has 8 or 16 "form C" relays and plugs 'n plays into the standard USB (Universal Serial Bus). The user controls the relays from any programming lan-guage that supports USB communica-

Plug-in style terminal block connectors allow quick hook-up to three contacts per relay. Each relay contact is rated at 1 amp @ 30VDC, and 0.5

amp @ 120VAC.

The module replaces internal PCbased plug-in cards in various test, control, and measurement applications. The single unit price for the Model JSB-210 is \$170.00 to \$205.00.

For more information, contact:

J-WORKS, INC. 12328 GLADSTONE AVE., UNIT 4 DEPT. NV SYLMAR, CA 91342 818-361-0787 FAX: 818-270-2413 E-MAIL: admin@j-works.com WEB: http://www.j-works.com

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DIGITAL MULTIMETERS/CURRENT CLAMPS

ensen Tools introduces a full line of high-quality digital multimeters and current clamps. From the full-featured JTM-105 - a true RMS meter to the JTM-63 - a low-cost, pocket-sized meter - the line provides a good value, costing less than comparable meters.

The entire line has been engineered to exacting tolerance and is manufactured using components of the highest quality, allowing Jensen Tools to offer a three-year "no hassle"

Jensen Tools can also ship meters within 24 hours with a certificate of calibration for a small fee.

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PCS64I PC OSCILLOSCOPE

Velleman, announces Digital PSC64I PC Storage Oscilloscope for use with an IBM-compatible PC. The PCS64I is geared towards both hobbyists and professionals.

It is a factory assembled and tested unit featuring two sep-arate channels and a

maximum sample rate of 64MHz. All standard scope functions are available, including features only found on digital equipment.

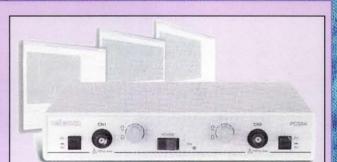
Apart from Y-position and input coupling, all settings are software-controlled.

The supplied WinDSO software (Windows™ 3.11/95/98) includes oscillo-WinDSO software scope, spectrum analyzer, and recorder modules. A DOS oscilloscope module is also provided.

Some features included are:

Oscilloscope Timebase 0.1µs to 100ms/div sensitivity; 10mV to 5V/div selectable trigger source, edge and level with pre-triggering; on-screen markers; true RMS read-out; and X/Y mode.

Spectrum analyzer - Frequency range 0 to 16 MHz; linear or logarithmic readout; zoom



function; and on-screen markers.

Recorder - Timebase 20ms to 2000s/div; automatic storage (up to one year); on-screen markers; and zoom function.

WinDSO allows saving of the sampled data as a graphic or ASCII format.

The oscilloscope is FCC-approved, fully optically isolated from the PC, and is equipped with the properties of the pr

with a charging circuit for an optional battery

For more information, contact:

VELLEMAN, INC. 7415 WHITEHALL ST., STE. 119, DEPT. NV FORT WORTH, TX 76118 817-284-7785 FAX: 817-284-7712 E-MAIL: velleman@earthlink.net WEB: www.velleman.be

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