

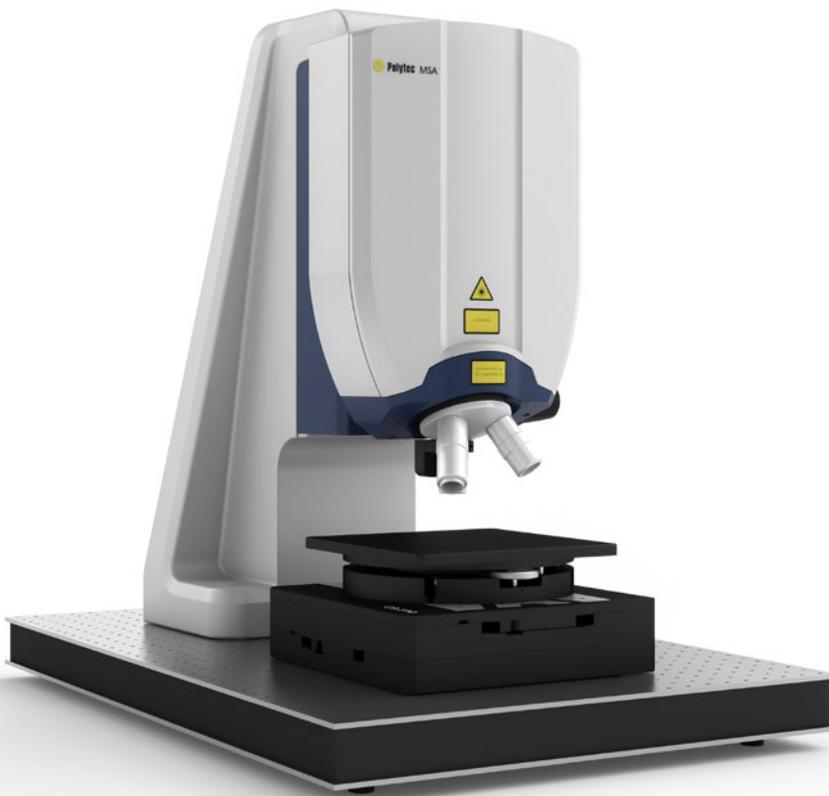
MSA-600 Micro System Analyzer

Visualization of dynamic response and static characterization are key to testing and developing MEMS devices. They are indispensable for validating FE calculations, determining cross-talk effects and measuring surface deformation.

The MSA-600 Micro System Analyzer is the all-in-one optical measurement workstation for characterizing surface topography as well as in-plane and out-of-plane motions.

The high-performance laser Doppler vibrometer delivers fast, real-time response measurement with sub-pm displacement resolution. The integrated stroboscopic video microscope enables the straightforward characterization and live-animation of in-plane motion. And the white-light interferometer option provides millions of 3D surface data in seconds.

Complemented by its straightforward operation and intuitive user interface, the MSA-600 is your powerful optical measurement solution in MEMS R&D and QC.



Highlights

- All-in-one optical measurement workstation
- True real-time response measurements without post-processing
- Unparalleled sub-pm displacement resolution
- Fast measurement and visualization of deflection shapes
- Straightforward and intuitive operation
- Automated system for easy integration into probe stations

MSA-600 Micro System Analyzer

Measuring 3D dynamics and topography of MEMS and microsystems

Preliminary datasheet



Technical data



MSA-600 system configurations

Basic configuration Out-of-plane vibration measurement up to 2.5 MHz

Options

Bandwidth extension Out-of-plane vibration measurement up to 25 MHz

Differential measurement Differential out-of-plane measurement

Planar motion analysis In-plane-motion analysis

Topography measurement Topography measurement

Metrological specifications

Out-of-plane measurement

| | Measuring principle | Laser Doppler vibrometry |
|--|---|---|
| Version | MSA-600-M (standard) | MSA-600-V (with bandwidth extension) |
| Max. frequency | 2.5 MHz | 25 MHz |
| Number of ranges | 13 velocity ranges | 13 velocity ranges |
| Max. velocity | 0.001 m/s ... 10 m/s, range dependent | 0.001 m/s ... 10 m/s, range dependent |
| Velocity resolution, average value ¹ | 0.005 (µm/s)/√Hz ... 1 (µm/s)/√Hz, range and frequency dependent | 0.005 (µm/s)/√Hz ... 2 (µm/s)/√Hz, range and frequency dependent |
| Displacement resolution | 50 fm/√Hz | 50 fm/√Hz |

In-plane measurement

| | Measuring principle | Stroboscopic video microscopy |
|---|---|-------------------------------|
| Version | MSA-600 with planar motion analysis option | |
| Frequency range | 1 Hz ... 2.5 MHz | |
| Max. velocity | > 0.1 m/s ... 10 m/s (magnification dependent) | |
| Objective magnification ² | 1x ... 100x | |
| Displacement amplitude resolution ³ | 5 nm | |
| Time resolution | 100 ns (strobe exposure time); max. strobe jitter ±40 ns | |
| System output | Displacement data, bode diagram, step-response plots, decay plots, trajectory plots | |

¹ Averaging is performed over the maximum bandwidth f_{\max} of the respective range.

² Objective specifications, as specified in table below.

³ Frequency noise floor for 512 shots per frequency on vibration isolated table.



| Metrological specifications | | |
|---|--|---------------|
| Topography measurement | | |
| Version | MSA-600 with topography measurement option | |
| Vertical measurement range | 250 µm | |
| Nominal sampling increment | 80 nm | |
| Method of evaluation ⁴ | smooth surface | rough surface |
| Resolution (RMS) ⁵ | 45 µm | 1.2 nm |
| Resolution of single measurement (RMS) | 300 µm | 14 nm |
| Repeatability ⁶ | 500 µm | 20 nm |
| Average flatness deviation ⁷ | < 5 nm | < 50 nm |
| Measurement performance on a traceable calibrated standard (PTB Type A1 (ISO 5436-1)) | | |
| Repeatability ⁸ | 0.07 % | |
| Extended measurement uncertainty ⁹ | 0.35 % | |

⁴ "Smooth surface": Evaluation of the correlogram phase. "Rough surface": Evaluation of the correlogram envelope.

⁵ Root mean square (RMS) of the signal amplitude at an averaging number of 50 measurements on a silver coated, parallel aligned plane mirror, measured under vibration-damped, temperature controlled conditions. Values for Resolutionsingle correspond to single measurements.

⁶ Standard deviation of the measured flatness in a series of 100 measurements on a parallel plate (A/20) slightly tilted.

⁷ Mean value of the flatness (according to ISO 1101), see (6).

⁸ RMS deviation of 30 step height measurements, referred to a calibrated step height of nominal 50 µm.

⁹ 3x combined standard uncertainty + deviation of the nominal value at 30 consecutive measurements under repeating conditions. The combined standard uncertainty is the quadratic mean out of the uncertainty of the normal and the standard deviation of the measurement values.

| Optical specifications | |
|---------------------------|--|
| MSA-I-600 Sensor Head | |
| Laser wavelength | 532 nm |
| Laser safety class | class 3R (< 5 mW visible output) |
| Light source wavelength | 470 nm |
| Light source safety class | class 2 LED product (< 20 mW visible output) |
| Camera | Full-field progressive scan camera |
| Camera resolution | 1732 x 1200 pixel |
| Camera frame rate | max. 56 fps |



| Bright field objectives | Magnification | Working distance (WD) mm | Spot diameter (1/e ²) μm | Field of view mm x mm |
|-------------------------|---------------|--------------------------|--------------------------------------|-----------------------|
| A-MOB-001X | 1 | 13 | 46 | 10.0 x 7.0 |
| A-MOB-002X | 2 | 34 | 23 | 5.1 x 3.5 |
| A-MOB-005X | 5 | 34 | 9.3 | 2.0 x 1.4 |
| A-MOB-010X | 10 | 33.5 | 4.6 | 1.0 x 0.7 |
| A-MOB-010B-LD | 10 | 48.9 | 4.6 | 1.0 x 0.7 |
| A-MOB-020X | 20 | 20 | 2.3 | 0.51 x 0.35 |
| A-MOB-050X | 50 | 13 | 1.4 | 0.20 x 0.14 |
| A-MOB-100X | 100 | 6 | 0.8 | 0.10 x 0.07 |

| Interference objectives | Magnification | Working distance (WD) mm | Type | Field of view mm x mm |
|-------------------------|---------------|--------------------------|-----------|-----------------------|
| A-IOB-02X5-B | 2.5 | 10.3 | Michelson | 4.0 x 2.8 |
| A-IOB-005X-B | 5 | 9.3 | | 2.0 x 1.4 |
| A-IOB-010X-B | 10 | 7.4 | | 1.0 x 0.7 |
| A-IOB-020X-B | 20 | 4.7 | Mirau | 0.51 x 0.35 |
| A-IOB-050X-B | 50 | 3.4 | | 0.20 x 0.14 |
| A-IOB-100X-B | 100 | 2 | | 0.10 x 0.07 |

General specifications

| Component | MSA-I-600 Sensor Head | MSA-F-600 Front-End | MSA-W-600 Data Management System | MSA-E-600 Controller |
|------------------------|------------------------------------|---|--|--|
| Power | via MSA-F-600 Front End | 100 ... 240 VAC ± 10%, 50/60 Hz max. 100 VA | 100... 240 VAC ± 10%, 50/60 Hz max. 525 VA | 100... 240 VAC ± 10%, 50/60 Hz max. 450 VA |
| Dimensions [W x L x H] | see figure | 485 x 150 x 380 mm (19", 84 TE/3 HE) | 485 x 190 x 550 mm (19", 84 TE/4 HE) | 499 x 177 x 373 mm (19", 98 TE/4 HE) |
| Weight | 12.6 kg | 9.0 kg | 18.0 kg | 12.0 kg |
| Operating temperature | 18 ... 30 °C (64.4 ... 86 °F) | +5...+40 °C (41...104 °F) | | |
| Storage temperature | -10 ... + 65 °C (14 ... 149 °F) | -10 ... + 65 °C (14 ... 149 °F) | | |
| Relative humidity | max. 80%, non-condensing | | | |

Compliance with standards

| | |
|-------------------------------------|--|
| Electrical safety | IEC/EN 61010-1 |
| EMC | IEC/EN 61326-1 Emission: Limit Class A, IEC/EN 61000-3-2 and 61000-3-3 Immunity: IEC/EN 61000-4-2 to 61000-4-6 and IEC/EN 61000-4-11 |
| Laser safety | IEC/EN 60825-1 (CFR 1040.10, CFR 1040.11) |
| Expanded uncertainty of measurement | SEMI MS4-0416 and MS2-113 |

Options and accessories

Please refer to the document "Accessories for stand-based instruments"

Software features

| Out-of-plane measurement | |
|-----------------------------|---|
| Data acquisition | |
| Video display | Live, full field, black & white video image of test object directly incorporated into user interface for interactive scan set up and beam positioning. Digital zoom into live video image. |
| Laser positioning | Visible laser moves with cursor on live video image by clicking or dragging the mouse. |
| Defining scan geometry | Utilizing APS Professional mode for up to 512 x 512 points per object of any shape. Measurement points are defined graphically over the live video image using a mouse. User can draw individual objects using polar, cartesian or hexagonal grids, or define single points. Define single points (optional): Single point geometry can be optimized by refining or coarsening the grid. Automatic generation of surface elements to connect scan points. |
| Scan geometry import | Geometry import from UFF or MEscope format. |
| Autofocus option | Automatic focusing of the laser at the current position of the specimen or during the scan; allowing for an optimized signal level at every scan position ¹ . |
| Sample positioning | Interactive control of X-Y positioning stage (optional) by using the mouse and absolute or relative displacements by precisely defined distances. Measurements at different positions can be acquired separately and combined for analysis and presentation. |
| Vibrometer control | All vibrometer parameters such as velocity range and tracking filter are software controlled. |
| Display | Simultaneous display of live video showing actual laser spot, entire scan area including scan points, and multiple analyzer displays of various signals (time traces and spectra). |
| Specimen excitation | Wide range of waveforms including sine, periodic chirp, white noise, random signals, sweep and arbitrary signals. |
| Acquired scan data | Entire spectrum acquired for all channels at all scan points |
| FastScan | Fast acquisition mode (up to 50 points/s) for measurements at a single frequency. Bandwidth is definable. Complex and magnitude averaging and signal enhancement are available. |
| Time domain data (optional) | Time domain acquisition, time domain averaging, time domain animation. |
| Gate input | Gate input for intermittent scan control. |
| Scan data validity check | Data quality check at all scanned points in Signal Enhancement (SE) mode. MSA-600 checks the quality of data in each spectrum. The averaged spectrum is weighted toward those spectra with the best signal to noise ratio. Measured points are labeled: optimal (SE only), valid, or A/D overload. |
| Trigger | Auto or manual threshold, rising or falling edge, source: external or any measurement signal |
| Averaging | Complex or magnitude averaging of spectra, peak hold, time |
| FFT lines | 6,400 standard; 12,800 optional; 819,200 optional |
| Window functions | Rectangular, Hamming, Hanning, Flat top, Blackman Harris, Bartlett, Exponential |



¹ Requires portal stand with automatic z-stage.



Data processing and analysis

| | |
|--------------------------|--|
| Data organisation | Support for project oriented workflow by a tree-style file browser for measurements, settings, macros, user defined waveforms, amplitude correction files. Context based actions on different file types. |
| Display | Color/gray, filled/unfilled contours and 3-D relief maps over stored video image (static or animated), averaged spectra over all scan points, individual spectra at each point as Bode or Nyquist plots, line profiles. Animation of video image for easy visualization of results. Data are scaled in velocity, acceleration or displacement. Logarithmic/linear axes |
| Data transfer | ASCII, Universal File Format (UFF), ME'scope and PolyWave binary data interface (optional). UFF and ME'scope data can be imported, analyzed and processed as user defined datasets and combined with measured data. |
| Graphics transfer | Graphic formats AVI (for animations), JPEG, BMP, TIFF, PNG, GIF. |
| Data processing | Complex spectral analysis provides the following quantities and functions for area and/or single-point data: magnitude, magnitude dB(A), phase, real, imaginary, frequency response function (FRF), H1, H2, auto power, cross power, coherence, averaged RMS over frequency. 3rd octave analysis, ESD, PSD. |
| Polytec Signal Processor | The Polytec Signal Processor is the user interface to the PolyMath library included in the PSV software. Easy-to-use spreadsheet for post processing of scan data. |
| Automated processing | Software can be fully automated. |

In-plane measurements

Data acquisition

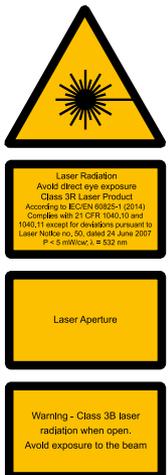
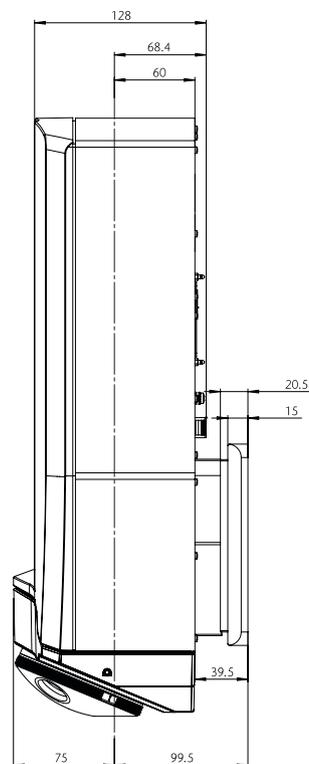
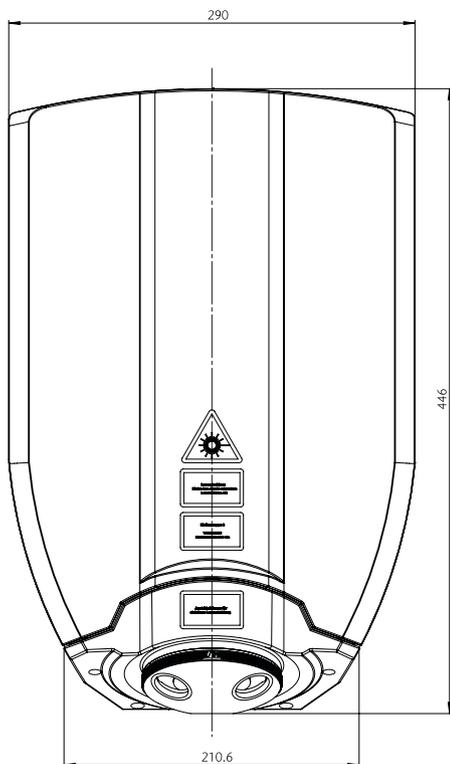
| | |
|-----------------------------|--|
| Working principle | In the Acquisition Mode, video sequences are sampled and analyzed using proprietary measurement algorithms. |
| Strobe illumination control | Control of the strobe pulses (interval, pulse length). |
| Data acquisition | Acquisition of the stroboscopic video image and live view of object movement. |
| Specimen excitation | Integrated signal generator software for specimen excitation with sine and pulse signals with excitation frequencies up to 2.5 MHz. Support for arbitrary, user-provided excitation signals. |

Data processing and analysis

| | |
|--------------------|---|
| Working principle | Motion analysis is performed interactively. Motion data are based on image correlation and displayed as X, Y displacement values. Sub-pixel resolution enables in-plane motion measurements with resolution in the nanometer range. |
| Data organization | Support for project oriented workflow by a tree-style file browser for measurements and settings. |
| Live video display | The live video mode provides a steady, slow-motion image sequence of the test object's motion for visual characterization. |
| Display | <ul style="list-style-type: none">■ Displacements for individual frequencies and their differentiations as well as frequency spectra, step responses and decay (ring down).■ Bode plots for both – horizontal and vertical – motion.■ Graphs can be examined using cursors, zoomed and panned. For each graph, different line and marker styles are selectable. |
| Data transfer | Graphs can be exported as image or ASCII file and sequences of images can be saved as AVI files. |

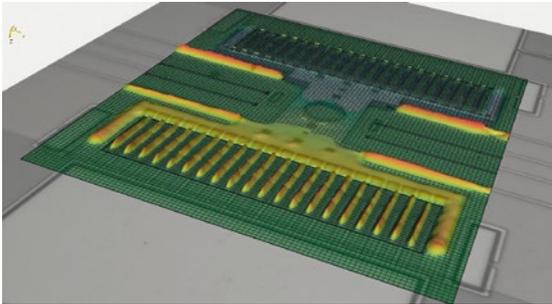


| Topography measurements | |
|-------------------------------------|--|
| Data acquisition | |
| Working principle | By shifting an interference objective with respect to the sample, a high resolution X-Y-Z mapping is generated. The interference pattern is captured with the video camera. |
| Measurement modes | <ul style="list-style-type: none">■ Short coherent measurement■ Smart Surface Scanning technique for extended contrast range |
| Data processing and analysis | |
| Data organization | Support for project oriented workflow by a tree-style file browser for measurements and settings. |
| Post-processing | Envelope or phase evaluation |
| Data evaluation | Linear regression; polynomial fit; subtracting; averaging; filters like median, erosion, high pass and low pass filter; masking functions |
| Data display | <ul style="list-style-type: none">■ Surface view: 2D, 3D presentation and isolines view, with video overlay■ Profile view: profile sections; correlogram; roughness/waviness parameters; graphs/diagrams, geometrical data like angle, heights, radius etc. |
| Data transfer | Graphs can be exported in various common image graphic formats; measurement data can be exported as ASCII file. |
| Automated processing | Software can be fully automated. |

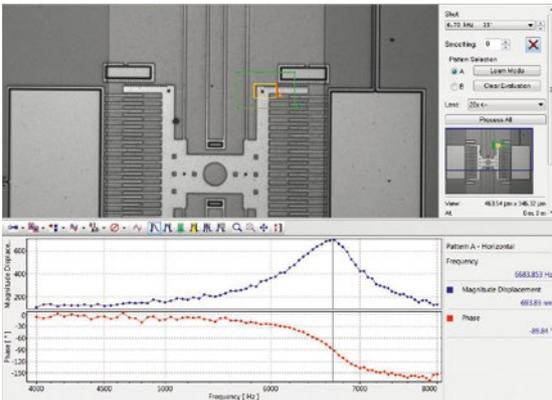


All dimensions given in mm

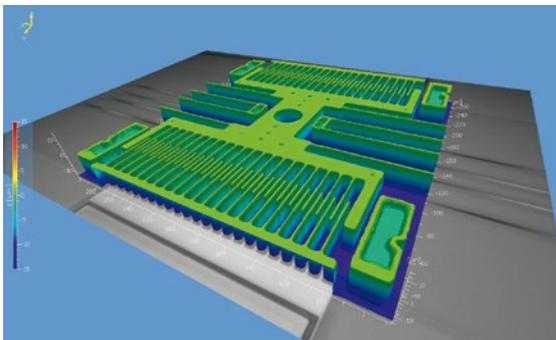
Comprehensive analysis of a MEMS electrostatic combdrive



Fast, real-time response measurement of the combdrive's out-of-plane dynamics reveals all system resonances. In addition, detect all in-plane modes with ultra-high sensitivity laser Doppler vibrometry measuring their minute parasitic out-of-plane contribution.



Bode plot of the combdrive's principal in-plane driving mode. Visualize the device operation with live-mode animation.



High-resolution surface topography measurement revealing every detail of the device topography – even as fully automated measurements on wafer-level.

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